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 - and James T. Clinthorne

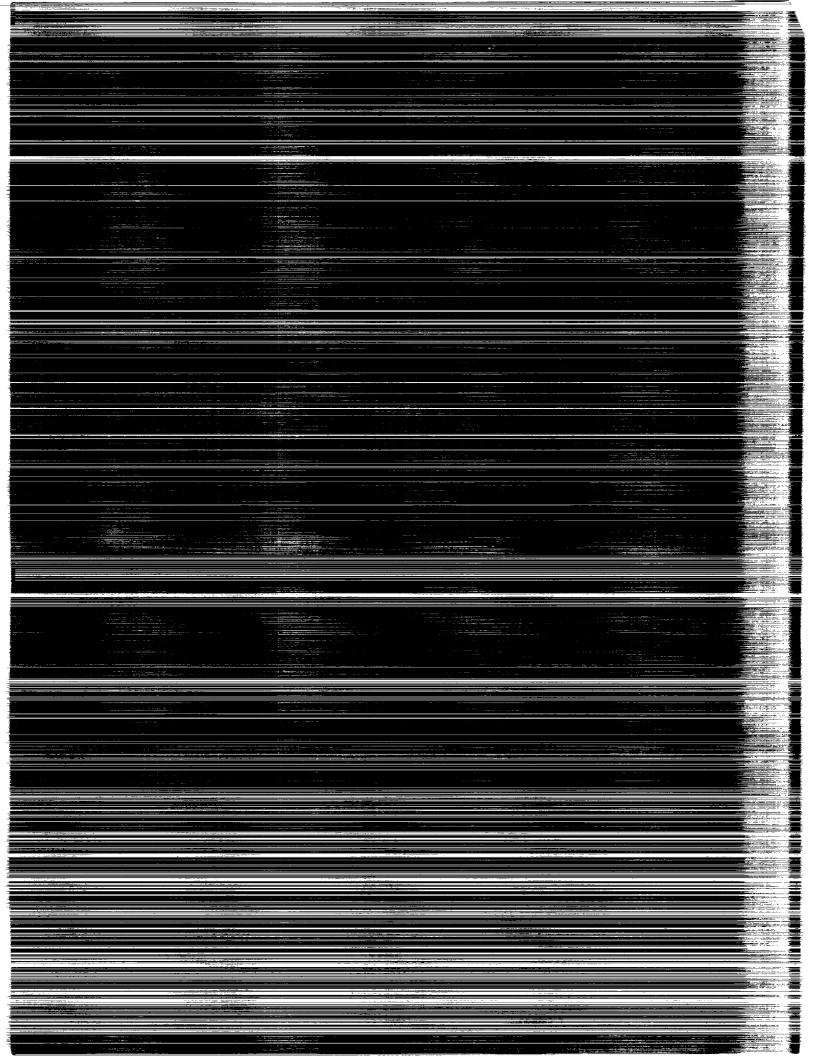
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Synthetic Aperture Radar Imagery of Airports and Surrounding Areas

Study of Clutter at Grazing Angles and Their Polarimetric Properties

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FOREWORD

This is the final report of the Phase III Extension for Contract NAS1-18465 (Processed Synthetic Aperture Radar (SAR) Data), sponsored by National Aeronautics and Space Administration (NASA) Langley Research Center (LaRC). This report is the last in a four report series. The thrust of the overall effort is the statistical description of ground clutter at airports and in the surrounding areas. In Phase I of this activity, SAR data of airports which existed in the Environmental Research Institute of Michigan (ERIM) SAR data archive were examined for utility to this program. Eight calibrated digital images at high resolution and coarse resolution were created. The coarse resolution images were provided to NASA LaRC for use in their Microburst/Clutter/ Radar Simulation programs whereas the high resolution images underwent a statistical clutter analysis at ERIM. In Phase II of this program, SAR data were collected on an opportunity basis at the Philadelphia Airport using a set of radar parameters which more closely matched those which are anticipated to be encountered by an aircraft on its approach to an airport. One calibrated digital image each at high resolution and coarse resolution was generated. During Phase III, a dedicated SAR mission was flown over the Denver Stapleton International Airport and surrounding area. A wide variety of geometries and scene contents were acquired and these data and study results were presented. An extension to Phase III was made for additional processing and analysis of SAR data to address collections with small grazing angles, collections which included mountains in the far range to document sources of possible range ambiguity, and the polarimetric properties of ground clutter with emphasis on determining what is the ground backscatter response for polarizations which enhance microburst features.

The work reported here was performed by members of the Center for Earth Sciences, Advanced Concepts Division, Environmental Research Institute, under the direction of Dr. S.R. Robinson. The principal investigator for this project was Dr. R.G. Onstott. The contract was

monitored by E.M. Bracalente, NASA Langley Research Center, Hampton, Virginia.

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I. INTRODUCTION

Low altitude microburst windshear represents a significant hazard to aircraft, particularly during take-off and landing. The intense down drafts and the resultant divergent outflow can have a significant effect on the lift characteristics of the endangered aircraft. When encountered at low altitude, the pilot has little time to react correctly to maintain safe flight. The Federal Aviation Administration (FAA), jointly with the National Aeronautics and Space Administration (NASA), has sponsored an investigation into the development of airborne sensors to detect microburst windshear. One sensor of interest is a microwave Doppler radar operating at X-band or higher frequencies. Critical to the analysis of the capability of such a sensor to perform this detection is the microwave backscatter description of both the microburst event and the clutter background, especially during the approach and departure from an airport.

NASA Langley Research Center (LaRC) has developed a Microburst/Clutter/Radar simulation program to assess the performance of Doppler radar as it views a low-level microburst along an approach to an airport. Inputs to this simulator include the airport ground clutter database, a simulated microburst database, the operating parameters of the proposed weather radar, and candidate signal processing software for use in detection. In the operation of the simulation program the received signal amplitude level for each range bin is calculated. Each range bin may include contributions from both the microburst and the ground clutter.

To date the Environmental Research Institute of Michigan has provided NASA LaRC with seventeen synthetic aperture radar (SAR) images of selected airport scenes for use in their Microburst/Clutter/Radar Simulator and for the characterization of the ground clutter surrounding airports. Eight of the images were archival data, one was of a target-of-opportunity airport, and eight were taken from a dedicated collection over the Denver Stapleton International Airport on 16 November 1988. In addition, statistical analyses of these airport environments have been performed by ERIM to describe the range of

scattering conditions encountered. Clutter types, mean backscatter intensities, probability distributions, and areal extent of the clutter types in the image were determined.

The Denver Stapleton International Airport was chosen by NASA LaRC as the focus of the dedicated data collection for a number of reasons. This airport has had a history of windshear events, many of which have been documented by the National Oceanographic and Atmospheric Administration. Additionally, it is located near the center of Denver, a large metropolitan area, and experiences heavy air traffic. As a clutter scene it is therefore representative of other airports which serve large urban areas. Finally, the airport is located near the Rocky Mountains, which allows the examination of the ambiguity effects of mountain clutter which have the potential to mask microburst targets. This report presents the results of additional processing and analysis performed on the SAR data obtained of the Denver Stapleton International Airport during Phase III of the contract work. This additional work encompassed three analyses: 1) the analysis of an image of the front range of the Rocky Mountains to obtain data on mountain clutter, 2) the analysis of airport clutter collected at small grazing angles, and 3) an examination of the polarization properties of airport clutter and heavy rain.

II. DATA COLLECTION

The NASA Denver collection consisted of one mission flown on 16 November 1988. Twenty-seven data passes were made with the purpose of collecting SAR data which would represent the radar clutter field which an aircraft would experience when landing at this airport. In simulating this flight geometry, a series of low altitude passes were utilized to image the ground scene at very large incidence angles. This configuration is illustrated in Figures 1a through 1d.

The location of the flight lines and pass identification of the images used in this analysis are provided in Table 1. A flight (Pass 14) was made parallel to the front range of the Rocky Mountains with an altitude of 5500 feet above ground level (AGL). The resultant image was named the Rocky Mountain X-HH image. The low-altitude X-HH and X-VV pair of images was taken from Pass 43, a north heading and west-looking flight track with an altitude of 2900 feet AGL. The polarimetric set of data came from Pass 37, an east heading and north-looking flight track with an altitude of 5600 feet AGL.

The radar used during this collection was the NADC/ERIM P-3 SAR . This radar operated at a frequency of 9.375 GHz (X-band) and at VV, HH, VH and HV polarizations. For the low altitude and Rocky Mountain passes VV and HH polarizations were used in a double swath mode. For the polarimetric images VV, HH, VH, and HV polarizations were collected in single swath mode. Low resolution, with an azimuth resolution of 2.8 m and a slant range resolution of 3.0 m, was used in order to maximize the coverage of the images. Operation in this mode was recommended since the final images would be digitally processed to a coarser resolution of 20 m.

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The clutter scene used in this analysis is a west looking image of the front range of the Rocky Mountains. Ground area coverage is illustrated in Figure 2 and the image is provided in Figure 3. The image subtends incidence angles from 0° to 85°. The ground range coverage is 19.6 km and extends from Harriman Lake on the east to Evergreen, Colorado in the west. The image covers an area in azimuth of approximately 10.1 km, which extends from just south of Hine Lake to the south side of Green Mountain. Approximately 65% of the image is occupied by the front range of the Rocky Mountains. The most prominent feature of the range is the Hogback, an uplift thrust feature which juts up at a steep angle. Behind the Hogback is the north end of the Rampart Range. The other 35% of the image contains an assortment of standard clutter features. The area has several lakes, reservoirs, and scattered residential suburbs, but the primary clutter type is grassland. Just south of Green Mountain is the city of Lakewood, Colorado.

The clutter content of the Rocky Mountains image is presented in Table 2. Easily three-fourths of the image is occupied by either the hogback thrust feature or the foothills of the Rockies. Of the remaining area of the image approximately one-third is residential, one twenty-fifth is water, and the rest is grassland. Table 3, Figure 4, and Appendix A present the statistics of the clutter sub-regions which were used in this analysis. A map of the selected clutter regions is presented in Figure A-1 for reference.

The results of a threshold analysis of the image are presented in Figures 5 and 6. The image in Figure 5 presents a comparison of radar scattering coefficient images thresholded at -30 dB, -20 dB, -10 dB, 0 dB, and 10 dB. The most prominent feature in the series of images is the lack of returns at far range. Only the hogback feature at the front of the range stands out significantly. A few returns from the Rocky mountains can be seen in the -30 dB threshold, but only from the front of the range. Some grassy areas and all water areas have backscattering coefficients of less than -30 dB, but most returns in the near range of the image are brighter than -30 dB. At the -20 dB threshold the Rocky

Mountains are not visible and the hogback returns have also been diminished, although they still represent the dominant geological feature of the scene. Other prominent returns in this backscattering coefficient bin are residential areas, the south end of Green Mountain, and specular returns coming from the extreme near range of the image. At the -10 dB threshold, the dominating features are the nearest section of the hogback and specular returns. Only a fraction of the image has radar scattering coefficients (or scattering cross sections) above 0 dB and these returns are mainly specular. Figure 6 presents a distribution of the thresholded returns. Almost 73 percent of the image has returns of -30 dB or less; these values are essentially in the noise. Approximately 25 percent of the returns have values of -30 dB to -10 dB; these values represent those returns from natural targets and residential areas. The remaining 2 percent of the data, which have backscattering coefficient values of -10 dB and higher, represent mostly specular returns and a few returns from the closest areas of the hogback.

The Rocky Mountains image is somewhat different than the other Denver images in that it has comparatively few clutter groups. The image content consists mainly of grassland and geological features, with a few residential, reservoir and lake areas scattered throughout. The incidence angle dependency plots for the clutter subregions in the image and the histograms of the clutter are presented in Figures 7 through 12. The grass clutter, Figure 7c and Figure 8, shows a decrease in the mean scattering coefficient value with increasing incidence angle. This is consistent with theory and previous experimentation. In the incidence angle range of 60° to 64° however, the data appears to cluster around two different scattering coefficient values, one at about -30 dB and one at about -25 dB. The bimodal nature of the data in this angle range can also be seen in the histogram in Figure 8b. This may represent a variation in surface type. In general, the histograms for the grass sub-regions are fairly symmetric and narrow, with means varying from approximately -22 dB at small incidence angles (around 45°) to -30 dB for larger incidence angles (around 79°) and with an average coefficient of variation of 1.35. These histogram shapes, means and coefficients of

variation are almost identical to that of the other Denver images and are indicative of the uniformity of the grassland areas.

The residential clutter, Figure 7b and Figure 9, also displays a decrease in the radar scattering coefficient with increasing incidence angle, but the data is less clustered than that of the grass subregions. This is due to aspect angle diversity in the residential data caused by variations in street orientation in the residential areas. The histograms for the residential clutter sub-regions are much broader than those of the grassland areas, with means from -5 dB at 40° incidence angle to -19 dB at 74° incidence angle and an average coefficient of variation of 6.62. For all residential clutter histograms, the leading tail is larger than the trailing tail, indicating a skew in the data towards larger radar scattering coefficients. This broad shape and comparatively large rightward skew in the histograms have also appeared in the histograms of other man-made targets in the Denver and Philadelphia areas and appear to be characteristic of man-made targets. The means and coefficient of variations for the residential clutter in the Rocky Mountain image are also on the order of that of residential clutter in other Denver images.

Both the thrust (hogback) feature and the mountains behind them display a decrease in radar scattering coefficient value as the incidence angle is increased. If the data from the two incidence angle plots in Figure 7 is overlain, both sets of data have the same decreasing trends. The mean normalized radar scattering coefficient has values which vary from about -17 dB at 65° incidence angle to -25 dB at 79°. The thrust feature has, for the most part, higher means than the mountains, with -11 dB at 65° and -22 dB at 79°, but has a slightly lower (by 2 dB) mean in the 70° to 74° range. This may be due to the change in aspect angle of the hogback that occurs in the 70° to 74° range of the image. The two clutter groups have similar coefficients of variation, with 1.2 for the mountain data and 1.1 for the thrust feature. The histograms of the clutter data, Figure 10 and Figure 11, for all data subsets except mountain data at 75° to 79°, are symmetric and narrow, much like those of the grass sub-regions. This similarity is to be expected. Both the hogback and the front range of

the Rockies are highly eroded and weathered surfaces. The same type of scrub grass which grows on the plains in front of these features grows on the features themselves. In addition, the erosional debris from the mountains has been washed down onto the plains, causing more similarity between the two. The surface of the hogback and the front range behind it are essentially the same surface as the plains before them. Differences in the means between the two are caused by differences in imaging geometry since both the hogback and the front range have a significant slope. The local incidence angle to the hogback varies from 42° to 59°, and that of the front range is significantly smaller than this. The returns from the water areas are presented in Figure 12. They are almost completely in the noise.

Although the mountainous terrain in this image would not be expected to produce severe range ambiguity effects due to moderate backscatter levels, this data may be used to examine the limitations of a radar system when imaging near such geological features. Mountainous terrain in the immediate vicinity of an airport has the potential to be a source of strong returns. If the backscattering cross sections of mountain and airport clutter is known, it is possible, using the ratio of the slant ranges to the clutter areas, to approximate the image slant range at which mountain clutter would significantly interfere with the airport returns. Mathematically, this can be calculated using the following equation:

$$\frac{\sigma_{\rm m}^{\bullet}}{R_{\rm m}^{4}} \ge \frac{\sigma_{\rm a}^{\bullet}}{R_{\rm a}^{4}} \tag{Eq. 1}$$

or

$$\frac{\sigma_{\rm m}^{\circ}}{\sigma_{\rm a}^{\circ}} \qquad \frac{{\rm R}^4}{{\rm R}_{\rm m}^4} \ge 1 \tag{Eq. 2}$$

where $\sigma_{\rm m}^{\bullet}$ and $\sigma_{\rm a}^{\bullet}$ are the backscattering cross sections of the mountain and airport clutter respectively, and R_m and R_a are the ranges to these features. In calculating a test case the maximum mountain return and minimum airport return will be used to form a worst case scenario. The

maximum return from the Rocky Mountain clutter was 1.57 dB at a range of 4779 m. The minimum backscattering cross section of an airport terminal was -9.6 dB. Given these values, the airport must be located at a slant range of 2382 m to make the product of the ratios of the backscattering cross sections and the slant ranges equal to one. As long as the airport is at a distance of at least 2400 m from the mountains, mountain clutter does not provide an additional enhancement.

The distribution of returns for the entire image is presented in Figure 13. The mean of the image is -18.97 dB, which is lower than the image distributions calculated for the other Denver images and is indicative of the less culturally developed nature of the image. On average, returns of -30 dB or less make up approximately 20 percent more of this image than of the other Denver images. The distribution plot of this image is also shaped differently from those of the other Denver images. The Rocky Mountains image displays much less of a skew to the right than the other Denver data analyzed. From past analyses, the rightward skew is indicative of the existence of man-made clutter returns, so the lack of this skew would point to a smaller contribution of man-made returns to the total image distribution.

IV. GROUND CLUTTER AT SMALL GRAZING ANGLES

The clutter scenes used in this analysis are a pair of X-HH and X-VV west looking images of the Denver Stapleton International Airport. The images are illustrated in Figures 14 and 15. The ground area coverage of these images is illustrated in Figure 16. The image subtends incidence angles from 0° to 87.5°. The ground range coverage is 19.6 km and extends from Peoria Street on the east to Sheridan Boulevard in the west. The image covers an area in azimuth of approximately 13.2 km and extends from 80th Avenue in the north to 1st Avenue in the south. In the near range of the image just northeast of the airport is Ladora Lake on the Rocky Mountain Arsenal. The arsenal also extends north of the airport. Directly east of the airport is an area of warehouses and airport storage facilities. Running east and west, and just south of the airport, is Colfax Avenue. Along Colfax, strip malls and other commercial buildings produce bright returns. Off of Colfax to the north and south are urban residential areas. South of Colfax Avenue in the near range is Lowry Air Force Base. Many buildings on the base can be identified. Just northwest of the airport is the Commerce City area. Just off Interstate 85 is the Mile High Kennel Club. It is characterized by a small area of low returns with a bright center. South of this feature are Interstates 270 and 70. Following a track south of Interstate 70 along Colorado Boulevard is the Park Hill Golf Course and the City Park. These rectangular shaped areas produce weak backscatter. Directly west of City Park is an area of bright returns originating from the high rise buildings of the downtown Denver area. North of downtown Denver is a mixed commercial and residential area. In the far range of the two images are some strong returns associated with the cities of Lakewood, Edgewater, Wheatridge, and Arvada.

Table 4 presents the results of the composition analysis of the low altitude images. The majority of the image, about 84 percent, contains clutter of a metropolitan nature in the form of urban, city, residential, or industrial areas. The airport and air force base take up about 10 percent of the images, and rural areas about six percent. Approximately half of the images consists of unclassifiable clutter

which is known from ground truth to consist of the metropolitan area of Denver.

The results of the threshold analysis of the data are presented in Figures 17 through 20. Figures 17 and 18 represent the distribution and thresholded images for the X-HH low altitude image and Figures 19 and 20 represent the same for the X-VV image. The threshold distributions indicate that 74 percent of the X-HH image and 62 percent of the X-VV image have scattering coefficient values of -40 db or less. The thresholded images show that areas of weakest backscattering cross sections are primarily located in the far range of the images. The runways at the airport and some of the grassy areas also appear to have values of -40 db or below. In this particular threshold bin the golf course is especially distinguishable in both polarizations and the Denver City Park can be discerned in the VV image. A bright return which stands out in the City Park area may be the Denver Museum of Natural History. Returns from the near range are dominant. Approximately 9.5 percent of the X-VV image and 5.5 percent of the X-HH image have returns between -30 db and -40 db. Areas with normalized scattering coefficients of this value are primarily located in the near range of the images and are represented mostly by the grassy areas at Lowry Air Force Base and the airport, as well as by water and runway returns. Near range returns still dominate the image. Fifteen percent of the VV image and 13 percent of the HH image have returns between -20 dB and -30 dB. Natural clutter areas appear to have the majority of their backscatter values within this range. Returns which are greater than -20 dB appear to arise almost exclusively from hard-target clutter. Neither the remaining returns in the near or far range of the image appear to dominate the scene. For like polarization, returns with values above -20 dB appear to be evenly distributed throughout the scene. Eight percent of the X-VV image and 5 percent of the X-HH image have returns between -10 dB and -20 dB. Sources are located primarily in the near range half of the image and are located in the urban and residential areas with some from the city area of Denver proper. Returns with values greater than -10 dB appear to be strictly associated with buildings in the city of Denver and the occasional strong return at

very near range. Three and a half percent of the X-VV image and 1.5 percent of the X-HH image have returns in the -10 dB to 0 db range. These returns are attributed to hard targets and are seen in the mid range of the image. There are approximately 2.2 percent of the X-VV image and 1.1 percent of the X-HH image pixels which have scattering coefficients greater than 0 dB. All are attributed to hard targets and all are located in the mid-to-far range of the image at incidence angles of 80° or greater.

General summaries of the statistical analysis that was performed on the low altitude image set are presented in Tables 5 and 6 and in Figures 21 and 22. Maps of the clutter areas used are presented in Figures A-2 and A-3. Results of the statistical analysis are presented in Tables A-2 and A-3. The results produced at the two like polarization (VV and HH) are very similar. Grass, water, and runway clutter produce the smallest scattering coefficients of all the different clutter types. Mean values of these clutter types were consistent with those of the previously analyzed Denver data and new values for small grazing angles were added. Scattering coefficients of residential and urban areas are consistently larger than those of natural targets, but do not display the amount of separation seen previously. They are, however, within a standard deviation of the residential and urban clutter of the previously analyzed image sets. Returns from hard target clutter areas, such as the city and industrial parks, are consistent with previous data as are the returns from single hard targets, such as terminals, warehouses, and parking lots.

Plots of scattering coefficients versus incidence angle for the image pair are presented in Figures 23 and 24. The most unique feature in this series of plots is the large increase in scattering coefficient values for incidence angles greater than 78° for building clutter at both VV and HH polarizations, Figures 23a and 24a. Backscatter values are constant at about -18 dB for angles up to 78°. Clutter returns rise to a maximum, about 30 dB higher than the baseline values at angles of about 85° to 86°. This sudden increase is attributed to specular scatter from the sides of buildings.

The grass clutter results are presented in Figures 23b and 24b. These plots display the characteristic behavior of terrain clutter; cross sections decrease slowly through incidence angles up to 68°, after which they decrease rapidly. The middle angle portion of the HH and VV responses have mean values of about -25 dB to -26 dB. The values of the grass returns measured for these images are identical to those analyzed in previous analysis, and are also similar to those obtained using scatterometers.

The angular response of urban clutter is presented in Figures 23d and 24d. Both the HH and VV data display trends which have an almost constant value of about -17 dB until 80° after which the range of values increases about 10 dB. This behavior is also representative of the urban clutter data from other areas. The HH and VV backscatter levels are most similar in value to those obtained from the second and third 'step west' images. Data at VV polarization shows a larger spread of values than HH data, an indication of polarization dependent scattering mechanisms.

Residential clutter, presented in Figures 23c and 24c, is also consistent with past analysis results. Both the HH and VV data sets have the same mean value of about -19 dB until about 78°, at which point the VV data remains constant, and the HH data decay with increasing angle. The VV data also shows a greater spread in values than for the HH data, a trend also apparent with urban clutter. The behavior of the residential clutter is most similar to that of the second and third 'step west' images, and about 2 dB lower than the values of the first 'step west' image. In addition, mean VV values are similar to those obtained at VV polarization from the polarimetric image set.

There is only a small range of incidence angle data available for city clutter and is shown in Figures 23f and 24f. The VV data show a mean scattering coefficient of -10 dB, while the HH data has a mean of -13 dB. The HH data is most similar in value to the first and third 'step west' images, but the VV mean values are about 4 dB lower than those obtained in the polarimetric image set. The cluster of city backscatter cross sections for both HH and VV polarizations lie within the clusters for building clutter.

The industrial clutter angular response data, presented in Figures 23e and 24e, also lacks a dense coverage at various incidence angles, but does extend over a wide range of angles. The mean cross section at HH is about -14 dB and at VV about -12 dB. These values are within the range of values obtained from the 'step west' images. As seen for the other hard target categories, cross section enhancements were seen at the small grazing angles as compared to those at the middle angles.

Finally, runway clutter is presented in Figures 23g and 24g, and show the behavior for smooth surfaces. The backscatter at VV and HH decrease with incidence angle, but their fall-off rates differ. The VV data starts out with a higher mean, (about -35 dB) at 70° and then decreases quickly. The HH data has a mean of about -40 dB at this angle and then cluster at a value of -46 dB. These trends are similar to those obtained through scatterometer measurements at VV polarization. Scatterometer data for smooth asphalt shows a higher mean value at VV polarization, by about 6 dB, for angles in the 65° to 75° range, and a slightly quicker fall-off rate.

In Figures 25 through 41 histograms of scattering coefficients for the various clutter types are presented. The incidence angle plots provide the most in depth presentation of the changes in mean value of the scattering coefficient with angle, this analysis will concentrate primarily on differences in the shape of the distributions for different clutter types and on differences in shape within a clutter type due to differences in incidence angle. Distributions for grass clutter are presented in Figures 25 and 26. Distributions are narrow and symmetric, with peak percentage of occurrences decreasing from about 10.5 percent as the incidence angle increases. Returns from grass are very weak at higher angles, where the grass return is at or below the radar system noise floor.

Residential clutter distributions are presented in Figures 27 and 28. These distributions are symmetric and are slightly wider than those of the grass clutter. Some distributions exhibit a slight leading tail (i.e., predominate distribution toward larger σ° to the right of the plot). These distributions are similar to those of the second and third 'step west' images and to those of the polarimetric image set. The

returns for the 80° to 84° and VV and HH polarizations show a large spread of values and distribution shapes which are unique and dissimilar to those obtained at the middle angles.

Urban clutter distributions are presented in Figures 29 and 30. These distributions are similar in shape to those of the residential areas but display a prominent leading tail, an indication of strong dominant scattering sources. At angles greater than 65°, a population of the distributions at HH polarization broaden while the distributions at VV polarization maintain similar shapes until about 80°. This difference may imply that more returns, though not necessarily greater returns, could be expected with VV polarization than with HH polarization.

The distributions with the highest content of man-made clutter are presented in Figures 31 through 39. In the distributions for the city clutter, Figure 31, a prominent leading tail is seen in both the HH and VV data. The VV data has a mean which is 5 dB higher than that of the HH data. These distributions are similar in both shape and size to those of the city obtained from the second, third, and fourth 'step west' images. Industrial distributions are presented in Figures 32 and 33. The most prominent feature of the distributions is the largeleading tails, which are present whether the distributions are broad or narrow. These distributions have the largest leading tail of all the man-made clutter, and are most similar to the industrial distributions of the third and fourth 'step west' images. Not surprisingly, the distributions for building clutter, Figures 34 and 35, are most similar in shape to those of the industrial clutter. Single buildings are probably most like an industrial area in that the only features present in the clutter area would be many man-made targets and very little of anything else.

Distributions were also created for hard target clutter areas. The parking lot distributions, Figure 36, are generally very broad. A leading tail is present but not prominent; the distributions are reasonably symmetric. The shapes of these distributions are similar to those of the polarimetric image set, and the second and third 'step west' images. Distributions for two terminals, one oriented parallel to

the line of flight of the radar (H5) and one oriented perpendicular to the line of flight (H6), are presented in Figure 37. All distributions exhibit a rightward skew, but the mean of the distributions varies. For the X-VV image, orientation appears to make no difference in the mean value. For the HH image, returns from terminal H5 are lower than those from H6 by 10 dB. Figures 38 and 39 present the distributions for some smaller man-made targets in the vicinity of the airport. Both X-VV and X-HH data displays a wide distribution with a strong rightward skew in the distributions for a airplane at the airport. This distribution is similar in shape to that of the airplane distribution in the third 'step west' image as well as similar in mean value. The VV distribution has a secondary peak at higher values. The distributions for a truck and airplane are similar in that the truck distributions also show a secondary peak, but unlike the airplane distributions, the truck distributions are much narrower. The warehouse distributions, Figure 39, are broad and similar to the distributions for building obtained in the 'step west' images but are broader than the building distributions just examined. The VV distribution has a prominent leading tail, whereas the HH distribution is reasonably symmetric.

In summary, the distributions change from being symmetric and narrow to broad and having prominent leading tail as the clutter areas change in content from entirely natural targets to entirely man-made targets. The distributions from the selected man-made features also follow this trend. Additionally, the distributions for the individual hard targets appear to differ depending upon whether the hard target is a building or vehicle.

Whole image clutter distributions are presented in Figures 40 and 41. The general shapes of the clutter distributions at VV and HH polarizations are most similar to those of the 'step west' set of Denver Images. In particular, they are almost identical to the distributions for the second and third 'step west' images. This should be the case in that the low altitude image set cover basically the same ground area as these 'step west' images. The small size of the distributions implies that much of the image content lies at the noise floor or below; most of

the pixel values in the images are at the noise threshold level. The mean scattering coefficients of the images are -12.21 dB for X-VV and -9.25 for X-HH and are lower than those obtained from the other metropolitan areas analyzed. The clutter distribution for the VV low altitude image is broader than that of the HH image, implying that the VV image has more non-threshold values than the HH image. This is also noticeable upon visual inspection of the image.

Tables 7 and 8 present the backscattering cross sections for some of the hard targets in the low altitude images. Table 9 presents a comparison of the backscattering cross section values from hard targets in previously analyzed Denver images to those obtained from the low altitude image set. The hard target values in the low altitude images correlate well with similar targets of approximately the same effective areas and located at similar incidence angles.

Figures 42 through 47 display individual targets from the series of Denver images as the targets were imaged at incidence angles from 60° to 84°. Table 10 lists the sources of these sub-images. These figures provide a visual illustration of how the returns change with increasing incidence angle. Natural terrain cross sections decrease quickly as expected. The grass clutter drops into the noise at around 80° and the returns from trees drop off at about 82°. Most hard targets are visible at all incidence angles but the dominant scatterers appear to scintillate and change position. At the middle incidence angles, many returns originate from the roofs of buildings. With increasing angle, fewer returns come from roof tops and the primary reflectors are associated with the fronts of the buildings which face the radar. This is evident in the images of the airport terminal area in Figure 42. In the scene at 68.9° returns arise from almost all locations within the image. Some radar shadowing of the buildings just below the airport is also visible. In the 78.6° and 78.9° images, returns from all areas are still apparent, but returns from the faces of structures which mainly face the radar are enhanced. Returns at 82.8° are limited to the structures which are oriented perpendicular to the radar, although areas of the terminal and of the fence surrounding the terminal which do not face the radar also produced strong backscatterer. Some returns also

may originate from the roofline of the back sides of the buildings as evidenced by the warehouse area in Figure 43. It is interesting to note that the returns from the parking lots at the airport, which appear to be quite strong at the incidence angles from 68° to 79°, completely disappear by 82.8°. At even higher incidence angles the urban clutter and city clutter become easily delineated. This is evident in Figure 45 of the Park Hill Golf Course. In the 68.3° image, the city area above and below the golf course visually has a mean similar to the urban area to the right of it. The images observed at 82.2° and 83° are dramatically different, and the city areas are much brighter than the urban areas.

V. POLARIZATION PROPERTIES OF MICROBURST AND GROUND CLUTTER

In this study, circular and elliptical polarized imagery were synthesized from the Pass 37 SAR image. Statistical analysis similar to that conducted on previously analyzed images, including the analysis of returns from various ground targets, were conducted and compared to the results obtained from the horizontal and vertical polarized images previously processed. An examination was made of the polarization properties of rain for conditions which may be encountered during microbursts. SAR data were then synthesized at these polarizations and statistics examined. The goal was to determine what polarizations may maximize the microburst return and minimize the ground clutter returns (i.e. to optimize the microburst-to-clutter ratio).

Methods to enhance the backscatter associated with microbursts for radars operating in the microwave region emphasizes the need to exploit the backscatter characteristics of hydrospheres or rain. Under some conditions, raindrops are spherical in shape. The backscatter cross section for a sphere in the Rayleigh region (drop size is much less than the radar wavelength) varies as the fourth power of the frequency. Hence, higher frequencies may be selected for microburst feature enhancement. A second opportunity also exist. That is to exploit the polarization properties of both the hydrospheres and the ground clutter.

Polarimetric Properties and Radar

The transmitted electromagnetic (EM) wave vector polarization is determined by the antenna structure. The incident EM wave excites currents on the illuminated target and the induced currents re-radiate EM energy, i.e. produce the scattered field. The radar antenna receives only the component of the scattered field that is co-linear to the transmitted wave. Since the direction of the scattered vector EM field is unknown, two antennas are required for completed reception. This is illustrated in Figure 48. The transmitted and received field vectors or incident and scattered fields are uniquely related to the target through

a scattering matrix. This is illustrated in Figure 49. A polarimetric radar provides a measure of the scattering matrix of a target. Note that the elements of the scattering matrix are complex. The notation used here is written where the first letter indicates the transmitted polarization and the second letter the received polarization. If the incident field vector is denoted as $\underline{\mathbf{E}}^i$ and the scattered field vector by $\underline{\mathbf{E}}^s$, then the scattered field is related to the incident field and scattering matrix [S] by

$$\underline{\underline{E}}^{\mathbf{g}} = e^{jkr} r^{-1} [S] \underline{\underline{E}}^{i}$$
 (Eq. 3)

where k is the wave number and r is range. The scattering matrix which includes all transmit-receive combinations is given by

$$[S] = \begin{bmatrix} S_{HH} & S_{HV} \\ S_{VH} & S_{VV} \end{bmatrix}$$
 or (Eq. 4)

$$[S] = \begin{bmatrix} |S_{HH}|e^{j\Theta HH} & |S_{HV}|e^{j\Theta HV} \\ |S_{VH}|e^{j\Theta VH} & |S_{VV}|e^{j\Theta VV} \end{bmatrix}$$
 (Eq. 5)

where S_{pq} is an element of the scattering matrix, p and q denote transmit-receive polarizations, $|S_{pq}|$ is the magnitude of the scattering matrix element, and $e^{j\Theta pq}$ is the element phase information. A scattering matrix may be normalized with respect to the phase of one of the elements so that relative phase differences are indicated. Therefore, the most often used form is

$$[S] = e^{j\Theta HH} \begin{bmatrix} |S_{HH}| & |S_{HV}|e^{j\Theta HV'} \\ |S_{VH}|e^{j\Theta VH'} & |S_{VV}|e^{j\Theta VV'} \end{bmatrix}$$
 (Eq. 6)

The $\Theta_{VH}{}^{\prime}$ indicates that the phase is measured with respect to the HH polarization.

There are five target types that are of interest in the microburstclutter problem. These are the flat plate, trihedral, sphere, dihedral and complex target. The scattering matrices for both the linear and circular basis for the four simple target types are summarized in Table 11. The exact nature of these matrices will become important later in this discussion. The scattering matrices for complex man-made targets may take on many forms, oftentimes they are combinations of the simple targets described here. Many complex targets provide backscatter returns at all polarization combinations.

For the general case of elliptical polarization one may use the diagram shown in Figure 50. Here the electric vector traces out an ellipse moving either clockwise (left-hand) or counter clockwise (righthand). The ellipticity diagram may be used to define the polarization of the wave. There are two angles, the tilt angle τ and ellipticity angle ϵ , in which the electric field may be expressed. The electric field is given by

$$\underline{\underline{E}} = \sqrt{E_x^2 + E_y^2 (\cos y^x + \sin y e^{i\delta y})}$$
where
$$y = 0.5 \cos^{-1}(\cos 2\epsilon \cos 2\tau) \text{ and}$$
(Eq. 8)

$$\gamma = 0.5 \cos^{-1}(\cos 2\epsilon \cos 2\tau)$$
 and (Eq. 8)

$$\delta = \tan^{-1}(\tan 2\epsilon / \sin 2\tau). \tag{Eq. 9}$$

In the process of polarization synthesis process the orthogonal vectors Z must be defined,

$$Z = r \begin{vmatrix} a \\ be^{j\delta} \end{vmatrix}$$
 (Eq. 10)

where $\delta = \Theta_V - \Theta_H$, $\tau = P_o^{.5} e^{i\Theta H}$, and $P_o = |Z_H|^2 + |Z_V|^2$.

In the linear basis, the orthogonal vectors are

$$Z_{V} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} Z_{H} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$
 (Eq. 11)

where in the case of Z_V , a=0, b=1, and $\delta=0$ or π , and Z_H , a=1, b=0, and $\delta=0$ or π . For the circular basis,

$$Z_{LC} = 1/\sqrt{2} \begin{vmatrix} 1 \\ j \end{vmatrix} \qquad Z_{RC} = 1/\sqrt{2} \begin{vmatrix} 1 \\ -j \end{vmatrix} \qquad (Eq. 12)$$

with a = b and δ = $\pi/2$ for Z_{LC} , and a = b, and δ = $3\pi/2$ for Z_{RC} . Elliptical basis is the most general case and

$$Z_{LC} = r$$
 $\begin{vmatrix} a \\ be^{i\delta} \end{vmatrix}$ $Z_{RC} = r$ $\begin{vmatrix} a \\ be^{i\delta} \end{vmatrix}$ (Eq. 13)

with a \neq 0, b \neq 0, and 0 < δ < π for Z_{LC} , and a \neq 0, b \neq 0, and $-\pi$ < δ < 0 for Z_{RC} .

Polarization Properties of Rain

For a wide range of meteorological conditions, raindrops are well described as spherical in shape. Backscatter properties of spheres are similar to those of flat plates and a trihedral corner reflectors. For a linearly polarized radar the scattered field orientation is identical to the incident field orientation, and an almost negligible amount of power is returned in the polarization orthogonal to the transmit polarization. This property is represented in the scattering matrix for a sphere in Table 11. For a circularly polarized wave incident on the sphere, a similar response occurs but the reflected wave encounters a change in polarization sense. In other words, the scattered field is

reflected in the opposite field rotation direction. If right circular is transmitted then left circular is scattered and is required to receive.

The natural shape for a raindrop is spherical. Depending upon the speed at which it falls to the earth it may take on the shape of an oblate spheroid. Wind forcing may also cause a rotation of raindrop resulting in a canting of the drop about vertical. In Figure 51, three diagrams are provided to illustrate this. To fully characterize a raindrop requires its equivolume diameter, axial ratio, and tilt angle τ formed between the minor axis and the normal to the earth.

Spherical raindrops produce no return in the orthogonal channel if linear polarization is used, or in the same sense, if circular-polarization is used. Even with the influence of the propagating medium and most conditions, the combinations of VV, HH, RL, or LR will provide the greatest backscatter return. However, in very heavy rain and thunderstorms considerable energy has been observed in the orthogonal polarizations (VH, HV, RR, and LL) [1] with depolarization ratios as small as 5 dB possible.

In a case of heavy rain, it has been reported [2], that with the selection of the optimum elliptical polarization that cancellation (i.e. the reduction in depolarization) in some areas of heavy rain may be improved by 12 dB. Using this example and assuming a circular polarization case with a depolarization ratio of 10 dB, the magnitude of the elements of the scattering matrices for circular polarization and the optimum elliptical polarization would be

$$[|S|]_{C} = \begin{pmatrix} 0.316 & 1.0 \\ 1.0 & 0.316 \end{pmatrix} \text{ and } (Eq. 14)$$

$$[|S|]_{E} = \begin{bmatrix} 0.08 & 1.09 \\ 1.09 & 0.08 \end{bmatrix}$$
 (Eq. 15)

This illustration shows that by utilizing the optimum polarization, in this case elliptical polarization, the cross-polarized channels have been enhanced by 0.75 dB.

Polarization Properties for a Canted Oblate Spheroid

As a first case, the polarization properties of a canted oblate spheroid are examined, since the resulting properties are easily understood. The raindrop has unequal major and minor axes and a major axis which is rotated about vertical. Starting with an uncanted spheroid, horizontal polarization aligns with the major axis and vertical polarization aligns with the minor axis. The result is an enhanced horizontal backscatter whose magnitude is dependent on the axial ratio. A polarimetric radar has the important attribute of being orientation insensitive. If the raindrops are canted, the radar may maintain the same backscatter response as in the uncanted case by realigning its transmit-receive field vectors with the major and minor axes of the canted raindrop. In doing so, an elliptical basis results.

Examination of the literature provides a wide array of observations with somewhat variable results. The case of heavy rainfall with rainfall rates were greater than 20 mm/hr and wind speeds greater than 20 m/s were characterized by raindrops with mean diameters of about 2 mm. Drops of this size have been reported to have axial ratios of about 0.95. For this wind speed a tilt angle of about 10° has been observed [3].

For the conditions chosen (axial ratio = 0.95, tilt angle = 10°), the ellipticity angle may be determined from

$$\epsilon = \tan^{-1}(1/\text{axial ratio}).$$
 (Eq. 16)

For right hand circular $\epsilon=-46.5^\circ$ and $\tau=10^\circ$ resulting in $\gamma=46.4^\circ$ and $\delta=88.97^\circ$. For left hand circular $\epsilon=46.5^\circ$ and $\tau=10^\circ$ and results in $\gamma=46.4^\circ$ and $\delta=-88.97^\circ$. A δ of -89° corresponds to a phase shift of 1° and is directly attributable to an axial ratio less than 1. The resulting elliptical basis vectors are

$$Z_{LC} = \begin{bmatrix} 0.6896 \\ 0.7242e^{-j88.97} \end{bmatrix} Z_{RC} = \begin{bmatrix} 0.6896 \\ 0.7242e^{j88.97} \end{bmatrix}$$
 (Eq. 17)

SAR clutter scenes were synthesized for this elliptical polarization case.

Propagation Through a Rain Filled Medium

Microbursts can originate from many convective systems. Typical thunderstorms which produce microbursts may be no more than 5 km in diameter at the base [4]. The core of the strong vertical and horizontal wind shear in the thunderstorm, referred to as a microburst, generally extends it influence to less than 4 km [5]. If the core is greater than 4 km, the phenomena is then referred to as a microburst. Heavy rainfall is often present during microburst activity. For a severe thunderstorm rainfall may be as high as 150 mm/hr. During heavy rain, raindrops will distort becoming oblate spheroids. A rain filled medium with these drop shapes may no longer have isotropic propagation properties. As an example, a differential phase shift between horizontal and vertical polarized waves may result [3]. In the case of a rain cell with a rain rate of 76 mm/hr a one-way differential phase shift of 7°/km may be induced.

Average rain rates during a microburst episodes have been estimated at 76.2 mm/hr with maximum rain rates of 165 mm/hr [6]. Observations suggest that most microburst occur in association with narrow precipitation shafts. Intense thunderstorm cells are generally only 3 km to 5 km wide at the base, so the area covered by heavy rain would be less than or equal to the width at the base. For a 3 km cell, a 6 km round-trip path through the cell would result in imaging the rain with a radar, with a 3 km path to the center of the microburst [6]. Under these circumstances a total two-way phase shift of 20° may be expected. Raindrops tend to have an orientation such that their major axis lies along the horizontal plane. Hence, horizontal-polarized returns are often larger than vertically-polarized returns [7,8]. In Figure 52, the ratio between HH and VV returns (ZDR) is shown versus the median drop

diameter. This results shows that the difference between VV and HH returns increases, almost linearly, with increasing drop size. The ratio between like and cross-polarized returns (LDR) is also shown. Depolarization increases rapidly from 0 to I mm diameters, but for diameters smaller than about 1 mm the absolute magnitude of the depolarization is small (below 30 dB). Depolarization is polarization sensitive, with horizontal polarization depolarized the least by raindrops [9].

Using results provided in [3] we will consider the effects associated with propagation through a rain-filled medium. In summary the parameters are a rainfall rate of 75 mm/hr, a viewing angle of 90° (corresponds to viewing the horizon) and a depolarization of -40 dB [3], a 20° phase shift (HH-VV), and a VV return about 2.5 dB lower than HH [8]. A scattering matrix may then be written as

$$[S] = \begin{bmatrix} 1 & 0.01 \\ 0.01 & 0.75e^{-j20^{\circ}} \end{bmatrix}$$
 (Eq. 18)

To determine the optimum elliptical polarization, polarization combinations were synthesized creating a polarization signature pair for the two cases where the transmit and receive polarizations are aligned and the case when they are orthogonal. These polarization signatures are provided in Figure 53. They show that HH-polarization provides the peak backscatter cross section of all polarizations (maximum σ of 1.000 at HH). Note that the cross-polarized maximum (σ value of 0.766) is smaller by 1.16 dB and occurs for a set of elliptical polarizations denoted LR.-Peak and RL.-Peak. Based on these peaks, the tilt and ellipticity angles were determined and the SAR clutter scenes were then synthesized for this case. The resulting basis vectors are

$$Z_{LC} = \begin{bmatrix} 0.6943 \\ 0.7197e^{j75.1} \end{bmatrix} Z_{RC} = \begin{bmatrix} 0.6943 \\ 0.7197e^{-j75.1} \end{bmatrix}$$
 (Eq. 19)

and the SAR clutter scenes were synthesized for this case. Polarization signatures were recalculated for the scattering matrix used above, but

with a zero phase difference with the purpose to examine the effect of the phase shift (see Figure 54). Note that the phase difference is responsible in shifting the null in the co-polarized case and the peak in the cross-polarized case from circular to elliptical polarization. This illustrates that the greater the phase shift, the greater is the difference between the optimum elliptical polarization and circular polarization.

VI. DENVER POLARIMETRIC SAR IMAGE SET

Image Set Description

In this analysis a single swath image (about 10 km x 10 km) which contains the Denver Stapleton terminal was selected. The ground coverage of this image is similar to that given in Figure 2 of the Volume III Final Report for the polarimetric image set. Image sets are presented in Figures 59 and 60 for linear and circular polarized. Visual examination allows the qualitative comparison for these simple targets to their ideal scattering matrices. Images at VV, HH, and HV polarizations are provided in Figure 55, 56 and 57. The image for VH is not provided, it is identical to that of HV. For most all classes of targets and clutter reciprocity holds, HV = VH. The image subtends incidence angles from 43° to 82° and the first half of the ground range is from 1593 m to 12047 m. The image covers an area which extends from just south of Lowry Air Force Base (AFB) to almost north of the Denver airport and from the warehouse district to the east of the airport to just west of Lowry AFB, and contains a good variety of ground clutter types. Starting from the south, which is in the image near range, is the Lowry AFB. The residential area just to the east of the base is part of the city of Aurora and the area to the west is part of the city of Denver. In this area streets are generally curvilinear, a characteristic of suburban developments. North of Lowry AFB, and extending in a band which crosses half the image is an urban community. This community, made up of blocks of smaller, closely-spaced, ranch style homes, is centered on Colfax Avenue, a main throughway through Denver, and extends up to the airport on the north side and down to Lowry AFB on the south side.

Further north is Denver Stapleton airport. Terminals, associated buildings, and parking lots west of the runways are easily distinguishable. East of the airport are additional airport buildings and large warehouses. Interstate 70 separates the airport buildings from the warehouse district, goes under the north/south runways, and cuts through part of the city just west of the airport. The city area

just to the west of the airport is a conglomeration of office buildings, hotels, and other related facilities. In the most northerly part of the image are the Denver Stapleton airport runways, warehouses and a highly industrialized suburb called Commerce City. The Commerce City area is separated from the business park by Interstate 270.

Calibration Target Array

An array of calibration targets was deployed during the SAR collection to absolutely calibrate the radar imagery according to backscatter levels as well as to permit the amplitude and phase balance between the transmit and receive channels (See Figure 58). The latter is important in polarimetric calibration. Three target types were used: trihedrals, dihedrals with three rotation angles, and active radar calibrators. Scattering matrices for the trihedrals and dihedrals are provided in Table 11. The active radar calibrators were oriented to produce an equal intensity response at each polarization. Scattering matrices were retrieved to quantitatively describe their responses. Examples of scattering matrices for the trihedrals are provided in Appendix E. It is instructive to study these targets and observe their presence or lack of presence at each polarization. Since the radar does have a finite isolation between channels, the zeros of the scattering matrices will be replaced by values similar to the system isolation. The dihedrals are particularly interesting. The rotation at the three difference angles produce three distinct scattering matrices at linear polarization. Dihedrals produce backscatter by a reflection from two conducting surfaces. Trihedrals produces backscatter by reflections off three surfaces. Circular polarized radar has the important property of separating returns into even-bounce origin (see LL or RR) or odd-bounce origin (see LR or RL). Note that the dihedrals are almost totally absent from circular cross-polarization images.

As suggested earlier, man-made targets may produce a wide variety of backscatter responses. As an example, aircraft cross sections have been observed to be less with circular-polarization than with linear-

polarization. Experimental results have shown that aircraft illuminated with one sense of circular polarization produced returns which were statistically equally distributed between the right-hand circular and left-hand circular polarizations. Hence, there was no circular polarization preference and a 3 dB reduction in the optimum power return, since the energy is distributed into two channels rather than one. In the linear polarization case, there was only about 0.5 dB reduction in the orthogonal channel. For this example of a man-made target of complex shape, circular polarization results in a 2.5 dB lower reduction in backscatter power (in RL or LR) compared with the use of linear polarization (VV or HH) [10].

VII. POLARIZATION PROPERTIES OF GROUND CLUTTER

Clutter statistics were obtained for the four transmit-receive polarization combinations in the scattering matrices for the linear polarization case, the circular polarization case, the elliptical polarization case for an oblate spheroid, and the elliptical polarization case of a rain filled medium. These tables are provided in Appendix D. Statistics were produced for urban, residential, grass, terminal area, and buildings. Many thousands of pixels were utilized to produce these results. Incidence angles ranged from 50° to 80°. A second set of tables was generated which describe the unique pieces of information a polarimetric radar provides, the polarimetric discriminants. Polarimetric discriminants are defined in Appendix D. These tables provide a compact method to describe the scattering properties of the clutter scenes analyzed.

Synthesis of Circular Polarization

In the synthesis of circular polarization from linear polarization, the following operations are performed:

$$S_{RR} = .5[(S_{HH} - S_{VV}) - j(S_{HV} + S_{VH})]$$

$$S_{RL} = .5[(S_{HH} + S_{VV}) + j(S_{HV} - S_{VH})]$$

$$S_{LR} = .5[(S_{HH} + S_{VV}) - j(S_{HV} - S_{VH})]$$

$$S_{LL} = .5[(S_{HH} - S_{VV}) + j(S_{HV} + S_{VH})]$$
(Eq. 20)

Note that S_{LR} and S_{RL} are nearly identical whenever S_{VH} and S_{HV} are small compared to S_{VV} and S_{HH} . In addition, it is important to point out that S_{RL} and S_{LR} fall midway between S_{HH} and S_{VV} for this case.

Clutter Responses at Linear and Circular Polarization

Clutter scenes of urban areas, a residential area, an area which contains objects along an airport runway, a plant, and an area about an

airport terminal were synthesized at circular polarization. These images are provided in Figures 61 to 66 at both linear and circular polarization, so that a comparison between the two may be made as a function of the different transmit-receive combinations. The sites selected are highlighted in an overlay found on the complete SAR image provided in Figure 56. The images are presented with equal intensity modulation to provide the best visualization of the different sources of scatter. The tables of statistics should be consulted to determine the quantitative differences between backscatter levels.

One of the urban areas is illustrated in Figure 61. The most striking difference in all the different cases is between the linear cross-polarization examples and all the others. The cultural aspect of this scene is most apparent in the linear co-polarized and circular polarization cases. In this case, VV, HH, RR, RL, LR and LL all show similar backscatter responses. The circular polarization cases, however, give the visual impression that the energy is equally spread in all channels. The VV image suggests that there are slightly more scattering points as compared to the response at HH-polarization. The prominent backscatter features in this urban scene are present in all the different polarization cases.

An urban area next to the Lowry Air Force Base is presented in Figure 62. There are three features of particular interest in this scene: the well structured urban area which is observed oriented to the radar look direction, the building complex in the upper right hand corner of the image, and the scatterers associated with a building in the upper left hand corner of the image. The urban area produced a response similar to that described in the example above, except that a greater number of scattering points appear in the HH image than the VV image. The circular polarization response suggests that the scattering centers are complex, dominated by neither single nor double bounce mechanisms, with the effect that the energy is, again, equally distributed among the four different polarization cases. Based upon the building scatter in the upper right hand corner, circular polarization provides the best choice for suppressing building clutter by insuring that features which are particularly polarization sensitive are

suppressed slightly. Note that this building is brightest in VV polarization, while HH and the circular polarization cases are similar. Linear cross-polarized returns are typically many dB lower than those of linear polarization. Therefore complex cultural clutter when mapped to circular polarization will be suppressed by spreading the energy into four channels rather than just two.

A residential area, Figure 63, also shows a response similar to that described above. The strong scattering points which dominate the response for the like linear polarization are presented in a similar manner in the circular polarization set. In comparing the differences between VV and HH, it is interesting to note that there are two distinct populations of polarization sensitive scatters. One set is enhanced with VV-polarization, while the second population is enhanced with HH-polarization. It was not determined if these populations were equally distributed. Again, it appears that circular polarization distributed the energy associated with these scatterers throughout all channels.

The scene in Figure 64 was chosen because it provided a linear string of point scatterers in a weak background. In the center is an assembly of points which line the sides and center of the airport runway. In the bottom edge of the image is a string of scatterers which may be a fence. Linear cross-polarization worked well to suppress the scatterers associated with the fence, but the points on the runway are still prominent, though probably reduced in intensity by many dB. The response at VV and HH polarization look reasonably similar, with HH-polarization providing possibly more scattering points, but at a minimum they are more distinct in the clutter background. It is difficult to tell the difference between the circular polarization case and the HH case.

An ensemble of organized scatterers is presented in Figure 65 and are associated with a plant facility. In this case, the most prominent features are observed in the linear cross-polarized scenes, but, in a general sense, there is a good deal of similarity between the responses for all of the polarization cases.

The terminal area at an airport presents a critical problem in that it has been seen to be the primary source of intense scatter within

the airport clutter area. In Figure 66, the Denver Stapleton terminal area is presented. Responses are similar in all polarization cases. Linear cross-polarization is reduced from that produced at the like polarizations. The greatest number of scatterers is visible in the VV image when compared to the HH image. The circular polarization cases are interesting in that RR and RL are most similar to the VV case, while LR and LL are more similar to the HH case.

Determination of Target-to-Clutter Ratios

Given that ZDR = $\sigma_{\rm HHr}/\sigma_{\rm VVr}$ (subscript r indicates that these are the radar returns for the rain in a microburst) and Pr = $\sigma_{\rm VVc}/\sigma_{\rm HHc}$ (subscript c indicates that these are the radar returns for the ground clutter), the target-to-clutter ratios (TCR) where the target of interest is the rain in a microburst, may be derived:

$$TCR_{HH} = Kr[|S_{HH}|^2]/Kc[|S_{HH}|^2],$$
 (Eq. 21)

$$TCR_{VV} = Kr[|S_{VV}|^2]/Kc[|S_{VV}|^2], \text{ and}$$
 (Eq. 22)

$$TCR_{PLc} = Kr[0.25(S_{HH} + S_{VV})^2]/Kc[0.25(S_{HH} + S_{VV})^2].$$
 (Eq. 23)

where Kr and Kc are system gain constants and RLc indicates circular polarization. Ratios of target-to-clutter ratios will be examined because the issue being addressed here is not what are the actual target-to-clutter ratios, but which polarization produces the largest ratio. Hence, by examining all ratios with respect to HH-polarization, the optimum polarization will be determined. Normalizing the TCR with respect to TCR_{HH} and expressing in terms of ZDR and Pr we have

$$TCR_{VV}/TCR_{HH} = ZDR^{-1}Pr^{-1}$$
, and (Eq. 24)

$$TCR_{RL}/TCR_{HH} \approx (ZDR^{-1} + 1)/(Pr + 1).$$
 (Eq. 25)

Based upon the above, general cases of ZDR and PR were examined. Because raindrops distort in a preferential way, $ZDR \ge 1$ completely describes the range of ZDR values. For the case of Pr, values may be both smaller and larger than 1. In examining the above there are four cases to consider:

- 1. If Pr = 1, then HH is the preferred polarization.
- 2. If ZDR = 1 & Pr < 1, then

VV is preferred over HH, VV is preferred over RLc, and RLc is preferred over HH.

3. If ZDR = 1 & Pr > 1, then

HH is preferred over VV, HH is preferred over RLc, and RLc is preferred over VV.

4. If the clutter scene is mixed, and cases of both Pr < 1 and Pr > 1 exist, then

RLc is preferred over VV or HH.

A computer program was written to examine the polarization preference if ZDR = 1 to 3, and Pr = 0.1 to 1. Results indicate that

- 1. For ZDR = 1 and 0.1 <Pr <1, then VV is preferred.
- 2. For ZDR = 2, VV is preferred for 0.1 < Pr < 0.5 and HH is preferred when 0.5 < Pr < 1.
- 3. For ZDR = 3, VV is preferred for 0.1 < Pr < 0.35 and HH is preferred when 0.35 < Pr < 1.

The clutter results obtained from the Denver polarimetric image set indicate that $\sigma^{\circ}_{HH} > \sigma^{\circ}_{VV}$ by 4 to 13 dB. Man-made targets such as the terminals and buildings produced polarization ratio values of about -5 dB and urban of about -7 dB. For these cases, Pr < 1 and VV is the preferred polarization.

Results

For the rain filled medium case, the matrix of the amplitudes of the scattering cross sections for the linear, circular, and optimum elliptical polarization cases are then

$$[|S|]_{L} = \begin{bmatrix} 1.0 & 0.01 \\ 0.01 & 0.75 \end{bmatrix}_{L}, \qquad (Eq. 26)$$

$$[|S|]_{c} = \begin{cases} 0.189 & 0.861 \\ 0.861 & 0.189 \end{cases}$$
, and (Eq. 27)

$$[|S|]_{E} = \begin{pmatrix} 0.0 & 0.884 \\ 0.884 & 0.0 \end{pmatrix} E$$
 (Eq. 28)

The above provide the following radar scattering cross sections relative to HH-polarization: $|S_{HH}|^2 = 0$ dB, $|S_{VV}|^2 = -2.5$ dB, $|S_{RLc}|^2 = -1.3$ dB, and $|S_{RLc}|^2 = -1.1$ dB. Target-to-clutter ratios (i.e. rain-to-clutter ratios) are derived based on the above and the clutter backscatter responses and are provided in Table I2. Results provided in this table show that the target-to clutter ratios for VV are larger than for HH (on average by about 5.75 dB) or for RLc (on average by about 2.75 dB). However, if the elliptical polarization which maximizes the cross-polarization response (noting that RLe \approx LRe) is obtained, then TCRs which are a few dB greater than those produced at VV-polarization may be

obtained. This was found true for the urban, terminal, or building clutter, but not for the residential clutter.

VIII. CONCLUSIONS

The mountain terrain data obtained from the Rocky Mountain image correlates well with data obtained from the other Denver images. Clutter groups common to all of the Denver data produced similar results. An interesting feature of the mountain terrain data is the similarity in the shape of the backscattering coefficient distributions of the mountain, geological thrust feature, and grass clutter. This is not surprising however, as the vegetation on the surfaces of the grass areas, mountains, and thrust feature was similar. The mean returns from the mountain areas and thrust features are significantly higher than those of the grassy areas due to the local slope of these geological features. An analysis of the returns from these two geological features produced results applicable to the problem of range ambiguity effects potentially associated with mountainous terrain. Although the data in the Rocky Mountain Image did not produce a range ambiguity problem with the SAR, an analysis may be performed using mean backscattering coefficients calculated from the data to determine range ambiguity effects for other systems. In calculating a test case using the maximum mountain return and minimum airport return found in the data, it was determined that as long as an airport is approximately 1.5 miles from steep geological features, mountain clutter may not present this type of a problem.

The analysis of the low altitude images has provided additional data to complement the description of ground clutter in the Denver area, especially that of hard targets at high incidence angles. These data provided excellent angle diversity and the scattering associated with the front sides of buildings at large incidence angles was dramatically illustrated and documented. In general, cultural clutter returns which arise from city buildings and prominent structures may produce backscattering coefficients 30 dB above a background level of -18 dB at 85° to 86°. Other clutter groups correlate well with previously analyzed Denver data. As with other clutter areas, the statistical distributions change from symmetric and narrow to asymetric and broad as the clutter areas change in content from entirely natural targets to entirely man-

made targets. Comparisons of selected image features at different incidence angles reveal that the primary scatterers at large incidence angles are the faces of hard-target structures which are perpendicular or nearly perpendicular to the radar. Most other clutter disappear into the noise at angles of 80° and beyond.

The polarization properties of hydrospheres and clutter were examined. The optimum linear polarization was determined by the polarization ratio. If $\sigma^{\circ}_{HHc} > \sigma^{\circ}_{VVc}$, then VV-polarization is the preferred polarization. VV-polarization is preferred over circular polarization (RL or LR), except when the clutter scene has a non-preferential mix of Pr ratios. In this case, circular polarization is anticipated to be the preferred polarization. It was illustrated in this study that elliptical polarization, based on the scattering matrix for a rain-filled medium, produced the optimum target-to-clutter ratio.

These results suggest that the distribution of the polarization ratio of the ground clutter needs to be well-characterized for the imaging geometry of the microburst detection radar. This supports the determination of the optimum polarization. Results also indicate that, at large angles, clutter levels are the greatest at HH-polarization. In addition, characterization of the polarization properties of microbursts may provide a reliable definition of the optimum elliptical polarization. If this polarization can be defined, then the optimum polarization is an elliptical polarization.

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Table 1. NASA LaRC Denver Flight Summary

Comments	1st Step West, West-Look	Full Pol Airport, West-Look	Full Pol Airport, East-Look	Full Pol Airpot Mid Angle, West-Look	Double Swath Airport, East-Look	2nd Step West, West-Look	Rocky Mountains, Double Swath	Rocky Mountains, Double Swath	Rocky Mountains, Double Swath	Rocky Mountains, Full Pol	Bocky Mountains, Full Pol				
End Lon	104:44.43	104:45.42	104:59.28	104:50.35	105:03.77	104:47.43	105:06.82	105:06.82	105:06.82	105:08.63	105:08.63	105:08.63	105:08.63	105:08.63	105:08.63
End Lat	39:36.49	39:36.49	39:56.51	39:36.49	39:56.51	39:36.49	40:14.52	40:14.52	40:14.52	39:32.48	39:32.48	39:32.48	39:32.48	39:32.48	39:32.48
Beg Lon	104:44.43	104:45.52	104:59.28	104:50.35	105:03.77	104:47.43	105:06.82	105:06.82	105:06.82	105:08.63	105:08.63	105:08.63	105:08.63	105:08.63	105:08.63
Beg Lat	39:56.51	39:56.51	39:36.49	39:56.51	39:36.49	39:56.51	39:32.48	39:32.48	39:32.48	40:14.52	40:14.52	40:14.52	40:14.52	40:14.52	40:14.52
Pass	8	4	9	ω	10	12	4	15	16	18	19	20	21	22	23

NASA LaRC Denver Flight Summary (Cont.)

388	Beg Lat	Beg Lat Beg Lon	End Lat	End Lon	Comments
52	39:36.49	104:50.43	39:56.51	104:50.43	3rd Step West, West-Look
27	39:56.51	104:41.03	39:36.49	104:41.03	Double Swath Airport, West-Look
ຄ	39:36.49	104:53.43	39:56.51	104:53.43	4th Step West, West-Look
ల్ల	39:36.48	39:36.49 104:53.43	39:56.51	104:53.43	4th Step West, West-Look
31	39:55.36	39:55.36 104:44.63	39:55.36	105:11.88	Double Swath Airport, South-Look
33	39:51.79	104:44.23	39:51.79	105:11.47	Full Pol Airport, South-Look
32	39:44.89	104:44.23	39:44.89	1,05:11.47	Full Pol Airport Mid Angle North-Look
37	39:41.17	104:44.24	39:41.17	105:11.46	Full Pol Airport, North-Look
39	39:37.60	104:44.64	39:37.60	105:11.86	Double Swath Airport, North-Look
4	39:36.49	104:53.43	39:56.51	104:53.43	4th Step West, West-Look
2 2	39:36.49	104:53.43	39:56.51	104:53.43	4th Step West, West-Look
43	39:40.49	104:53.31	39:52.50	104:53.31	Low Altitude, West-Look
4	39:40.49	104:53.31	39:52.50	104:53.31	Low Altitude, West-Look

Table 2. Image Composition Areal Analysis, Rocky Mountain Image

	Doront of Total langua Aron
	reiceill of Total IIIIage Alfa
Residential	8.0
Rural	19.0
Thrust Feature	7.0
Mountains	66.0

Clutter Returns for Targets in the Rocky Mountains Image, X-HH Table 3.

7	Mean (dB)	MIN (dB)	Max (dB)	SDev (MAG)	Mean + SDev (dB) Mean
Grass (45°-49°)	-21.89	-35.48	-12.81	0.59509E-02	2.83
Grass (60°-64°)	-26.11	-35.48	-6.94	0.39100E-02	4.44
Grass (65°-69°)	-27.57	-35.48	-8.68	0.28616E-02	4.21
Grass (70°-74°)	-28.68	-35.48	-14.37	0.16956E-02	3.52
Grass (75°-79°)	-29.81	-35.48	-18.71	0.12856E-02	3.48
Mountain (65°-69°)	-17.23	-35.48	-5.63	0.22962E-01	3.45
Mountain (70°-74°)	-16.17	-35.48	-5.21	0.28489E-01	11.07
Mountain (75°-79°)	-25.57	-35.48	-9.19	0.64210E-02	5.21
Residential (40°-49°)	-5.15	-35.48	20.33	0.20633E+01	8.90
Residential (50°-59°) -13.14	-13.14	-35.48	17.10	0.47496E+00	10.33
Residential (60°-64°) -18.30	-18.30	-35.48	13.15	0.12981E+00	9.90
Residential (65°-69°) -12.52	-12.52	-35.48	21.00	0.11668E+01	13.39
Residential (70°-74°) -19.08	-19.08	-35.48	8.17	0.80215E-01	8.74
Thurst (65°-69°)	-11.37	-35.48	1.57	0.78578E-01	3.17
Thurst (70°-74°)	-18.22	-35.48	-5.01	0.16711E-01	3.24
Thurst (75°-79°)	-21.65	-35.48	-9.56	0.71796E-02	3.12
Water (55°-59°)	-35,42	-35.48	-27.46	0.45580E-04	0.64
Water (65°-59°)	-35.23	-35.48	-21.25	0.24487E-03	2.59
Water (70°-74°)	-35,46	-35.48	-29.22	0.32042E-04	0.46

Table 4. Image Composition Areal Analysis, Low Altitude Images

Clutter Scene	Percent of Total Image Area
Rural	7.10
Residential	1.95
Urban	18.71
City	0.22
Airport Grounds	8.12
Lowry AFB	1.62
Recreational Areas	0.64
Warehouses	2.10
Mixed City and Industrial	11.37
Unclassified/City	48.17

Table 5. Clutter Returns for Targets in the X-HH Low Altitude Image

	(dB)													-	i	
0	Mean + Surey (dB)	3.13	5.40	7.96	11.92	13.71	12.38	5.38	6.58	4.27	11.86	3,29	10.24	5.32	5.05	5.37
	≱			9.1 - 5.2	- - -1		-			-		÷ .				
	SDev (MAG)	0.43735x10-2	0.23352x10-2	0.45907x10 ⁻¹	0.36690x10 ²	0,10742x10 ¹	0.92445x10 ⁰	0.42338x10-1	0.48624x10-1	0.13275x10-3	0.59904x10 ⁰	0.16065x10 ⁻³	0.29332x101	0.46675x10-1	0.21023x10 ⁰	0.29543x10-1
	Max (dB)	-11.25	-7.13	0.50	33.58	20.97	20.18	0.98	5,65	-41.00	13.84	-28.84	19.22	-5.37	3.15	-8.49
	MIN (dB)	-47.22	-47.22	-43.59	-47.22	-47.22	47.22	-40.43	-47.22	-47.22	-47.22	-47.22	-32.29	-32.46	-30,33	-44.90
III ago	Mean (dB)	-23.82	-30.24	-20.58	4.01	-13.21	-12.46	-17.62	-18.63	-41.00	-13.79	-38.29	-5.13	-17.15	-12.85	-19.17
	4	Grass (40°-49°)	Grass (75°-79°)	Buildings (40°-49°)	Buildings (85°-89°)	Industrial (80°-84°)	City (80°-84°)	Residential (65°-69°)	Urban (65°-69°)	Water (60°-64°)	Parking Lot (80°-84°)	Runway (60°-64°)	Terminal (H6)	Plane (H73)	Plane (H75)	Truck (H14)
										-						

RS-90-131-2a

Table 6. Clutter Returns for Targets in the X-VV Low Altitude Image

	ımage				
·	Mean (dB)	MIN (dB)	Max (dB)	SDev (MAG)	Mean + SDev (dB)
Grass (40°-49°)	-24.22	-53.33	-12.50	0.40316x10-2	3.15
Grass (75°-79°)	-31.39	-53.33	-2.00	0.32115x10-2	7.34
Buildings (40°-49°)	-19.24	-40.05	-0.54	0,49171x10 ⁻¹	7.10
Buildings (85°-89°)	6.35	-53.33	35.33	0.58432x10 ²	11.63
Industrial (80°-84°)	-9.01	-53.33	21.02	0.16915x101	11.60
City (80°-84°)	-7.55	-53.33	28.52	0.39557x10+1	13.71
Residential (65°-69°) -17.29	17.29	-39.94	2.76	0.63513x10-1	6.44
Urban (65°-69°)	-18.78	-41.80	1.96	0.52876x10 ⁻¹	6.98
Water (60°-64°)	-38.35	-53.33	-23.13	0.30207x10-3	4.87
Parking Lot (80°-84°)	09'6- (-53.33	14.26	0.98772x10 ⁰	10.00
Runway (60°-64°)	-31.43	-53.33	-20.58	0.10600x10-2	3.99
Terminal (H6)	-11.90	-42.40	10.23	0.45606×10 ⁰	9.07
Plane (H73)	-20.39	-46.01	-0.52	0.57611x10 ⁻¹	8.63
Plane (H75)	-15.99	-42.82	3.04	0.17623x10 ⁰	9.03
Truck (H14)	-18.07	-39.10	-7.17	0.41057x10 ⁻¹	5.60

Table 7. Hard Targets Represented as σ , Low Altitude Image, X-HH

Indentifier	Region	0	σ (dDám\	Effective Area
			(dBśm)	(m²)
H1	Building	77.43	28.12	18,102.5
H5	Terminal	78.85	29.82	12,239.42
H6	Terminal	78.09	42.43	57,371.33
H7 H8	Terminal	74.82	13.18	25,194.24
нв Н9	Parking Lot	81.13 79.36	34.51 27.37	16.236.29
H10	Parking Lot Plane	79.36 74.82	-0.77	26,842.75 1,508.54
H11	Plane	77.67	11.03	1,026.43
H12	Plane	75.90	2.56	1,446.34
H13	Parking Lot	77.37	30.30	36,827.14
H15	Truck	66.98	-0.39	373.25
H16	Truck	77.44	2.18	279.94
H17	Parking Lot	79.45	28.35	13,779.07
H19	Plane	77.18	12.75	1,244.16
H20	Plane	77.23	13.11	1,959.55
H21 H22	Plane	77.18	16.65	948.67
H23	Parking Lot Fence	81.13 76.44	25.79 10.19	6,283.01 12,379.39
H25	Building	64.34	22.30	30,497.47
H26	Building	50.88	21.70	15,552.00
H27	Parking Lot	79.57	32.12	31,555.01
H29	Building	83.81	60.96	6,531.84
H33	Building	82.82	40.71	2,597.18
H34	Building	82.88	20.59	202.18
H54	Building	85.83	33.90	248.83
H56	Building	85.47	41.28	746.50
H59 H63	Building Building	85.58 83.92	47.34 44.69	1,026.43
H65	Building	86.04	53.09	1,010.88 637.63
H68	Building	86.95	50.06	186.62
H73	Plane	77.40	16.93	2.410.56
H74	Plane	76.87	9.47	1,384.13
H75	Plane	78.12	20.61	2,255.04
H76	Truck	78.12	8.88	2,006.21
H77	Truck	74.62	9.58	2,006.21
H78	Building	49.54	22.13	18,662.40
H79 H80	Building	67.23	23.24	18,646.85
H84	Building Building	58.30 79.62	28.96 40.04	18,631,30
H87	Building	79.02 74.05	17.65	37,153.73 6,236.35
H89	Building	74.36	22.24	30,964.03
H91	Building	76.72	17.62	13,125.89
H94	Building	77.78	28.55	7,185.02
H95	Building	65.70	26.10	9,253.44
H96	Building	65.82	26.59	13,359.17
H97	Building	66.27	21.28	6,454.08
H110	Terminal	78.37	32.74	29,144.45
H111 H112	Structure	58.20 58.20	6.60	1,259.71
H114	Structure Structure	71.79	12.08 14.88	1,259.71
H115	Structure	73.43	12.04	1,259.71 1,259.71
H117	Structure	75.86	17.78	1,150.85
H124	Structure	80.57	0.51	15.55
H125	Warehouse	46.51	22.39	6,220.80
H126	Warehouse	55.14	24.60	24,883.20
M1	Tree	70.16	10.74	762.05
M2	Tree	55.63	18.83	4,665.60
М3	Tree	66.66	24.24	15,334.27
M4 M5	Tree	51.67	22.59	30,326.40
CIM	Tree	74.00	19.31	13,965.70

Table 8. Hard Targets Represented as σ, Low Altitude Image, X-VV

	~go, /			
Indentifier	Region	0	σ	Effective Area
			(dBsm)	(m²)
		77.40	00.70	00 00E 14
H1	Building	77.43 78.85	29.72 33.36	30,995.14 30,466.37
H5 H6	Terminal Terminal	78.09	36.01	62,208.00
H7	Terminal	74.82	21.32	43,234.56
H8	Parking Lot	81.13	38.03	38,257.92
H9	Parking Lot	79.36	33.32	38,833.34
H10	Plane	74.82	11.43	3,110.40
H11	Plane	77.67	12.85	2,892.67
H12	Plane	75.90	-4.69	2,861.57
H13	Parking Lot	77.37	29.99	38,880.00
H15	Truck	66.98	-0.32	388.80
H16	Truck	77.44	1.28	373.25
H17	Parking Lot	79.45	23.96	18,055.87 3,094.85
H19	Plane	77.18 77.23	3.77 4.78	3,405.89
H20 H21	Plane Plane	77.23 77.18	7.20	1,586.30
H22	Parking Lot	81.13	33.31	34,727.62
H23	Fence	76.44	9.13	17,760.38
H25	Building	64.34	19.12	31,057.34
H26	Building	50.88	24.57	15,552.00
H27	Parking Lot	79.57	34.97	70,621.63
H29	Building	83.81	61.74	11,912.83
H33	Building	82.82	45.51	9,206.78
H34	Building	82.88	-2.45	1,057.54
H54	Building	85.83	36.26	1,073.09
H56	Building	85.47	44.68	2,970.43
H59	Building	85.58	49.59	2,130.62 1,026.43
H63 H65	Building Building	83.92 86.04	28.41 55.33	2,441.66
H68	Building	86.95	50.48	451.01
H73	Plane	77.40	17.54	6,345.22
H74	Plane	76.87	13.48	6,407.42
H75	Plane	78.12	21.52	5,894.21
H76	Truck	78.12	5.86	2,239.49
H77	Truck	74.62	5.02	2,239.49
H78	Building	49.54	23.46	18,662.40
H79	Building	67.23	26.64	18,662.40
H80	Building	58.30	29.51	18,662.40
H84	Building	79.62	41.42	62,052.48
H87 H89	Building	74.05 74.36	20.76 17.43	6,298.56 31,104.00
H91	Building Building	76.72	14.54	18,506.88
H94	Building	77.78	29.51	7,776.00
H95	Building	65.70	27.42	9,253.44
H96	Building	65.82	23.92	13,436.93
H97	Building	66.27	25.11	6,469.63
H110	Terminal	78.37	33.83	53,887.68
H111	Structure	58.20	7.88	1,259.71
H112	Structure	58.20	13.22	1,259.71
H114	Structure	71.79	12.52	1,259.71
H115	Structure	73.43	11.69 10.48	1,259.71 1,259.71
H117 H124	Structure Structure	75.86 80.57	5.19	217.73
H125	Warehouse	46.51	26.26	6,220,80
H126	Warehouse	55.14	27.10	24,883.20
М1	Tree	70.16	14.75	762.05
M2	Tree	55.63	17.98	4,665.60
М3	Tree	66.66	23.09	15,552.00
M4	Tree	51.67	22.17	30,326.40
M5	Tree	74.00	15.30	13,996.80

Table 9. Comparison of Hard Target σ Values

Table 10. Incidence Angles of Sub-Images

oub-illages	Incidence Angle	68.9° 78.6° 78.9° 82.8°	68.3° 78.4° 82.2° 83.9°	67.4° 77.7° 78.1°	67.9° 72.9° 80.5°	72.8° 79.7°	63.9° 77.3° 81.7°
inciderice Arigies of Sub-infages	Source Image	Third 'Step West' Low Altitude Image Second 'Step West' First 'Step West'	Fourth 'Step West' Third 'Step West' Second 'Step West' Low Altitude Image	Third 'Step West' Low Altitude Image Second 'Step West'	Low Altitude Image Second 'Step West' First 'Step West'	Fourth 'Step West' Third 'Step West'	Fourth 'Step West' Third 'Step West' Second 'Step West'
rable 10.	Feature	Terminals Terminals Terminals Terminals	Golf Course Golf Course Golf Course Golf Course	Planes Planes Planes	Warehouses Warehouses Warehouses	City Park City Park	Dog Track Dog Track Dog Track

Scattering Matrices for a Sphere, Flatplate, Trihedral, and Dihedral are Provided for Both the Linear and Circular Basis Table 11.

Scallering Mail IX
Linear bas
1 0
0 -1 0
<u></u> 0
0.707 0.707 0.707 -0.707
1 0

Normalized Radar Scattering Cross-Sections and Rain-to-Clutter Ratio's for Urban, Residential, Terminals, and Buildings Table 12.

Description	壬 8	M dB	LR _c	Rain Filled LRe dB	VV/LRc dB	LR _e /VV dB
Rain RFM/ Normalized	Ø	-2.5	-1.3	1.1	-	!
Urban Residential Terminals Buildings	-9.64 -7.8 +5.81 1.89	-16.3 -20.4 -1.09 -4.29	-13.6 -13.4 +1.57 -1.48	-16.54 -13.8 53 -6.05		
Urban Residential Terminals Buildings	0000	-6.66 -12.60 -6.89 -6.18	-3.96 -5.6 -4.23 -3.37	-6.90 -6.0 -6.33 -7.94		
Urban Residential Terminals Buildings	0000	4.2 10.1 4.4 4.3	7.8.9.5 7.8.9.1	5.8 6.6 6.6	2. 5. 5. 5. 5. 5. 5. 5. 5. 5. 5. 5. 5. 5.	1.6 -5.2 .6 2.3

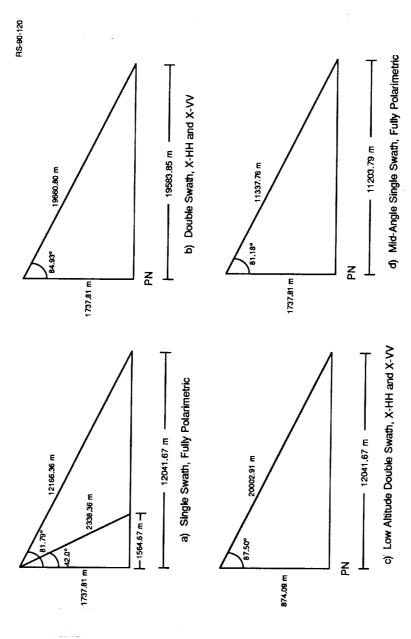
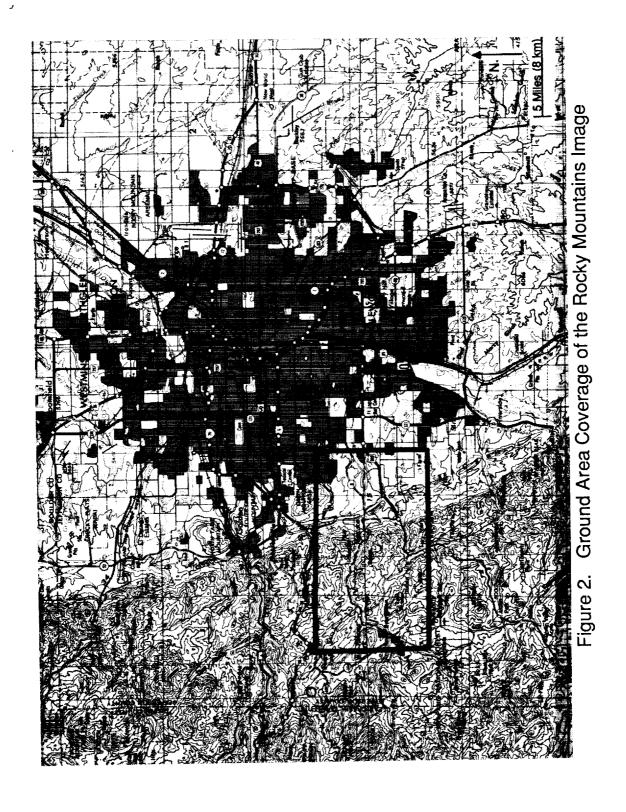


Figure 1. Image Geometries Used in the Denver Collection a) Single Swath b) Double Swath c) Low Altitude d) Mid-Angle



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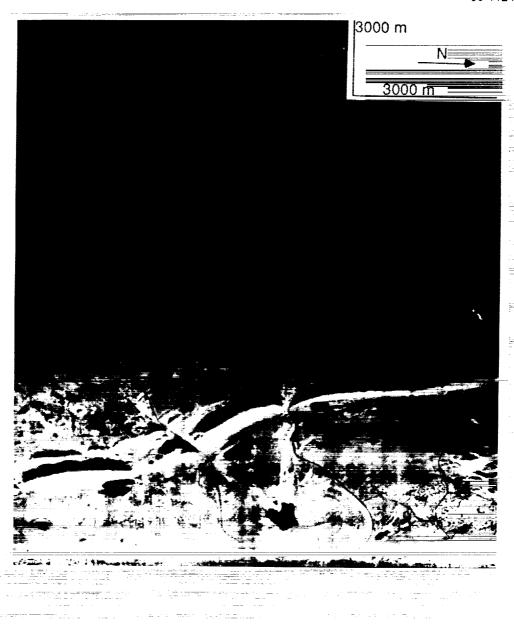


Figure 3. Rocky Mountains Image, X-HH

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Bar Chart Presentation of Means and Standard Deviations

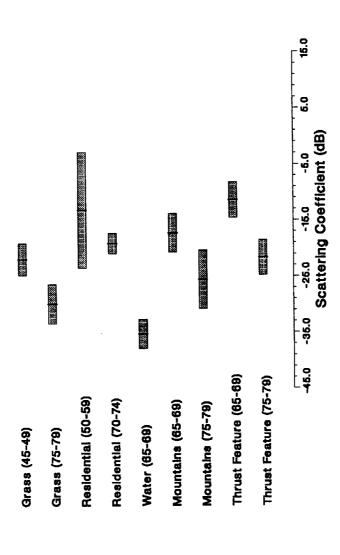
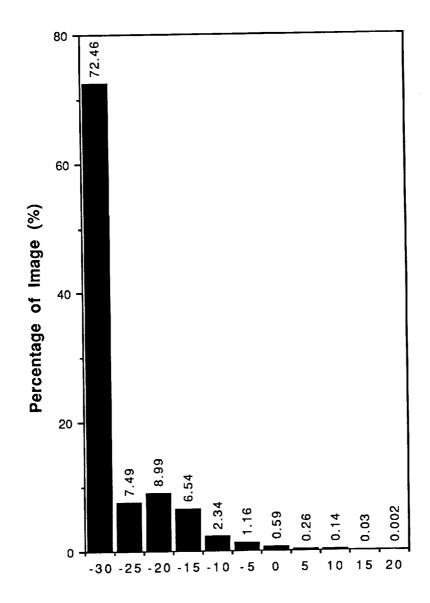


Figure 4. Mean Scattering Coefficient Values, Rocky Mountains Image, X-HH



Figure 5. Threshold Images, Rocky Mountains Image, X-HH



Radar Scattering Cross-Section (dB)

Figure 6. Distribution of Threshold Values, Rocky Mountains Image, X-HH

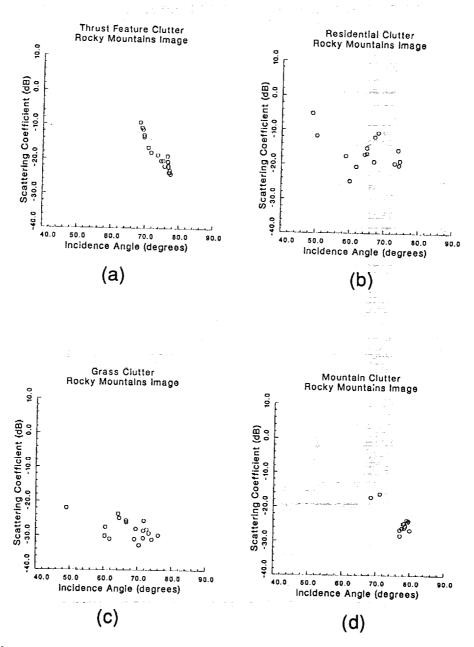


Figure 7. Incidence Angle vs. Scattering Coefficient Plots

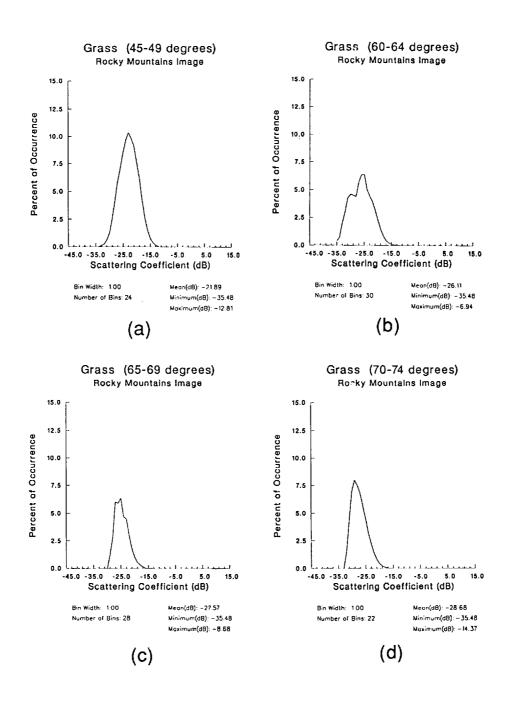


Figure 8. Clutter Distributions of Grass Areas, X-HH

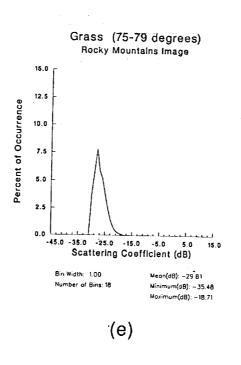


Figure 8. Clutter Distributions of Grass Areas, X-HH (Cont.)

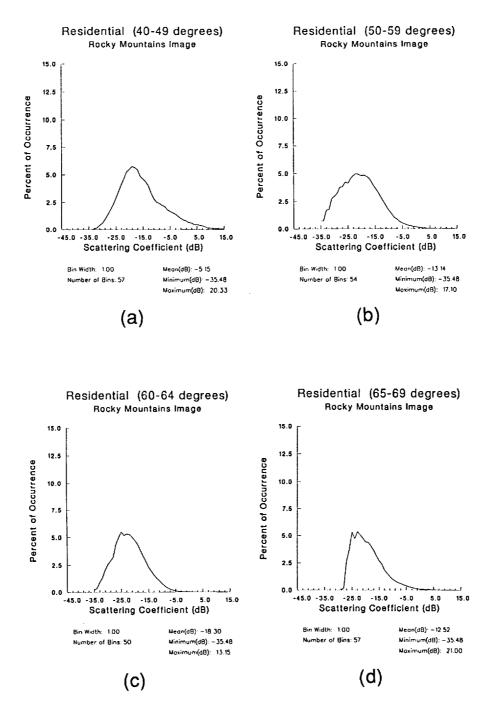


Figure 9. Clutter Distributions of Residential Areas, X-HH

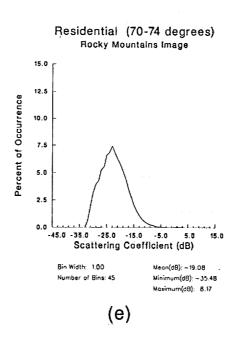


Figure 9. Clutter Distributions of Residential Areas, X-HH (cont.)

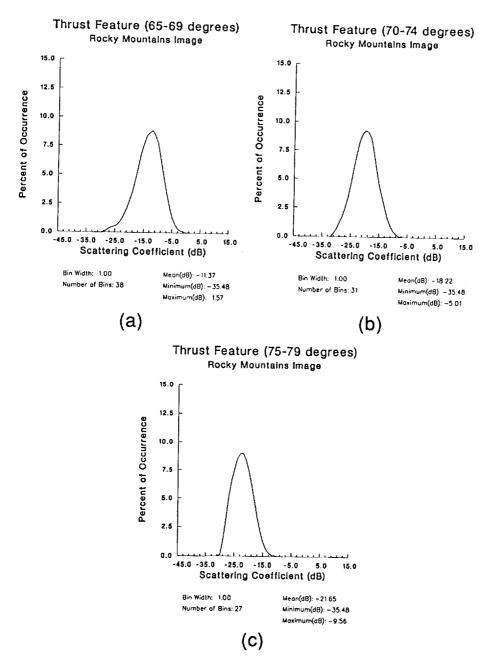


Figure 10. Clutter Distributions of Thrust Feature Areas, X-HH

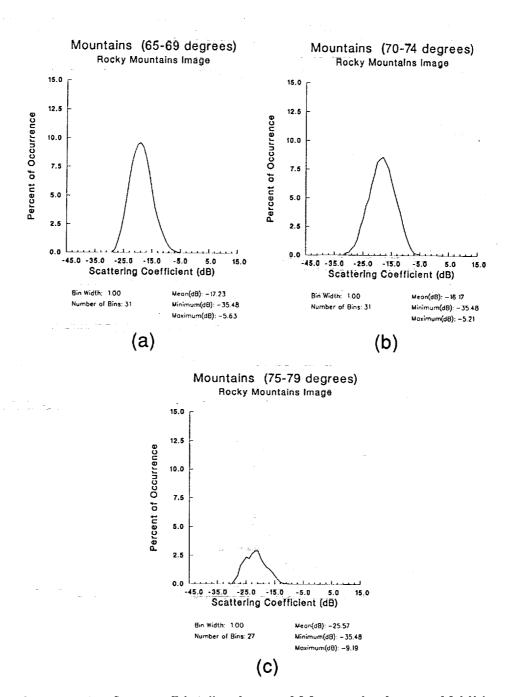


Figure 11. Clutter Distributions of Mountain Areas, X-HH

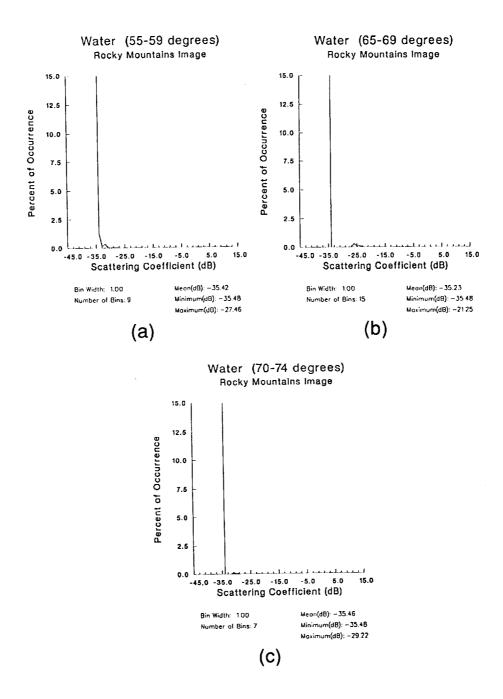
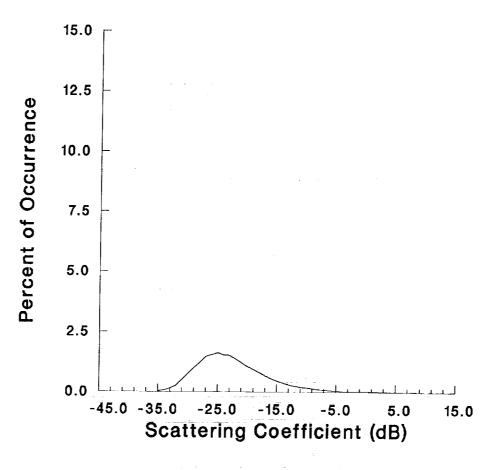


Figure 12. Clutter Distributions of Water Areas, X-HH

Rocky Mountains Image



Bin Width: 1.00

Number of Bins: 68

Mean(dB): -18.97

Minimum(dB): -35.48

Maximum(dB): 31.29

Figure 13. Clutter Distribution, Rocky Mountains Image, X-HH

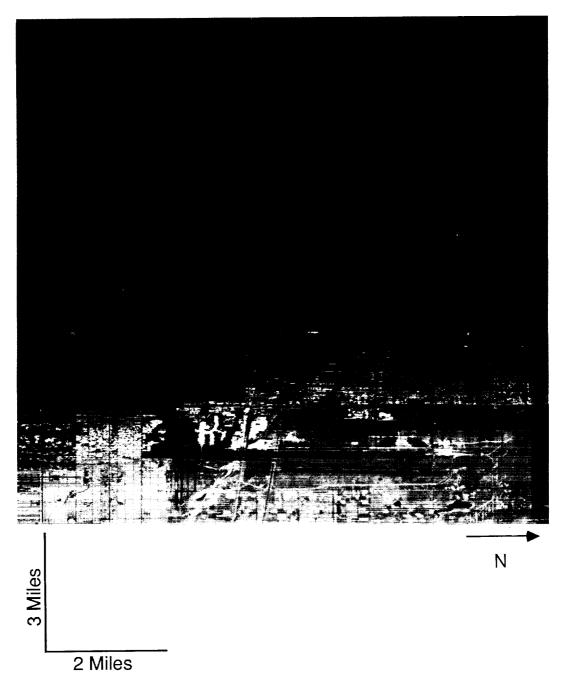


Figure 14. Low Altitude Image, X-HH

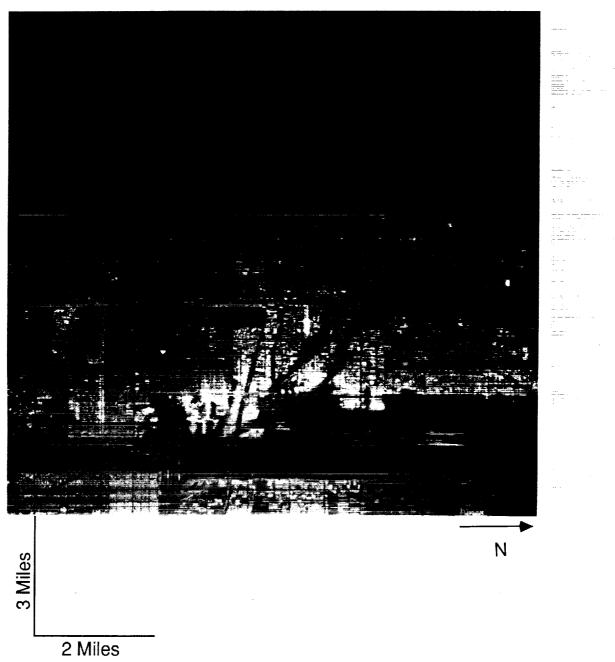


Figure 15. Low Altitude Image, X-VV

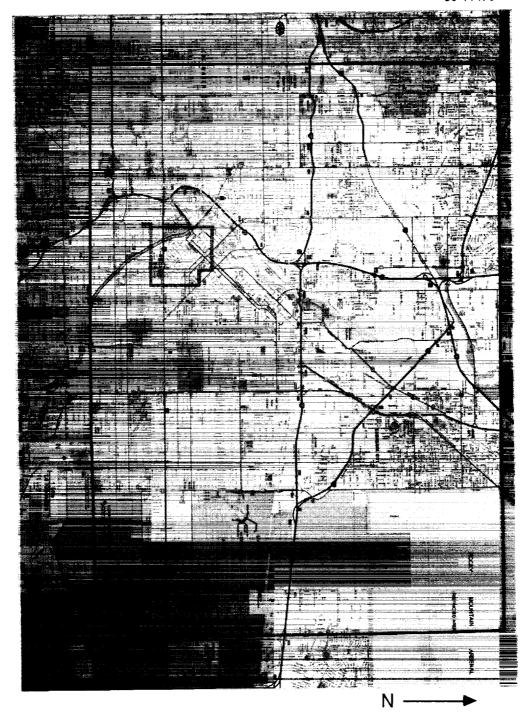


Figure 16. Ground Area Coverage of the Low Altitude Images

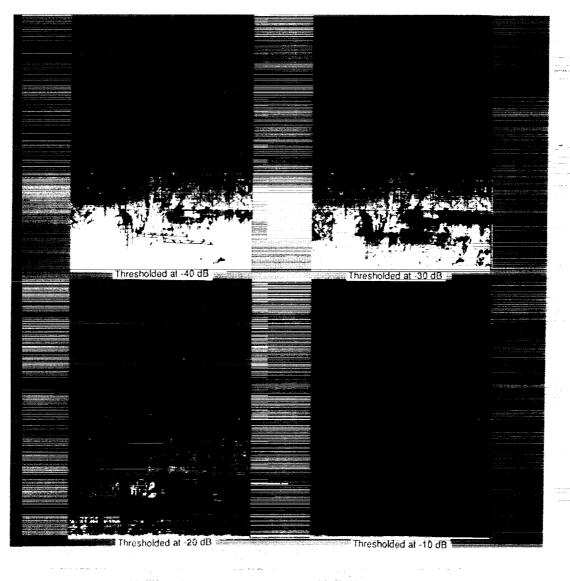


Figure 17. Threshold Images, Low Altitude Image, X-HH

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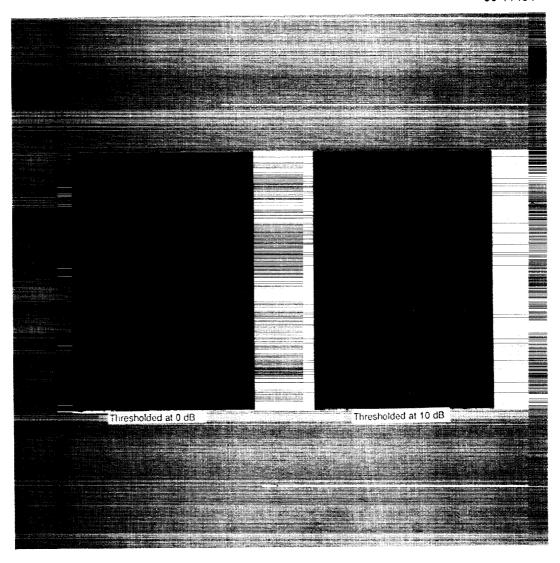
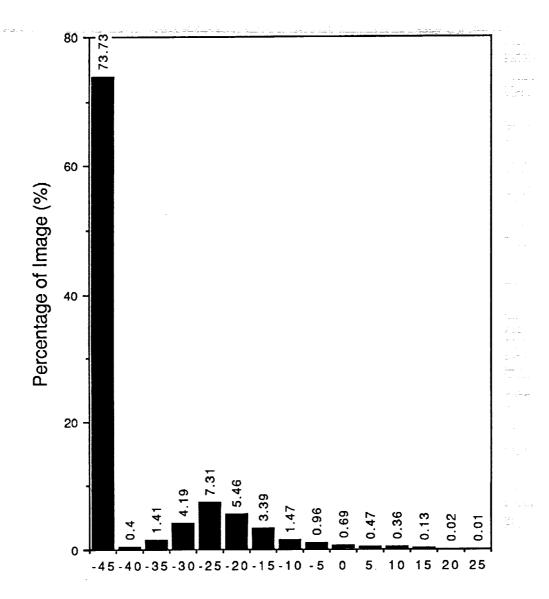


Figure 17. Threshold Images, Low Altitude Image, X-HH (cont.)



Radar Scattering Cross-Section (dB)

Figure 18. Distribution of Threshold Values, Low Altitude Image, X-HH

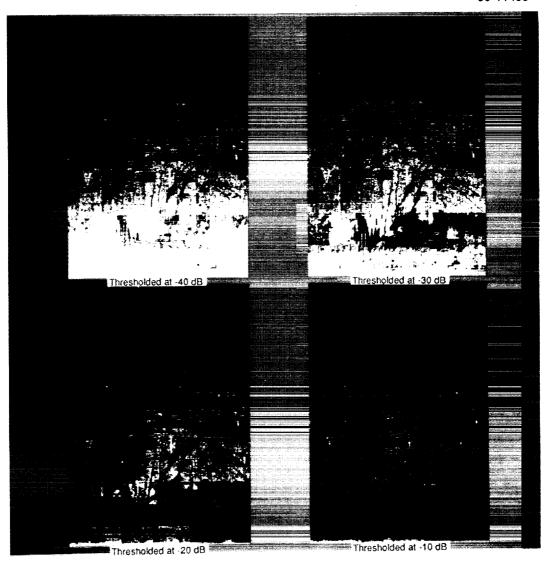


Figure 19. Threshold Images, Low Altitude Image, X-VV

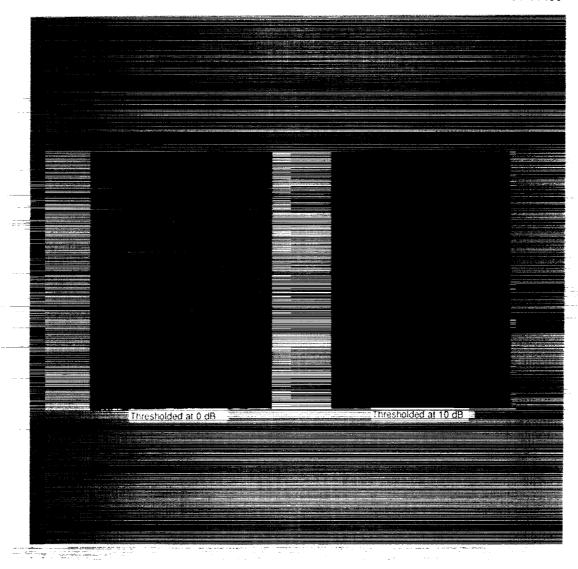
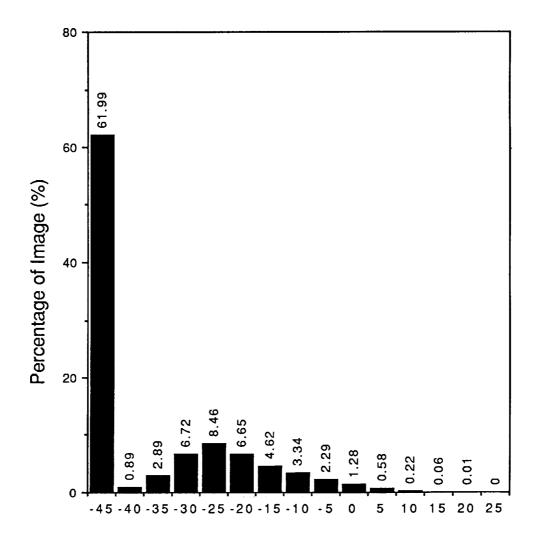


Figure 19. Threshold Images, Low Altitude Image, X-VV (cont.)



Radar Scattering Cross-Section (dB)

Figure 20. Distribution of Threshold Values, Low Altitude Image, X-VV

Bar Chart Presentation of Means and Standard Deviations

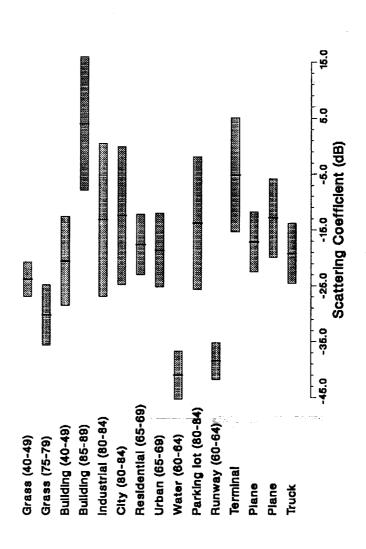


Figure 21. Mean Scattering Coefficient Values, Low Altitude Image, X-HH

Bar Chart Presentation of Means and Standard Deviations

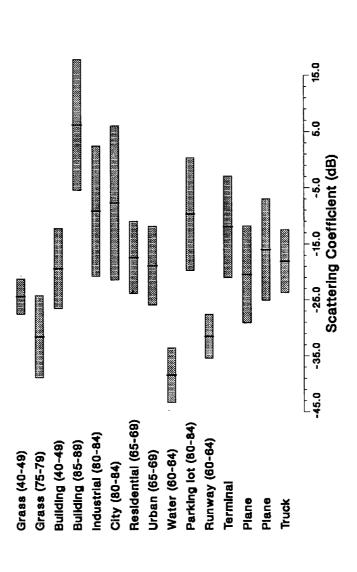


Figure 22. Mean Scattering Coefficient Values, Low Altitude Image, X-VV

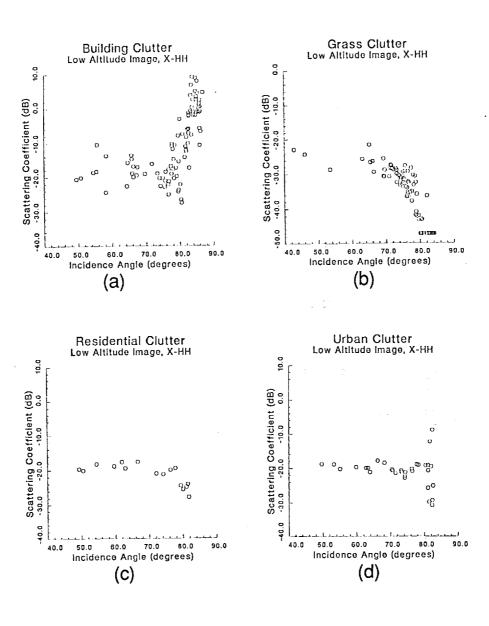
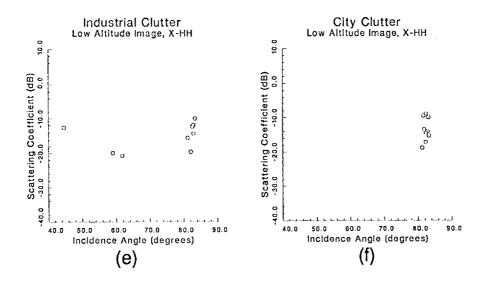


Figure 23. Scattering Coefficient vs. Incidence Angle Plots, X-HH



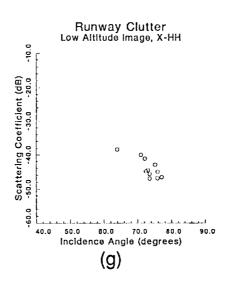


Figure 23. Scattering Coefficient vs. Incidence Angle Plots, X-HH (cont.)

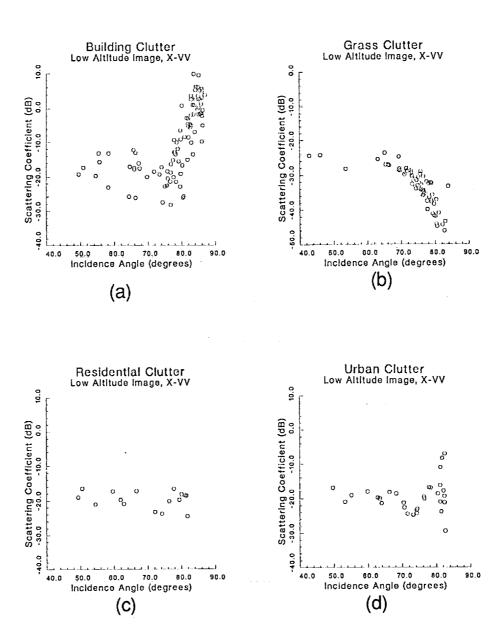
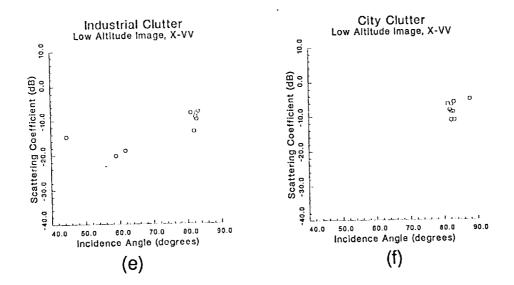


Figure 24. Scattering coefficient vs. Incidence Angle Plots, X-VV



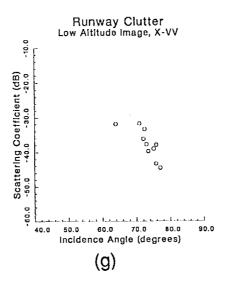


Figure 24. Scattering Coefficient vs. Incidence Angle Plots, X-VV (cont.)

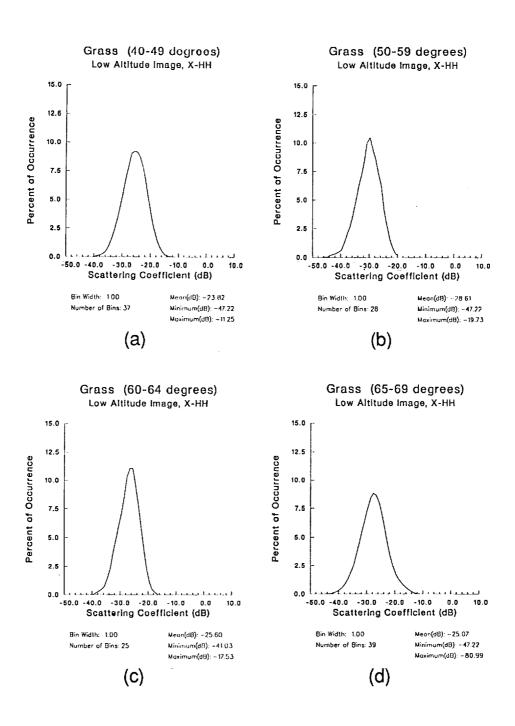


Figure 25. Clutter Distributions of Grass Areas, X-HH

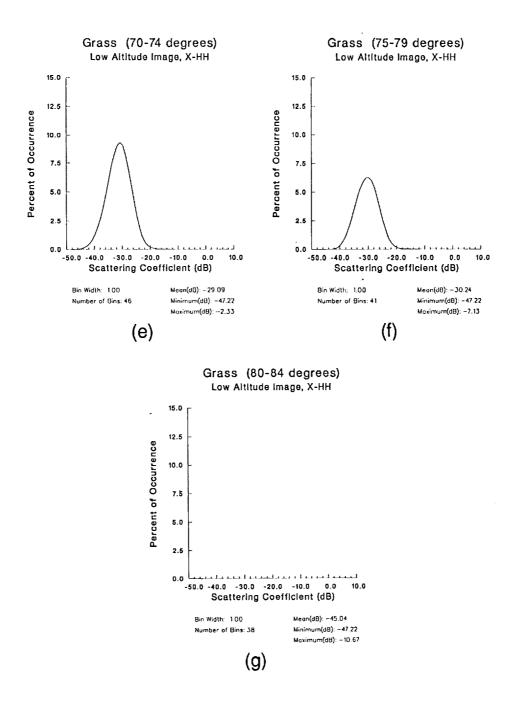


Figure 25. Clutter Distributions of Grass Areas, X-HH (cont.)

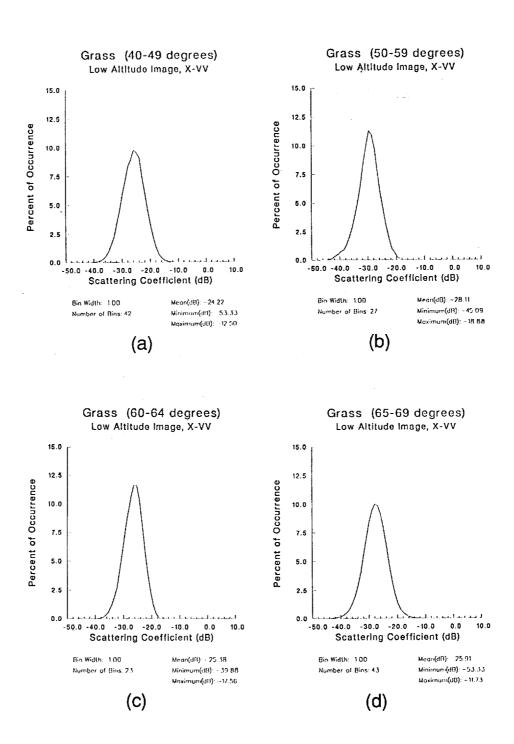


Figure 26. Clutter Distributions of Grass Areas, X-VV

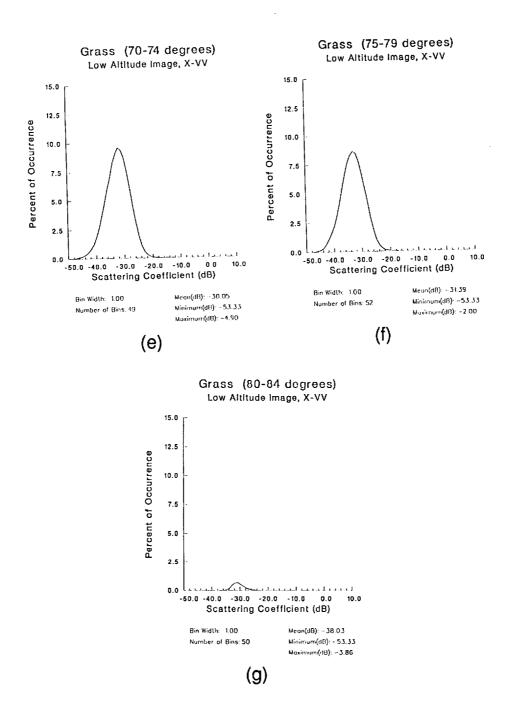


Figure 26. Clutter Distributions of Grass Areas, X-VV (cont.)

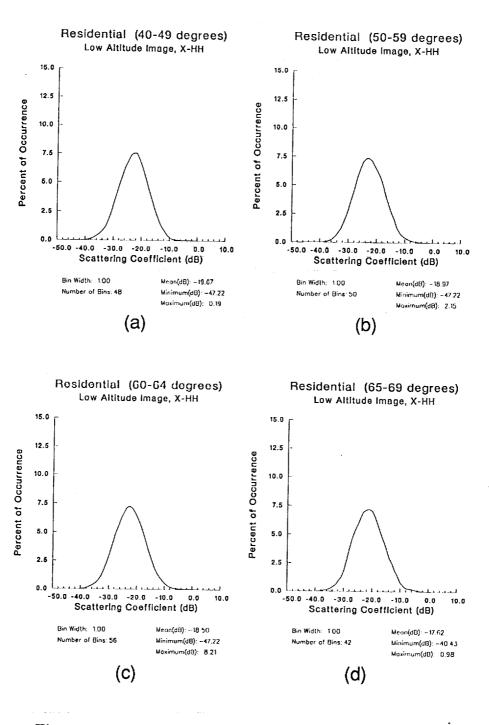


Figure 27. Clutter Distributions of Residential Areas, X-HH

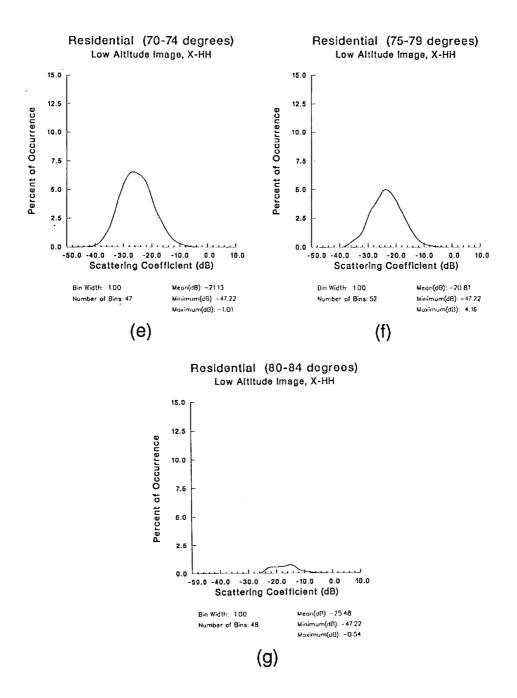


Figure 27. Clutter Distributions of Residential Areas, X-HH (cont.)

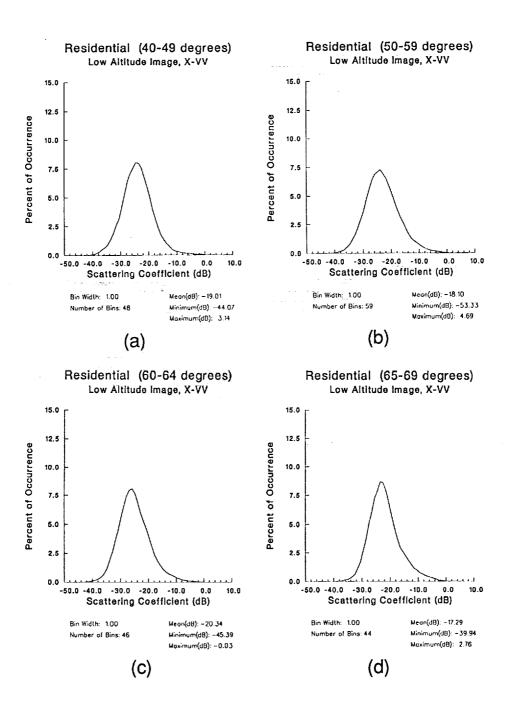


Figure 28. Clutter Distributions of Residential Areas, X-VV

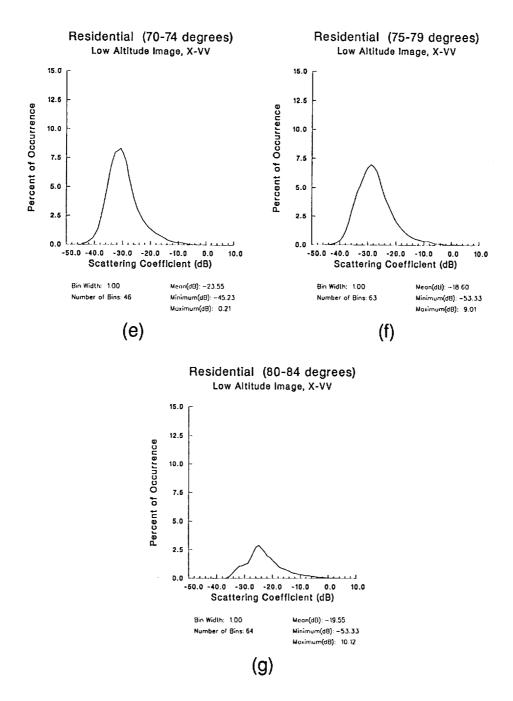


Figure 28. Clutter Distributions of Residential Areas, X-VV (cont.)

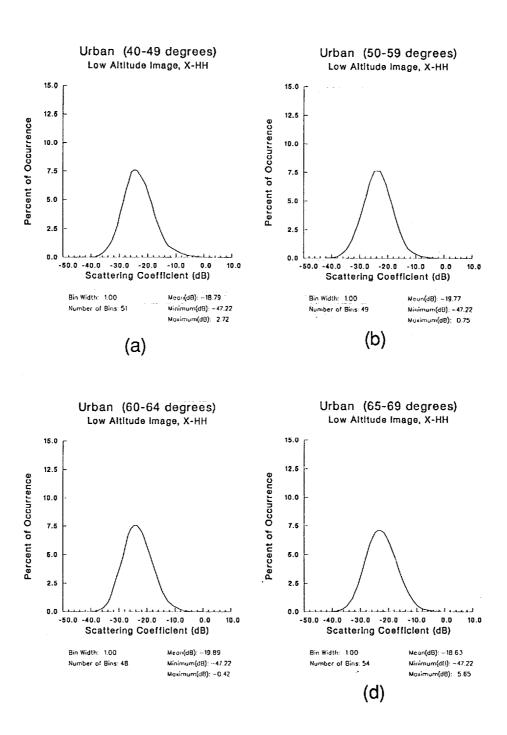


Figure 29. Clutter Distributions of Urban Areas, X-HH

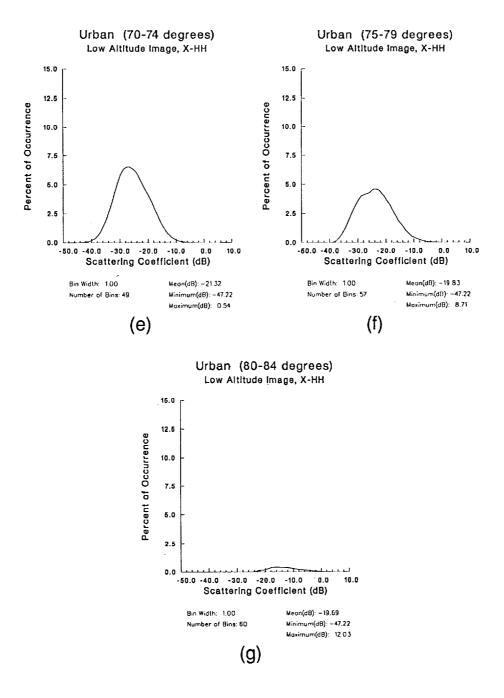


Figure 29. Clutter Distributions of Residential Areas, X-HH (cont.)

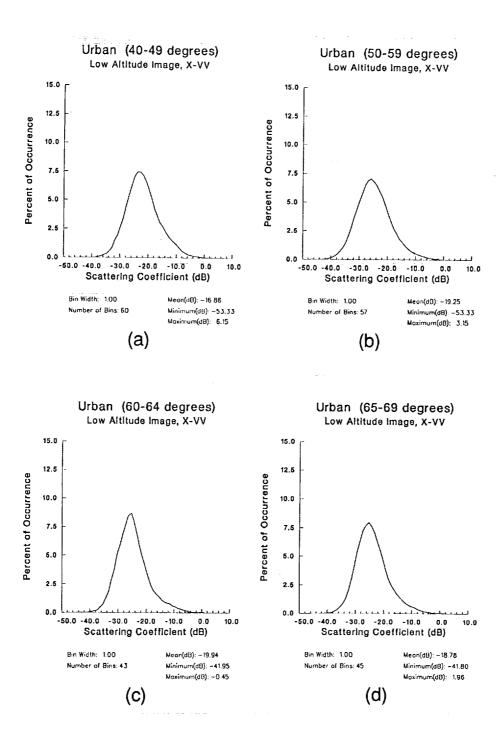


Figure 30. Clutter Distributions of Urban Areas, X-VV

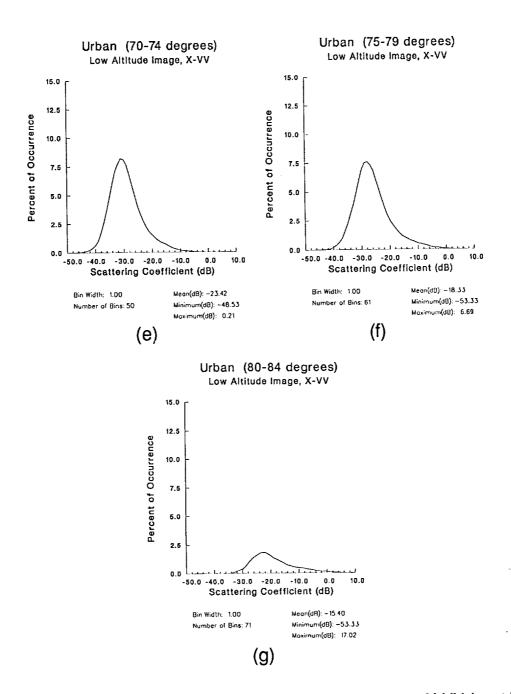


Figure 30. Clutter Distributions of Residential Areas, X-VV (cont.)

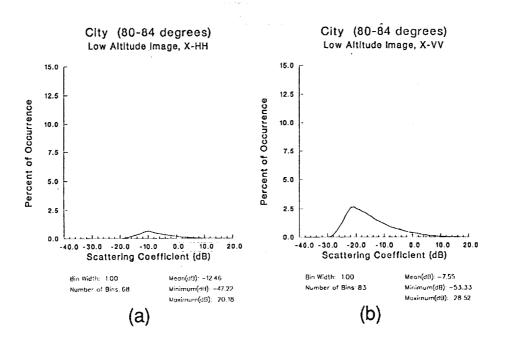


Figure 31. Clutter Distributions of City Areas, X-HH and X-VV

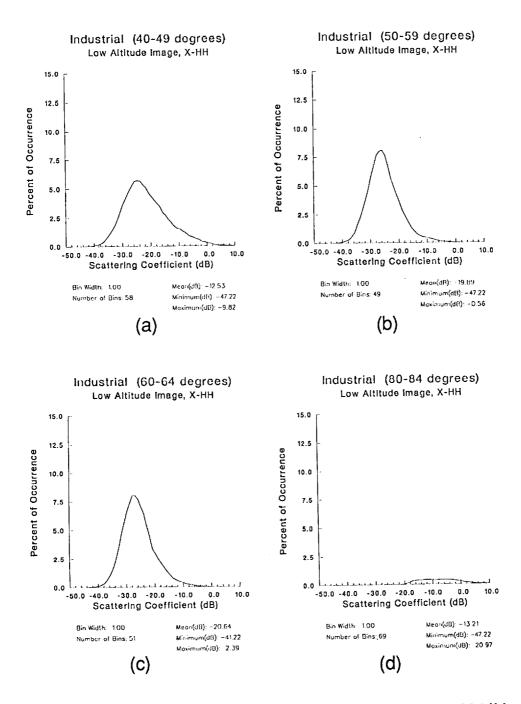


Figure 32. Clutter Distributions of Industrial Areas, X-HH

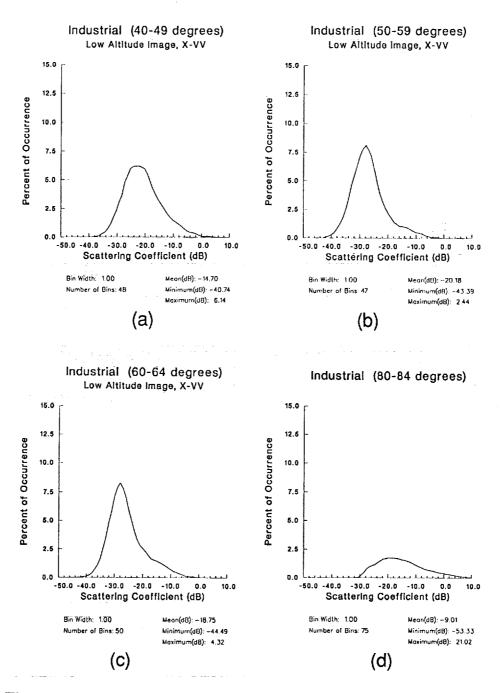


Figure 33. Clutter Distributions of Industrial Areas, X-VV

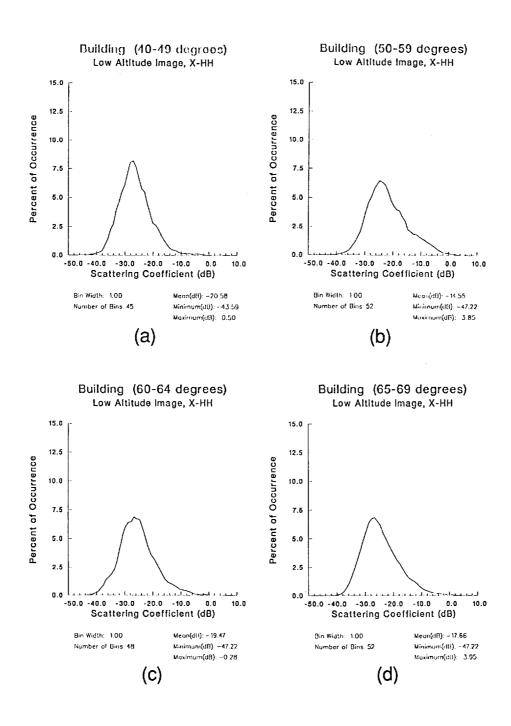


Figure 34. Clutter Distributions of Building Areas, X-HH

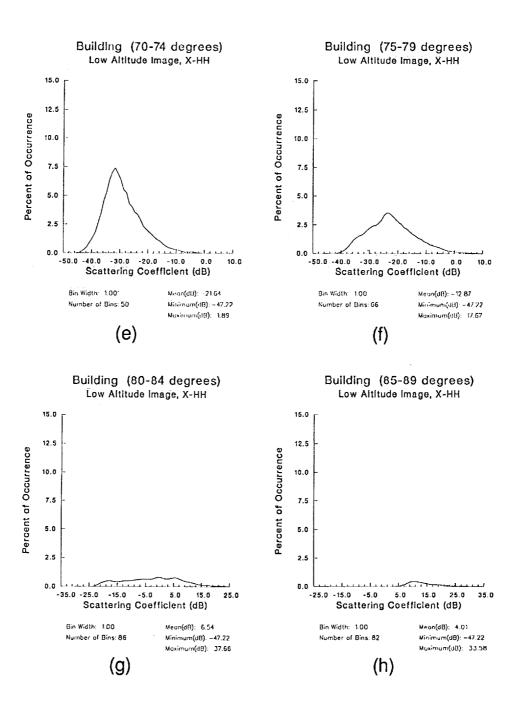


Figure 34. Clutter Distributions of Building Areas, X-HH (cont.)

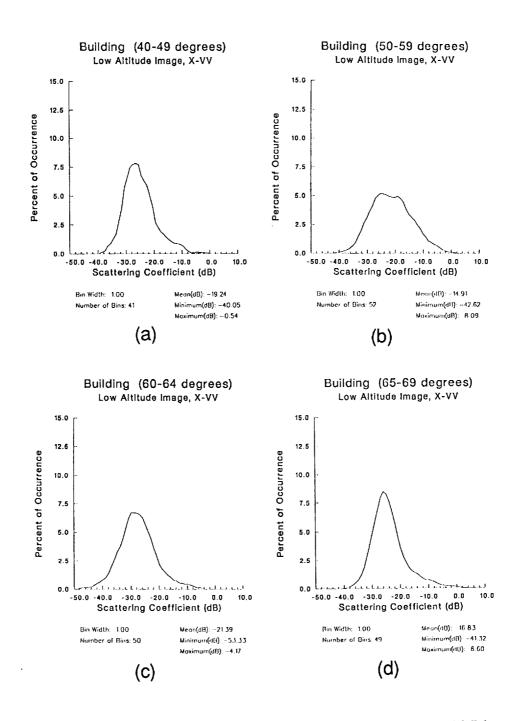


Figure 35. Clutter Distributions of Building Areas, X-VV

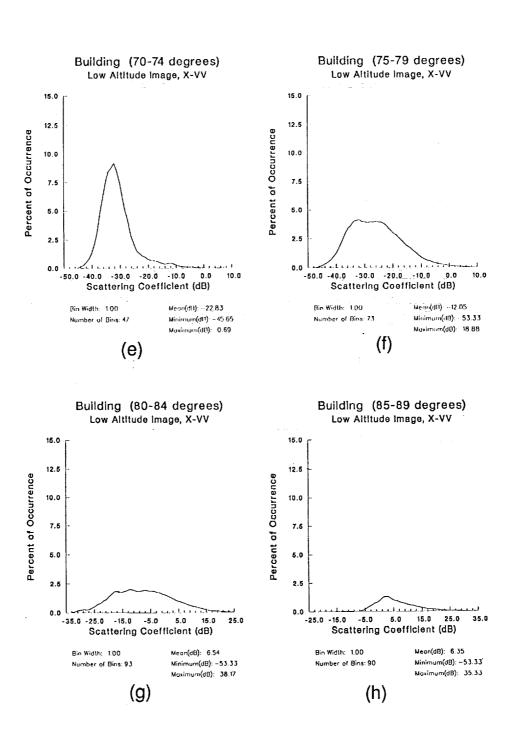


Figure 35. Clutter Distributions of Building Areas, X-VV (cont.)

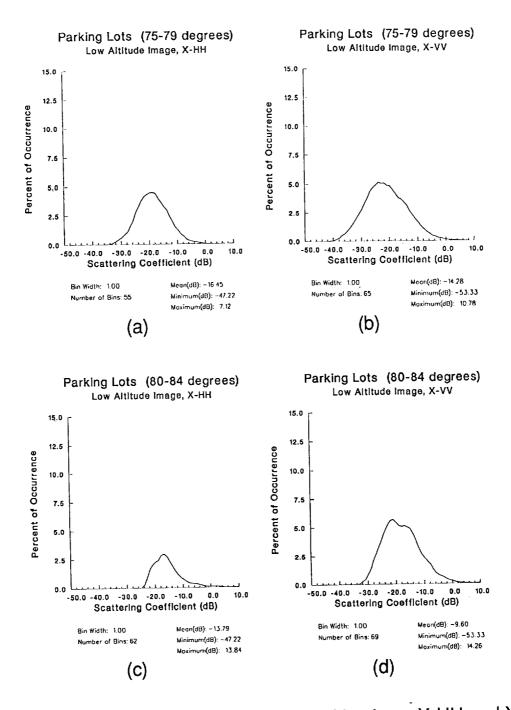


Figure 36. Clutter Distributions of Parking Lots, X-HH and X-VV

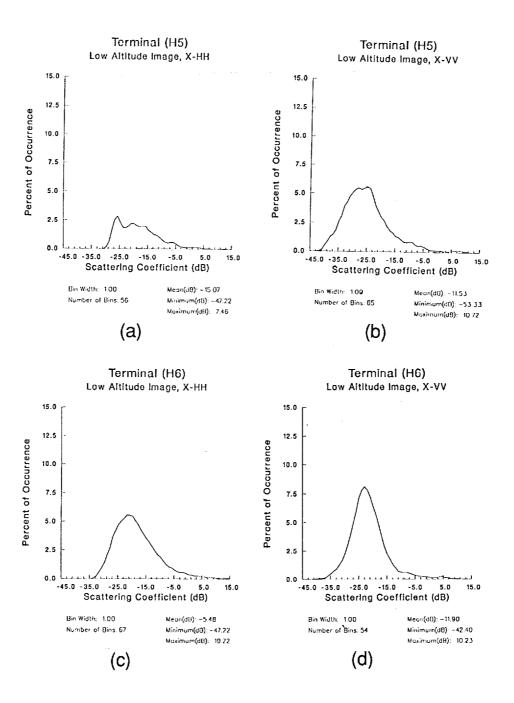


Figure 37. Clutter Distributions of Airport Terminals, X-HH and X-VV.
The Orientation of the Terminal to the Line of Flight is Parallel for (a) and (b) and Perpendicular for (c) and (d).

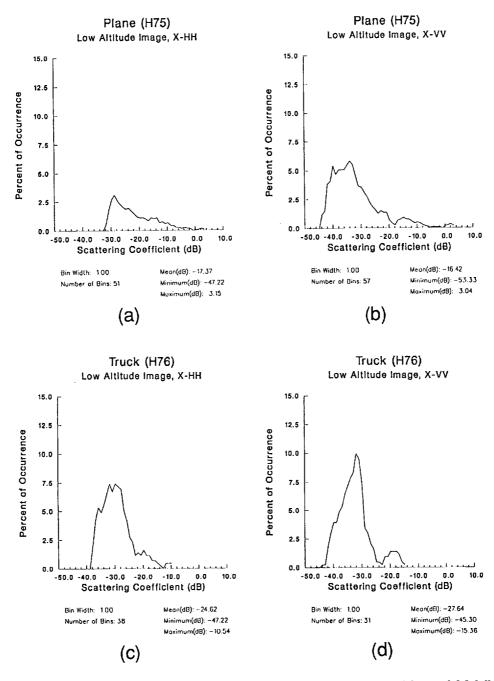


Figure 38. Clutter Distributions of Vehicles, X-HH and X-VV

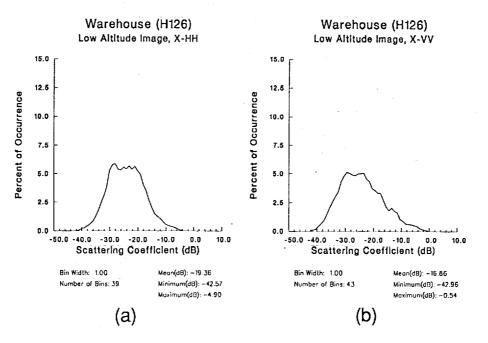
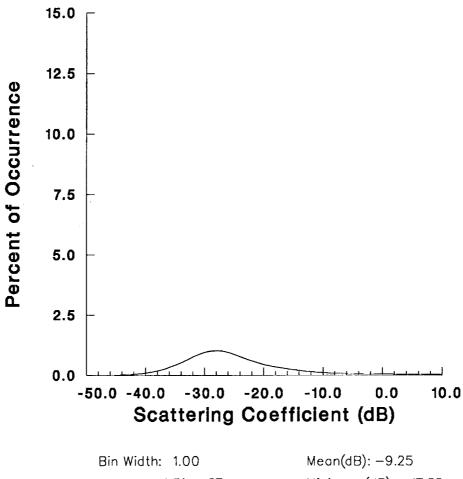


Figure 39. Clutter Distributions of Warehouses, X-HH and X-VV

Low Altitude Image, X-HH



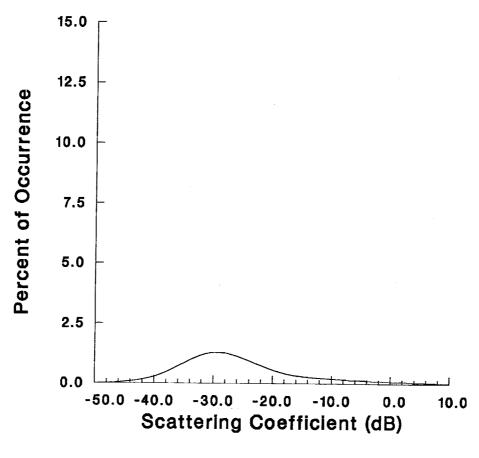
Number of Bins: 87

Minimum(dB): -47.22

Maximum(dB): 38.41

Clutter Distributions, Low Altitude Image, X-HH Figure 40.

Low Altitude Image, X-VV



Bin Width: 1.00

Mean(dB): -12.21

Number of Bins: 93

Minimum(dB): -53.33

Maximum(dB): 38.17

Figure 41. Clutter Distributions, Low Altitude Image, X-VV

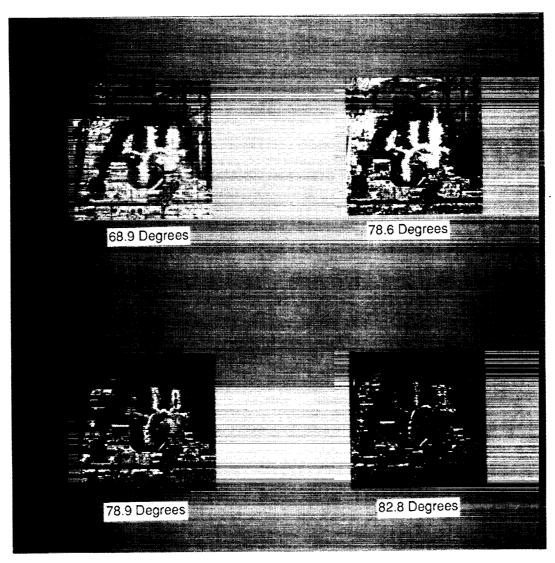


Figure 42. Denver Stapleton International Airport Terminal, Imaged at Successive Incidence Angles, X-HH

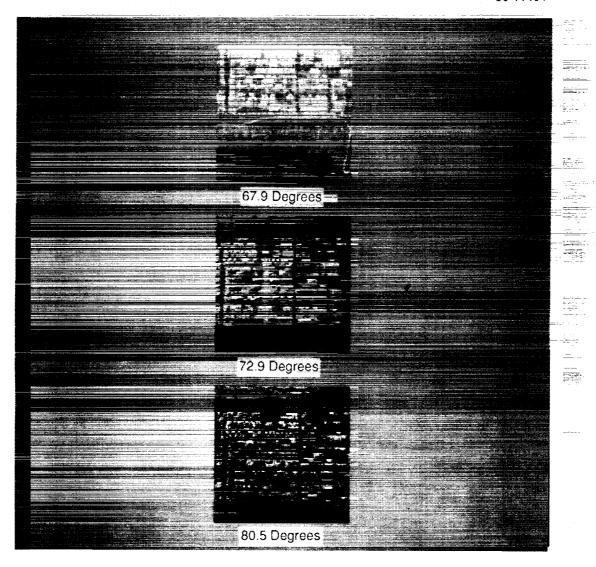


Figure 43. Warehouses at the Airport, Imaged at Successive Incidence Angles, X-HH

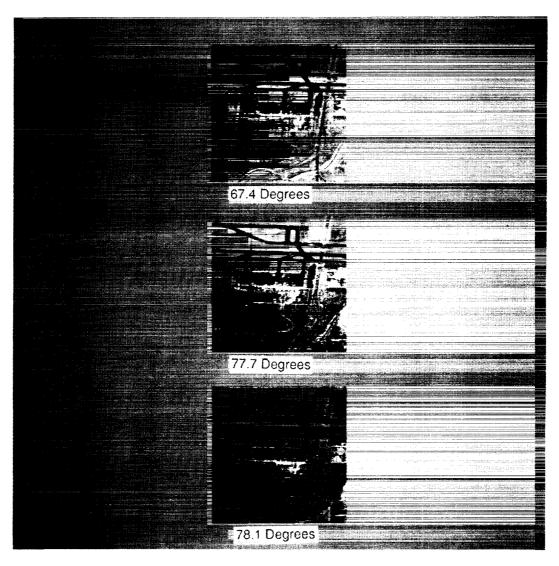


Figure 44. Planes at the Airport, Imaged at Successive Incidence Angles, X-HH

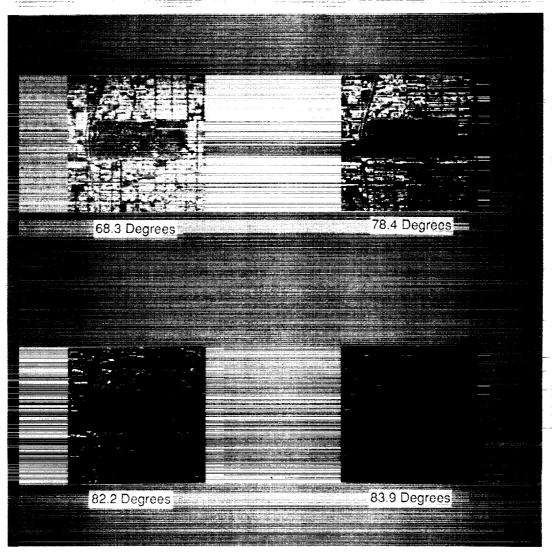


Figure 45. Park Hill Golf Course, Imaged at Successive Incidence Angles, X-HH

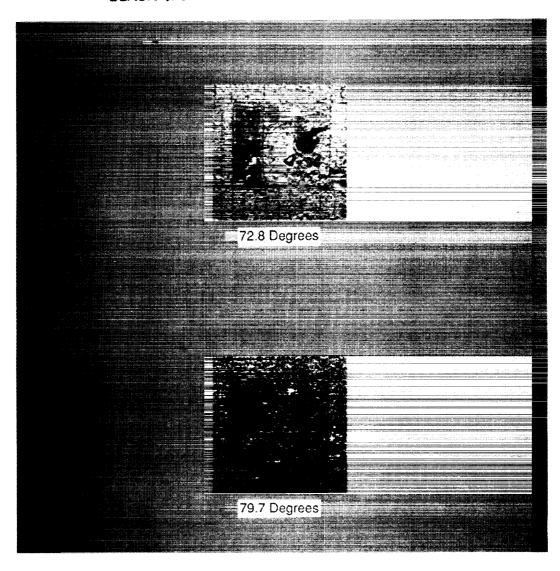


Figure 46. Denver City Park, Imaged at Two Incidence Angles, X-HH

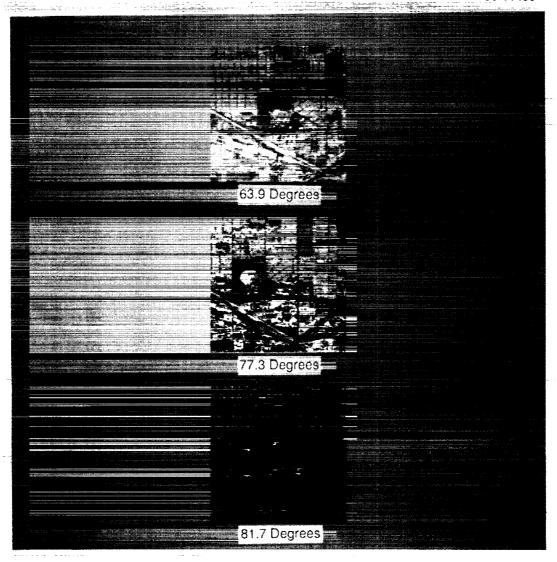


Figure 47. Mile High Kennel Club, Imaged at Successive Incidence Angles

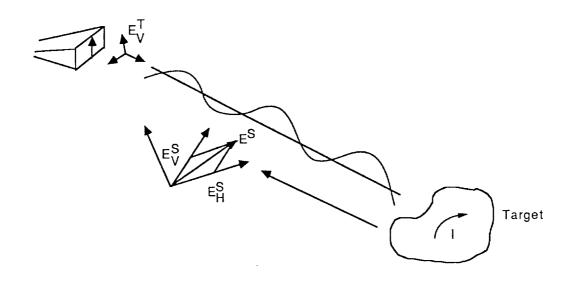
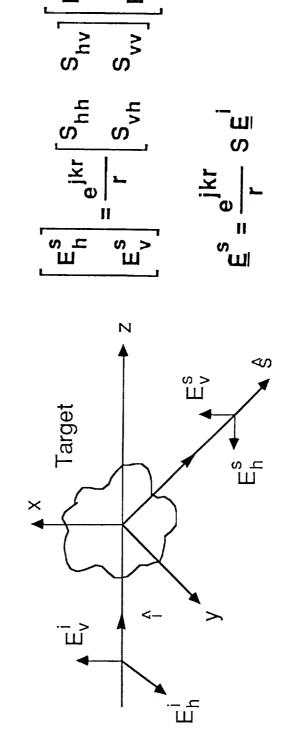


Figure 48. Diagram to Illustrate the Relationship Between the Transmitted and Scattered EM Wave Vector for a Conventional Radar

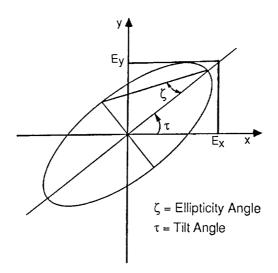
SCATTERING MATRIX

 Transmitted and Received Field Vectors are Uniquely Related to Target Through Scattering Matrix



Polarimetric Radar Provides the Scattering Matrix of a Target

Figure 49. The Scattered Field Vector Es and Incident Field Vector Ei are Uniquely Related by the Target Scattering Matrix S



$$\overline{E} = \sqrt{E_x^2 + E_y^2} (\cos \gamma \hat{x} + \sin \gamma e^{j\delta} \hat{y})$$
 where
$$\gamma = 1/2 \cos^{-1} (\cos 2 \zeta \cos 2 \tau)$$

$$\delta = \tan^{-1} (\tan 2 \varepsilon / \sin 2 \tau)$$

		Co-Polarized			Cross-Polarized			
Н	-1	τ = 0°, 180°	$\zeta = 0^{\circ}$		HV	$\tau = 90^{\circ}$	ζ = 0°	
V١	/	$\tau = 90^{\circ}$	$\zeta = 0^{\circ}$		VH	$\tau=0^{\circ},180^{\circ}$	$\zeta = 0^{\circ}$	
RI	7	$\tau = 0^{\circ}\text{-}180^{\circ}$	ζ = -45°		RL	$\tau = 0^{\circ}\text{-}180^{\circ}$	$\zeta = +45^{\circ}$	
LI	_	$\tau = 0^{\circ} - 180^{\circ}$	ζ = +45°		LR	$\tau = 0^{\circ} - 180^{\circ}$	$\zeta = -45^{\circ}$	

Figure 50. The Ellipticity Diagram for Elliptical Polarization May be Used to Define Polarization

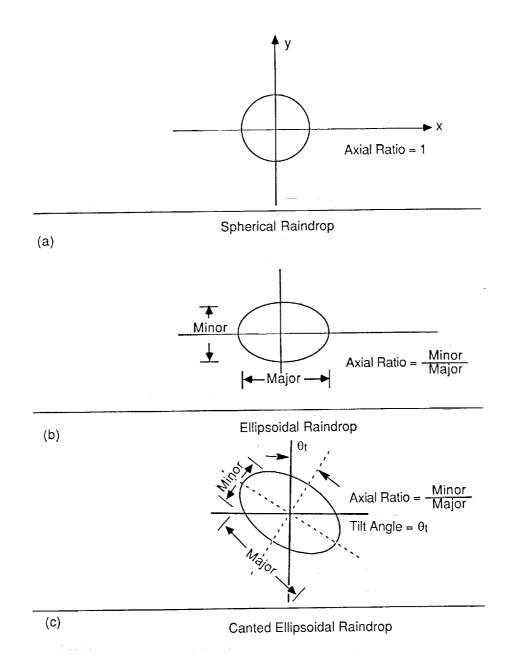


Figure 51. A Raindrop May be Spherical or Ellipsoidal, and May be Rotated to the Axis Normal to the Earth. A Raindrop is Characterized by its Effective Diameter, its Axial Ratio, and a Tilt Angle.

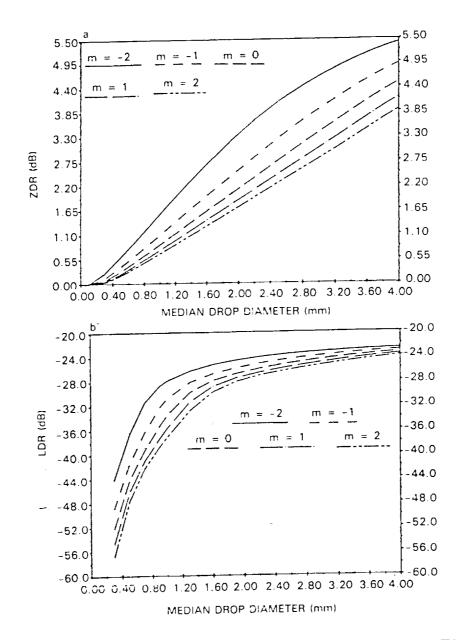
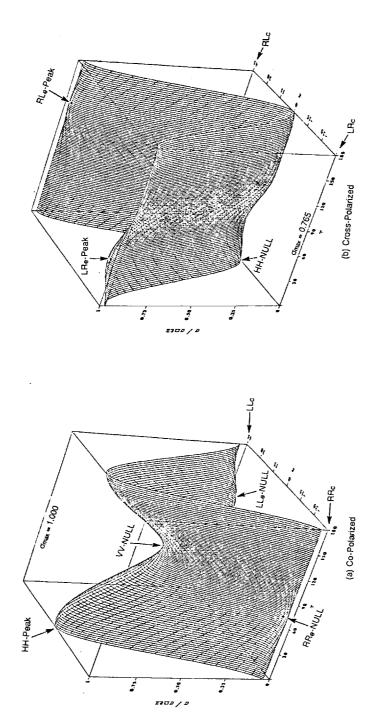
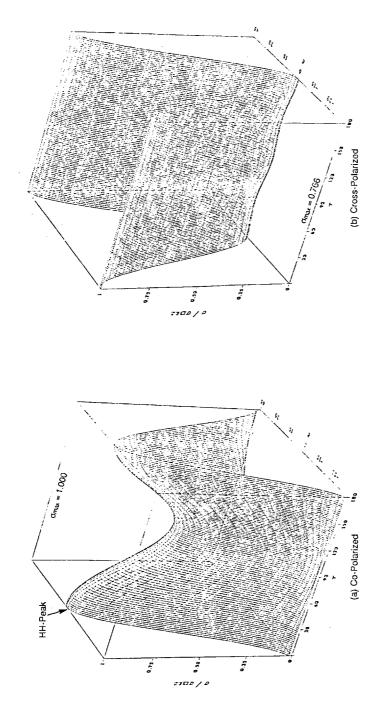


Figure 52. The Ratio Between HH and VV Returns (ZDR) is Shown (a) Versus Median Drop Diameter for 5 Values of the Parameter m in the Gamma Drop Distribution. A Corresponding Comparison Between Like-and-Cross-Polarized Returns (LDR) is Shown in (b). These Results are From Bringi et al. [8].



Signatures are Shown for the Case of a Wave Propagating Through a Rain Filled Medium Which Produces a Phase Shift of 20° (HH-VV) and 2.5 dB Greater Attenuation in VV-Polarization Than HH-Polarization. The Co-Polarized (a) and Cross-Polarized (b) Polarimetric Figure 53.



Response is 2.5 dB Weaker Than the HH Response. The Phase Shift Between HH and VV Polarization has Been Set to Zero for Illustration Purposes The Co-Polarized (a) and Cross-Polarized (b) Polarization Signatures are Shown for the Case of Wave Propagation Through a Rainfilled Medium Where VV-Polarization Figure 54.











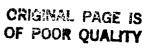




Figure 55. Denver Stapleton International Airport Polarimetric Set, VV

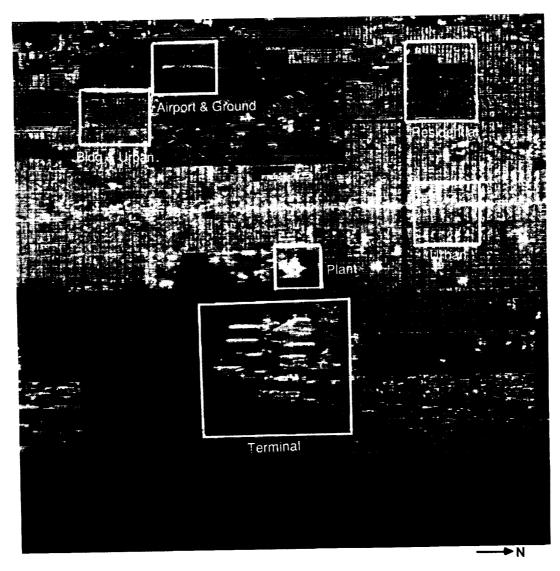


Figure 56. Denver Stapleton International Airport Polarimetric Set, HH.

The Location Map for Linear and Circular Polarization Image
Sets are Highlighted

Figure 57. Denver Stapleton International Airport Polarimetric Set, HV

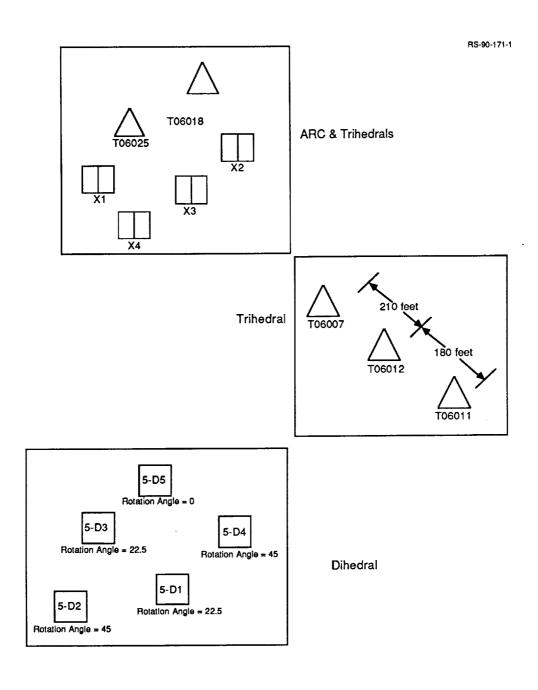


Figure 58. Calibration Target Array Site Plan

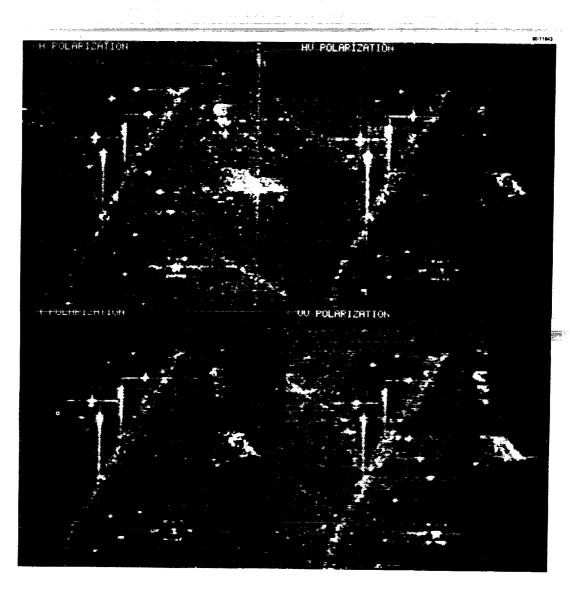


Figure 59. Linear Polarization Image Set of Calibration Target Array

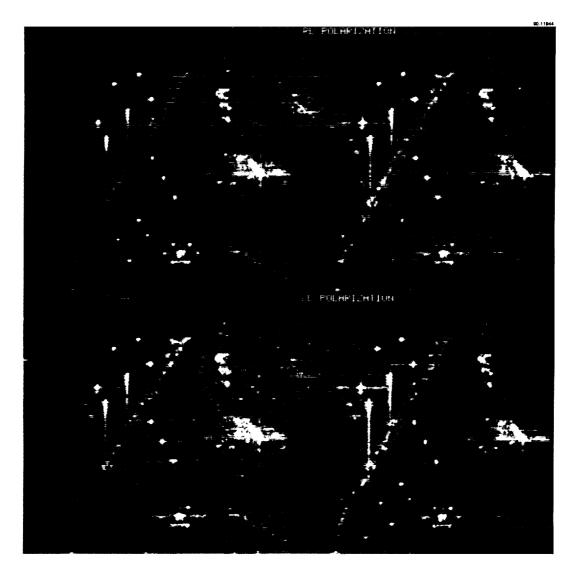


Figure 60. Circular Polarization Image Set of Calibration Targets Array

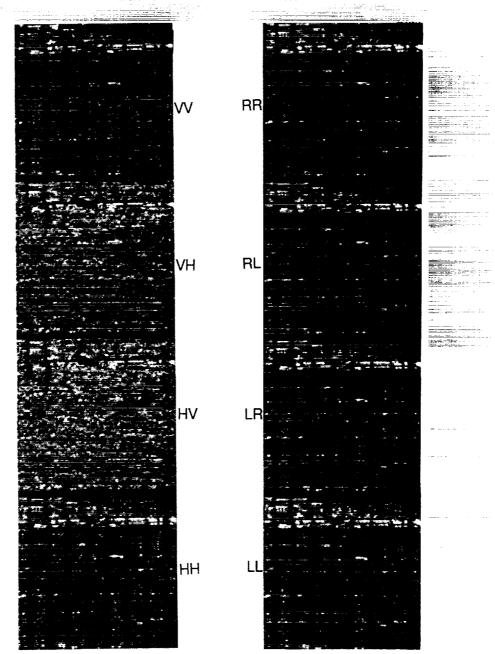


Figure 61. Linear and Circular Polarization Image Set for an Urban Area

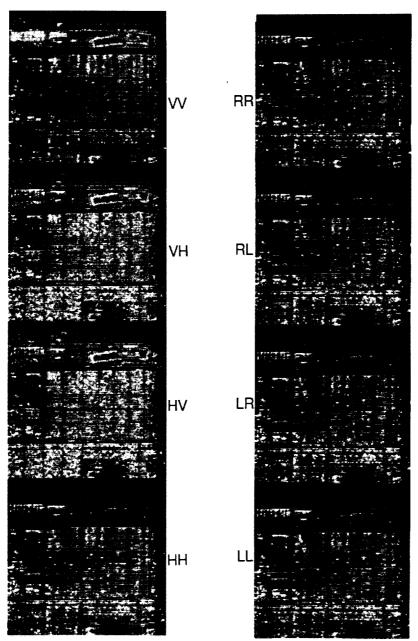


Figure 62. Linear and Circular Polarization Image Set for an Urban Area Next to Airforce Base Area

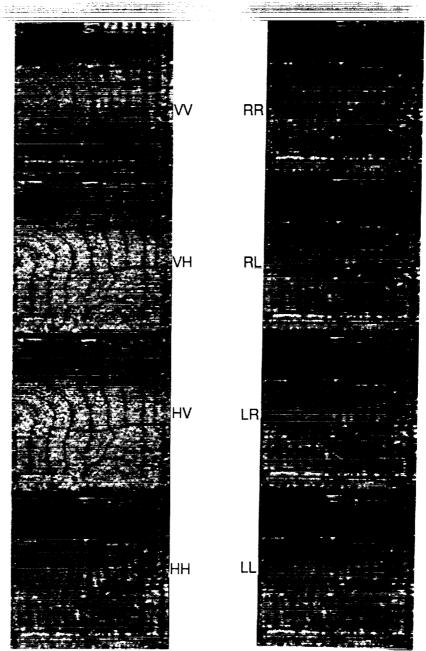


Figure 63. Linear and Circular Polarization Image Set for a Residential Area

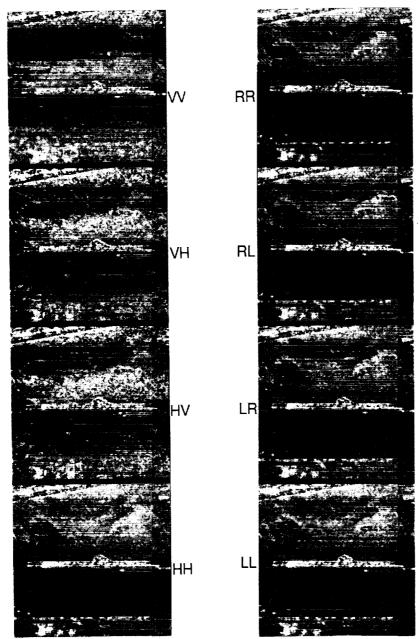


Figure 64. Linear and Circular Polarization Image Set for an Airforce Base Runway Area

Figure 65. Linear and Circular Polarization Image Set for a Plant Area

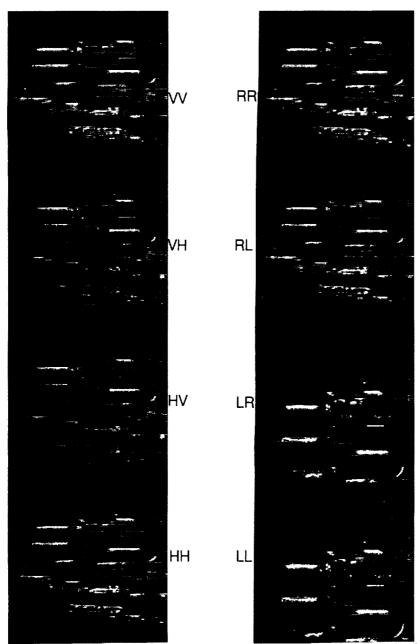


Figure 66. Linear and Circular Polarization Image Set for a Terminal Area

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APPENDIX A

Clutter Statistics for Rocky Mountain and Low Altitude Images

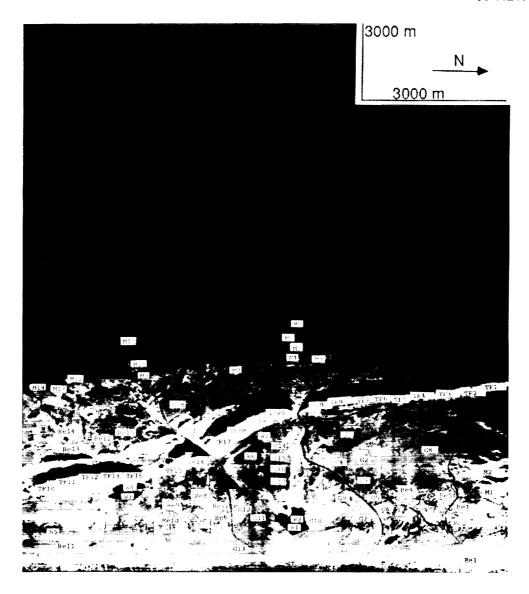
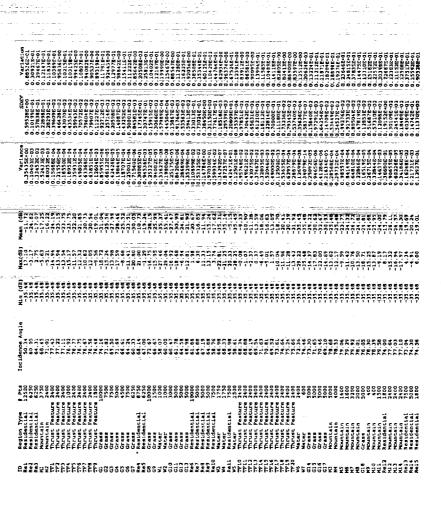


Figure A-1. Map of Clutter Locations, Rocky Mountains Image, X-HH

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Table A-1. Clutter Statistics for the Rocky Mountains Image



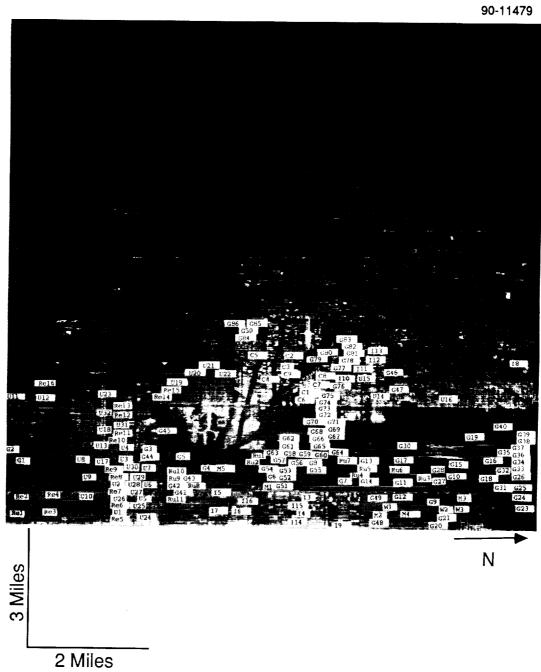


Figure A-2. Map of Clutter Locations, Low Altitude Image

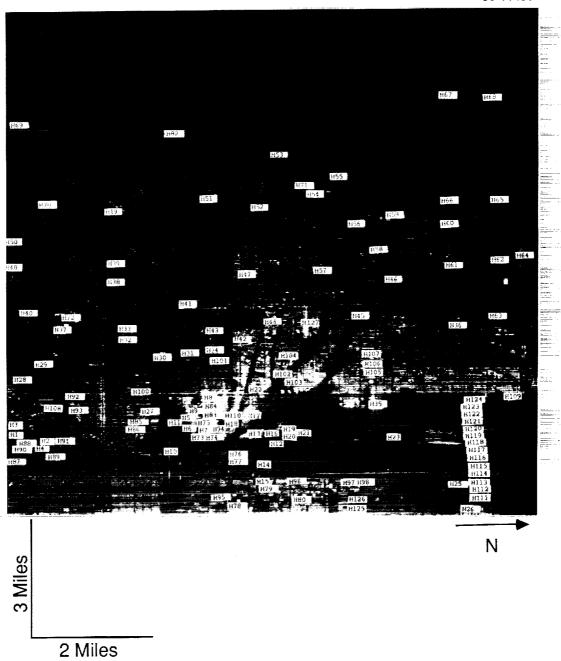


Figure A-3. Map of Clutter Locations, Low Altitude Image

Table A-2. Clutter Statistics for the Denver Low Altitude Image, X-HH

Variation 0.39318*00 0.39318*00 0.39318*00 0.334598*00 0.334598*00 0.65058*00	0.23256:01 0.310036:01 0.310036:01 0.310036:01 0.59586:01 0.59586:01 0.6756:09 0.669578:00 0.669578:00 0.669578:00 0.669578:00 0.669578:00 0.669578:00 0.669578:00 0.669578:00 0.669578:00 0.669578:00 0.669578:00 0.669578:00 0.669578:00 0.669578:00 0.669578:00 0.669578:00 0.669578:00 0.66958:00 0.6
SSEV-01.0.30398.E-01.0.30398.E-03.0.30398.E-	0.114468+00 0.2114468+00 0.2112128+02 0.212128+02 0.12128+02 0.13748+03 0.41468-04 0.113768-03 0.11376
Variance 0.46119E-0.2 0.46119E-0.2 0.46119E-0.2 0.128637E-0.3	0.431422-01.04.258E-01.04.258E-01.04.258E-01.04.258E-01.05.1528E-05.01.058E-07.0088E-07.01.058E-07.01.058E-07.01.058E-07.01.058E-07.01.058E-07.0088E-0
Mean 10 10 10 10 10 10 10 10 10 10 10 10 10	14.00 11.00
78. 20.014.	11.75.72 11.75.73 11.75.73 11.73 12.4.23 13.54.23 13.54.23 13.54.23 13.54.23 13.54.23 13.54.23 13.54.23 13.54.23 13.54.23 13.54.23 13.54.23 13.54.23 13.54.23 13.54.23 13.54.23 14.1
### ### ##############################	4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4
Pt. Pt. St. St. St. St. St. St. St. St. St. S	1200 1200 1200 1200 1200 1200 11100 11100 1000
Incidence Angle 62.96 62.96 62.96 63.59 63.59 77.43 77.43 77.59	51.05 77.77 77.77 77.77 77.77 78.50
Regional Type Residential Residential Residential Grass Building Grass Building Building Urban U	Partie Partie Baniding Plane Plane Plane Plane Parting Lot Parting Lot Parting Partie
282822 2822 2822 2822 2822 2822 2822 2	H H H H H H H H H H H H H H H H H H H

Table A-2. Cont.

0.93048870 0.281228-00 0.281228-00 0.136288-02 0.136288-02 0.999758-00 0.999758-00 0.999758-00 0.999758-00 0.999758-00 0.10510	0.24738E+01 :0.38610E+01 : 0.25090E+01
0.137208-03 0.74528E-03 0.74528E-03 0.116978E-02 0.116978E-02 0.117748E-02 0.117748E-02 0.117748E-03	0.17778E+01 0.40055E+00 0.18181E+01
0.188248-07 0.139188-06 0.159288-05 0.159288-05 0.159288-05 0.294758-05 0.294758-05 0.294758-05 0.294758-05 0.294758-05 0.294758-05 0.294758-05 0.29478-05 0.29478-05 0.29478-05 0.29478-05 0.29478-05 0.29478-05 0.29478-05 0.29478-05 0.29478-05 0.29478-05 0.29478-05 0.29478-05 0.29478-05 0.29478-05 0.29478-05 0.29478-05 0.29478-05 0.29478-06	
8 4 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5	1.43 1.43 1.40
1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1	9.75 3.62 10.72
	-53.33 -53.33 -53.33
20000000000000000000000000000000000000	150 159
8.04.00.00.00.00.00.00.00.00.00.00.00.00.	85.51 86.05 85.96
Water Water Walding Grass Building Grass Building Grass Gras	Building Building Building
######################################	222 222

Cont.	
A-2.	
Table	

0.211548-01 0.567038-02 0.567038-02 0.567038-02 0.289768-01 0.289768-01 0.289768-01 0.281058-01 0.39038-03 0.39038-01 0.39038-01 0.39038-01 0.39038-01 0.39038-01 0.39038-01 0.39038-01 0.39038-01 0.39038-01 0.464728-01 0.46	0.213188-01 0.21318-01 0.15600-0 0.15600-0 0.12366-01 0.37318-01 0.37318-01 0.37318-01 0.37318-01 0.37318-01 0.5318-01 0.65058-01 0.65058-01 0.65058-01 0.746608-01 0.746608-01 0.746608-01
0.10178E-01 0.10178E-01 0.10178E-01 0.10178E-01 0.10178E-01 0.10078E-01	0.45699E-03 0.45699E-03 0.2131E-02 0.74180E-03 0.40141E-03 0.40141E-03 0.43141E-03 0.53317E-01 0.53313E-01 0.53313E-01 0.53313E-01 0.53313E-01 0.1946E-00 0.4973E-01 0.1946E-00
4 5 3 1 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5	0.134582-06 0.134582-05 0.586582-05 0.586582-05 0.16138-06 0.16138-06 0.11737-02 0.11737
0.000 4.000	1375.70 137
4 1 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	24, 93 -23, 93 -113, 62 -113, 62 -20, 61 -20,
&&&&&&&&&&&&&&&&&&&&&&&&&&&&&&&&&&&&&&	24444444444444444444444444444444444444
1120 120 120 120 120 120 120 120 120 120	1,000 1,000
88888888888888888888888888888888888888	809.18 809.18 809.18 809.18 809.18 809.18 809.18 809.18 809.18 809.18 809.18 809.18 809.18 809.18 809.18 809.18
Building Bui	Grass Grass Grass Grass Grass Grass Grass Grass Grass Residential Residential Residential Residential Residential Residential Residential Residential Residential Residential Residential Residential Residential
36666666666666666666666666666666666666	6439 6442 6442 6443 6443 6443 6443 6443 6443

0.77566E+00	0.69839E+00	0.87711E+00	0.91504E+00	0.91727日+00	0.80566E+00	0.11998E+01	0.12200至+01	0.20584E+01	0.17456E+01	0.29030E+01	0.42001E+01	0.47496E+01	0.47291E+01	0.10174E+02	0.16194E+02	0.17929E+02	0.18313E-03	0.18313E-03	0.18313E-03	0.18313E-03	0.18313E-03	0 183125-03	0 183135-03	מי בייניייי	0.18313E-03	0.35212E+01	0.34836E+01	0.24403E+01	0.35196E+01	0.33938E+01	0.18464E+01	0.28922E+01	0.23476E+01	0.27651E+01	0.27980E+01	0.34119E+01	0.42086E+01	0.39534E+01	0.37044E+01	0.52177E+01	0.43254至+01	0.338225+01	0 523088+01	0.409445+01	0 361775+01	0 604848+01	0 940288+01	10.1101010
0.21946E-03	0.23733E-03	0.32068E-03	0.27279E-03	0.16447E-03	0.18780E-03	0.22333E-03	0.20711E-03	0.14011E-03	0.25839E-03	0.18935E-03	0,16238E-03	0.16011E-03	0.38632E-03	0.37583E-03	0.39755E-03	0.81356E-03	0.85106E-09	0.85106E-09	0.85106E-09	0.851068-09	0.85106E-09	0 851069-09	0 100TCB:0	0.031002-03	O. KOLOPKIOS	0.5/4/5E-01	0.37318E-01	0.17903E-01	0.26665E-01	0.12263E-01	0.90058E-02	0.48219E-01	0.23339E-01	0.39245E-01	0.32780E-01	0.17602E-01	0.37365E-01	0.91239E-01	0.35894E-01	0.23312E+00	0 12025E+00	0 40876E-01	0 111138+00	0 107548-01	0.10/345-01	0 126528+00	0 131375+00	22.21.01.0
0.48161E-07	0.56325E-07	0.10283E-06	0.74412E-07	0.27052E-07	0.35268E-07	0.49878E-07	0.42897E-07	0.19630E-07	0.66764E-07	0.35854E-07	0.26369E-07	0.25636E-07	0.14924E-06	0.14125E-06	0.15805E-06	0.66187E-06	0.72430E-18	0.72430E-18	0.72430E-18	0 724305-18	0 724305-18	01 206405 0	0 104200	0.724505-10	0.72430E-18	0.33033E-02	0.13927E-02	0.32050E-03	0.71103E-03	0.15038E-03	0.81104E-04	0.23250E-02	0.54473E-03	0.15402E-02	0.10745E-02	0.30983E-03	0.13961E-02	0.83245E-02	0.12884E-02	0 54346E-01	0.144618-01	0.16708E-02	0 123508-01	0.15645-03	0.113045-03	160085-01	0.100005-01	U.1/27/27
-35.48	-34.69	-34.37	-35.26	-37.46	-36.32	-37.30	-37.70	-41.67	-38,30	-41.86	-44.13	-44.72	-40.88	-44.32	-46.10	-43.43	-53.33	-53.33	-53.33	-53	55.65		55.55	23.33	-53,33	-17.99	-19.70	-21.35	-21.21	-24.42	-23.12	-17.78	-20.03	-18.48	-19.31	-22.87	-20.52	-16.37	-20.14	-13 50	115.56	0 0	11.71	100	12.02	154.10	110.73	170.11
-29.15	-28,89	-27.33	-27.69	-29.95	-29.26	-27.75	-28.21	-30.41	-28.58	-29.23	-29.05	-29.18	-25.52	-22.81	-20.99	-17.88	-53.33	-53.33	-53 33	153.23	200	ייייייייייייייייייייייייייייייייייייי	10.00	-53.33	-53.33	0.03	-0.88	-2.06	-3.48	-6.37	-12.81	-4.91	-8.19	-5.34	-7.22	-8.41	-4.86	-1.21	-5.83	50	100	1 1	00.0	101	-10.78	70.4	0.0	07.0
-53,33	-45.77	-53.3.	-53.33	-53.33	-53.33	-53,33	-53.33	-53,33	-53.33	-53.33	-53.33	-53	-53.33	-53.33	-53 33	-53.33	-54.33	-53 33	20.62	22.5	5.55	100.00	20.00	-54.33	-53.33	-44.25	-39.84	-39.63	-40.59	-45.28	-39.25	-34.07	-37.90	-36.10	-39.59	-53,33	-41.63	-53.33	-53,33	-53.33	22.5			10.55	103.33	140.04	55.53	-53.33
100	100	400	400	400	400	400	400	400	400	400	400	00.4	00.4	007	700	00.5	400	700	400	000		9	000	200	400	1800	1800	1800	1800	1800	81	81	81	81	81	188	81.	1 6	1 6	1 6	1 6	3 8	7 6	7 6	72 C	7800	1800	TROO
76.79	76.63	76.54	21.77	77.68	78.29	78.79	78.94	69.62	59.67	50.08	80.34	90.53	40.00	20.10	80.13	20.20	90.00	33.03	000	7	40.00	83.79	83.73	83.96	84.11	59.85	62.82	63.95	70,39	71.52	58.20	65.94	69.69	77.77	73.43	00.57	75.86	76.82	22.27	71.00	7.07	01.61	77.67	80.21	80.57	13.34	77.78	80.33
Grace	Grass	Grade	Grace	Grace	Grade Grade	Grace	Grass	0 5 6 1 5	G1 030	G1 833	01000	25070	25000	61.033	Or ass	GI GIS	OT TO	Grass	Grass Grass	22015	Grass	Grass	Grass	Grass	Grass	Urban	Urban	Urban	Urhan	Urhan	Structure	Structure	Stricture	Stricting	Structure	Stricture	Structure	Ctringting	Structure	Structure Characteristics	Structure	Structure	Structure	Structure	Structure	Urban	Urban	Urban
695	3 29	495	+ V	990	200	95	000	220	2,5	175	7 (2.5	* 10	7.5	26	36	96	50	000	105	282	683	489	685	989	U25	026	1127	1728	1129	H111	121	1113	H114	H115	4111	וווו	0110	0 1 1 1	1111	HIZO.	HIZI	H122	H123	H124	030	U31	632

Table A-3. Clutter Statistics for the Denver Low Altitude Image, X-VV

		*					
Variation 0.24604E+01 0.19604E+01 0.2666E+01 0.6433E+01	0.911138701 0.1278018401 0.913698401 0.533338401 0.278058401	0.278628+01 0.213888+01 0.208178+01 0.123088+01 0.522168+01	0.26348E+01 0.18602E+01 0.17346E+01 0.17346E+01 0.96168E+01 0.68842E+01	0.25093E+01 0.82359E+00 0.11553E+02 0.21965E+01 0.437867E+01 0.29068E+01	0.23678-01 0.528988-01 0.236708-01 0.236708-01 0.274998-01 0.274998-01 0.239618-01 0.239618-01	0.42996E-01 0.34193E-01 0.34512E-01 0.3455E-01 0.04256E-01 0.07363E-01 0.10171E-01 0.10171E-01 0.10171E-01	0.184628+01 0.1023948+01 0.1023948+01 0.101585+01 0.252578+01 0.193718+01 0.484738+01 0.352808+01
SDEY 0.26464E-01 0.22112E-01 0.39659E-01 0.10925E+00	0.500658-03 0.500658-03 0.545348-01 0.604298-01 0.26896E-01	0.39971E-01 0.16414E-01 0.17290E-01 0.11778E+00 0.64914E-01	27050E 16019E 30182E 38712E 54342E 21218E	0.12195E-02 0.54215E-03 0.84057E+00 0.30835E-01 0.52294E-03 0.15267E-01	0.97826E-01 0.91512E-02 0.52493E-04 0.12088E-03 0.29543E-01 0.59354E-02 0.59354E-02	0.350198700 0.350198700 0.18462E-01 0.11157E-01 0.70221E-01 0.69938E-03 0.334628-04 0.13552E-04	0.51395E-01 0.14997E-02 0.49519E-03 0.49519E-03 0.7935IE-01 0.7975EE-01 0.7975EE-01 0.42359E-01
Variance 0.70035E-03 0.48895E-03 0.15729E-02 0.11935E-01 0.10639E-06	0.25067E-01 0.25065E-06 0.36516E-02 0.72341E-03	0.15977E-02 0.26943E-03 0.2995E-03 0.13871E-01 0.42138E-02	0.73172E-03 0.25660E-03 0.91094E-03 0.14986E-06 0.29531E-06 0.45020E-01	0.14871E-05 0.29393E-06 0.70652E+00 0.95279E-03 0.23147E-05 0.23307E-03	0.95700E-05 0.85744E-04 0.27555E-09 0.14613E-07 0.15281E-03 0.15229E-04 0.12675E-02	0.12263E+00 0.34083E+03 0.50870E+03 0.1249EE-01 0.49309E-02 0.48913E-08 0.11197E-08 0.18376E-03	0.26415E-02 0.22492E-03 0.22492E-03 0.2492E-06 0.51623E-01 0.62966E-02 0.63613E-03 0.63613E-03 0.17943E-03
Mean (dB) -19.68 -19.48 -18.28 -17.70 -33.78	10,04 134.04 120.24 122.97	-18.43 -21.15 -20.81 -20.19 -19.05	4444444 844444444444444444444444444444	-33,13 -31,82 -11,38 -35,57 -23,88	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	11222685 1222685 1222685 1222685 1444685	113.35 28.34 28.34 13.34 12.5.34 11.7.88 11.88
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0.28123E+01	0.76328E+01	0.69282E+01	0.434/36+01	0 548698+02	0.24987E+01	0.33703E+01	0.15687E+02	0.74795E+01	0.50433E+01	0.250025101	0.50250E+01	0.42351E+01	0.39409E+01	0.45424E+01	0.21303E+01	0.382882+01	0.890148+01	0.629138+01	0.421825+01	0.35275E+01	0.45097E+01	0.42120E+01	0.37837E+01	0.5365BE+01	00-3000000	0.00000E+00	0.103362401	0.00000E+00	0.74930E+01	0.65198E+01	0.85049E+01	0.80672E+01	0.11442E+02	0.534466+01	0.42168E+01	0.40942E+01	0.83130E+01	0.118625+02	0.22260E+02	0.13571E+02	0.61578E+01	0.335565701	0.12169E+02	0.15638E+02	0.79678E+01	0.77117E+00	0.93513E+00	0./0004E+00	0.13022E+01	0.793298+00	0.77506E+00	0.96727E+00	0.96994E+00	0.72421E+00
0.11858E+00	0.14651E+00	0.5/322E+01	0.4040/5400	0.46872E+00	0.82039E-01	0.31110E-01	0.26043E+00	0.40244E-01	0.389168-01	0 80694E-01	0.93381E-01	0.39064E+00	0.17366E+00	0.15425E+00	0.44238E-01	0.75392E-01	0.30/325+00	0 480595+00	0.25727E+00	0.13155E+00	0.87787E+00	0.23487E+00	0.94543E+00	0.13875E+01	0.00000E+00	0.00000E+00	0.834795-02	0.0000E+00	0.258258+00	0.17996E+00	0.94505E-01	0.47319E+00	0.425525+00	0.29745E+00	0.36375E-01	0.42084E-01	0.13778E-01	0.139638-01	0.68480E-01	0.11308E-01	0.64585E-02	0.63535E+00	0.43984E+00	0.20278E+01	0.19277E+00	0.10232E-02	0.78689E-03	0.33/928-03	0.00/435-03	0.59994E-03	0.55122E-03	0.40909E-03	0.53048E-03	0.39451E-03 0.29572E-03
0.14061E-01	0.214658-01	0.32859E+02	0.079716+01	0.21970E+00	0.67303E-02	0.96784E-03	0.67824E-01	0.161965-02	0 586018-04	0.651158-02	0.87200E-02	0.15260E+00	0.30159E-01	0.23794E-01	0.19570E-02	0.56840E-02	0.43222400	0 230967400	0.66189E-01	0.17306E-01	0.77066E+00	0.55162E-01	0.89384E+00	0.19250E+01	/T-956936-1-	0.160015-04	0.69687E-04	-0.52693E-17	0.66695E-01	0.32387E-01	0.89311E-02	0.22391E+00	0.179402+00	0.88476E-01	0.13231E-02	0.17710E-02	0.18983E-03	0.19497E-03	0.46895E-02	0.12786E-03	0.41/12E-04	0.40367E+00	0.19346E+00	0.41121E+01	0.37160E-01	0.10469E-05	0.61920E-06	0.0/3696-00	0.506385-06	0.35992E-06	0.30384E-06	0.16735E-06	0.281415-05	0.874495-07
-13.75	71.71-	10.02	106	-10.68	-14.84	-20.35	-17.80	60.77	-25.08	-15.44	-17.31	-10.35	-13.56	-14.69	-16.83	-17.06	26.61	-10.23	-12.15	-14.28	-7.11	-12.54	-6.02	70.01	77.75	-24.21	-21.53	-47.22	-14.63	-15.59	-19.54	-12.32	10.00	-12,55	-20.64	-19.88	18.72	-29.29	-25.12	-30.79	67.67	-13.50	-14.42	-8.87	-16.16	-28.77	130.75	20.73	130.25	-31.21	-31.48	133.74	79.75	-36.04
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-47.22	77.75	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	247.22	-47.22	-47.22	-47.22	-47.22	-39.19	-47.22	-47.22	27.74-	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	77.75	27.74	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	77.75	-47.22	-47.22	-47.22	-47.22	-39.25	144.49	-47.72	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22
1200	0000	4000	4000	225	400	405	2000		1200	525	525	200	595	864	416	416		006	675	450	450	009	009	000	000	2000	2000	3000	3500	7500	7500	7500	2500	7500	7500	7500	0000	2000	2000	2000	2000	7500	7500	7500	2000	004	904	2	400	400	225	100	100	100
28.30	92.33	78.01	79.62	78.56	78.23	74.05	76.75	74.50 54.50	76.72	79.74	78.89	77.78	65.70	65.82	66.27	64.70	200	82.56	81.92	81.56	82.72	82.03	82.43	82.74	0.4.4	46.10	65.17	83.89	78.37	81.25	82.17	82.02	83.40	44.57	61.82	29.00	81.81	82.38	82.61	82.33	49.73	61.32	81.91	82.40	82.39	69.69	4.5	76.47	73.77	74.62	75.36	75.94	75.80 AC 27	76.42
Bullding	C.L.C.	Building	Building	Building	Building	Building	Building	Butlding	Building	Part Jahra	Building	Building	Building	Building	Building	Building	Bullaing	Sep 10	Grass	Grass	Grass	Terminal	Industrial	Trhan	Urban	Urban	Urban	The	City	city	City	City	Grass	Grass	Grace	Grass	Grass	Grass	Grass	Grass	Grass													
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0.10086E+01	0.96767E+00	0.13289E+01	0.198658+01	0.27306E+01	0.20242E+01	0.54327E+01	0.46007E+01	O. 70530E+01	0.72042E+01	O. 00000E+00	0.00000E+00	0.12177E+02	O. 00000E+00	0.18349E+02	0.00000E+00	0.00000E+00	0.00000E+00	0-10000000+00	0.00000E+00	0.000000000	0.0000000	0.00000E+00	0.00000E+00	0.00000E+00	0.15145E-01	0.19806E+01	0.14169E+01	0.18563E+01	0.21124E+01	0.15196E+01	0.31276E+01	0.23332E+01	0.294146+01	0.25422E+01	מישטרביני ט	101101101	0.194140401	0.19955E+01	G. 41088E+01	0.359838+01	0.47239E+01	0.63244E+01	0.62224E+01	O. 22756E+01	0.24557E+01	0.10499E+02	
0.56195E-03	0.56492E-03	0.38867E-03	0.58334E-03	0.45958E-03	0.95942E-03	0.35828E-03	0.375552-03	0.45479E-03	0.35041E-03	0.00000E+00	0.00000E+00	0.59215E-03	0-00000E+00	0,42792E-02	0.00000E+00	0-00000E+00	0.00000E+00	0-00000E+00	0-00000E+00	0 00000E+00	0: 00000E+00	0.00000E+00	0,00000E+00	0.00000E+00	0-1632BE-01	0.20107E-01	0-10932E-01	0.16954E-01	0.15353E-01	0.55226E-02	0.40128E-01	0.28981E-01	0./1828E-01	0.32298E-01	TO 237770	TO 120 / 100	0.14201E-01	0.4480ZE-01	0.69501E-01	0.37939E-01	0.19748E-01	0.37923E-01	O. 11212E-01	0.17405E-01	0.31437E-01	0.127045+00	
0.31579E-06	0.31913E-06	0.15107E-06	0.34029E-06	0.21121E-06	0.92049E-06	0.12837E-06	0.14104E-06	0.20683E-06	0.12279E-06	-0.52693E-17	-0.52693E-17	0.35064E-06	-0,52693E-17	0.18311E-04	-0.52693E-17	-0.52693E-17	-0.52693E-17	-0.52693E-17	-0.52693E-17	-0.52693E-17	-0.52693E-17	-0.52693E-17	-0.52693E-17	-0.52693E-17	0.26661E-03	0.40430E-03	0.11951E-03	0.28742E-03	0.23572E-03	0.30499E-04	0.16102E-02	0.83987E-03	0.51589E-02	0.1043ZE-02	0.023045-00	0.1120/12-02	0.203945-03	0.6151.25-03	0.483048-02	0.14393E-02	0.38998E-03	0.14381E-02	0.12571E-03	0.30294E-03	0.98831E-03	0.161408-01	
-32.54	-32.34	-35,34	-35.32	-37.74	-33.24	-41.81	-40.88	-41.91	-43.13	-47.22	-47.22	-43.13	-47.22	-36.32	-47.23	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-19.67	-19.93	-21.13	-20.39	-21.39	-24.40	-18.92	-19.06	-16.12	-18.96	07.071	10.01	67.17-	19.06	-17.72	-19.77	-23.79	-22.22	-27.44	-21.16	-18,93	-19.17	
-25.93	-25.99	-24.93	-23.77	-25.29	-21.86	-24.37	-25.55	-22.81	-22.78	-47.22	-47.22	-19.25	-47.22	-10.67	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.32	-7.48	46.4~	-7.91	-6.15	-4.84	-15.42	-5.32	-7.64		-7.00		0.00	85.01-	-7.16	-2.66	-6.54	-8.71	-4.76	-11.27	-4.92	-4.27	5.95	
-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-40.27	-39,82	-40.18	-47.22	-43.44	-39.12	-36.66	-38.52	-32.88	-40.10	77.14-	77./-	77.75	-47.22	-47.22	-47.22	-47.22	-47.22	-47.22	-41.81	-47.22	-47.22	
100	100	400	400	400	400	400	400	400	004	400	400	400	400	400	400	400	400	400	400	400	400	400	200	400	1800	1800	1800	1800	1800	81	81	81	81	81	, S	5	T 10	18	81	81	81	81	81	1800	1800	1800	
76.79	76.63	76.54	77.15	77.68	78.29	78.79	78.94	79.69	79.65	80.09	80,34	80.57	81.06	82.15	82.72	83.00	83.04	83,38	83.39	83.54	83.79	83.73	83.96	84.11	59.85	62.82	63.95	70.39	71.52	58.20	65.94	69.69	71.79	73.43	75.00	75.86	76.82	77.59	78.15	79.15	79.72	80.21	80.57	73.32	77.78	80.39	
Grass	STASS	Grass	Grass	Grass	Grass	Grass	Grass	Grass	Grass	Grass	Grass	Grass	Grass	Grass	Grass	Grass	Grass	Grass	Urban	Urban	Urban	Urban	Urban	Structure	Structure	Structure	Structure	Structure	Structure	Structure	Structure	Urban	Urban	Urban													
62		3 2	. 29	99	67	99	69	20	7.	72	73	74	75	76	77	8	20	80	81	82		84	150	98	22	26	22	28	52	111	1112	1113	1114	1115	116	117	1118	1119	1120	1121	1122	1123	1124	130	15	32	

$\label{eq:appendix} \mbox{\sc APPENDIX B}$ Processing and Calibration of SAR Data

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APPENDIX B

Processing and calibration proceeded in much the same manner as the other Denver images. The phase histories of the images were focused in azimuth and range. This was achieved by convolving the data with a match filter of the transmitted chirp in azimuth and range. The images were processed to remove the effects of system noise and were then radiometrically corrected to compensate for the effects of range fall-off, the antenna gain pattern, and resolution cell power. The radiometrically corrected images were then converted to normalized radar scattering coefficients (NRSC) by normalizing the magnitude of the radar cross section by the resolution area.

The absolute calibration of the Denver images was performed based on data obtained from a calibration array positioned at Denver Stapleton International Airport and Lowry AFB. This array is described in Volume III report Appendix A. For a radar operating in its linear region, a linear relationship will exist between the measured intensity of a point target in an image and the expected value of the backscattering cross section of the target. The slope of the function is unity and the yintercept of the function is a measure of the system gain function. Groups of three 60 cm trihedral corner reflectors were placed in grassy fields around the Denver Airport. The returns from these reflectors were used to calibrate the images. In images with no corner reflectors, such as the Rocky Mountains image, measured intensities from corner reflectors in other Denver images were used to determine the absolute system gain function. This gain function was then adjusted for differences in attenuation and transmitted power between the images under analysis and the calibrating image, and the adjusted gain function was then applied to the image under analysis.

APPENDIX C

Discussion of Statistical Analysis Performed

APPENDIX C

Two analyses were performed in this additional work. One analysis employed clutter analysis techniques similar to those performed on previous data. The second analysis employed complex polarimetric analysis of the full-polarization data set. Statistical clutter analysis was performed on the pair of X-HH and X-VV low altitude images and on the Rocky Mountain image. The purpose of the low altitude analysis was twofold. First, the low altitude images provided clutter information at incidence angles larger than any that have been analyzed before. These images would provide needed information about the returns from depression angle which are almost identical to that of the glide slope of incoming aircraft. Second, analysis of this data would provide more information to the database of clutter which has been developed over the course of the NASA LaRC windshear analysis. The Rocky Mountain image was analyzed in order to focus upon an aspect of clutter indigenous to the Denver area. First and foremost, an attempt to analyze and quantify the effect of range ambiguity caused by the mountains was necessary. Secondly, an analysis of the normalized scattering coefficients of the mountains and their relation to geological slope and position was performed to characterize the effects of such topography and to determine when mountain topography represents a potential hazard to windshear detection.

The analyses of these images were performed on a 4096 element by 4096 record slant range image of normalized scattering coefficients with the finest resolution possible. The images have one independent sample per resolution cell. Statistical analyses were performed to characterize the returns from different clutter types in the images. A thresholding analysis, which separated the normalized scattering coefficient into bins of 5 dB, was also performed in order to locate and quantify sources which produced similar absolute backscatter levels.

Regions of critical clutter types were located and extracted and the mean, standard deviation, and coefficient of variation for each of these subregions were calculated using techniques described in Appendix C of Volume II. During Phase I, probability density function analysis indicated that most clutter types were well described using a gamma density function. These regions of similar type were then employed in general clutter characterization and in the examination of the change in response with incidence angle. Areas of similar clutter types and incidence angles were merged. Histograms, means, standard deviations, and coefficients of variation were calculated. The general shape of the histograms was also examined. It should be noted that in order to compare the expected scattering cross sections from point and man-made targets to normalized scattering cross sections the area extent of the target must be taken into account. Incidence angle effects in the data were examined by plotting the mean return of each sub-region as a function of the mean incidence angle. Clutter types common with the other Denver images were also compared to previous analysis results.

For the polarimetric analysis, previously analyzed amplitude data was reprocessed complexly and phase calibrated using a polarimetric array set up at the Denver Stapleton International Airport. The phase characteristics of different clutter types were then calculated and compared. In addition, spans, depolarization ratios, correlation coefficient magnitudes and phase differences were calculated.

APPENDIX D

Polarization Properties of Hydrospheres and Ground Clutter

APPENDIX D POLARIMETRIC DISCRIMINANTS

Given a scattering matrix of the form

$$[S] = \begin{bmatrix} S_{HH} & S_{HV} \\ S_{VH} & S_{VV} \end{bmatrix}$$

the covariance matrix may be defined as

$$[C] = \begin{bmatrix} \langle S_{HH} S_{HH}^* \rangle & \langle S_{HH} S_{VH}^* \rangle & \langle S_{HH} S_{VV}^* \rangle \\ \langle S_{VH} S_{HH}^* \rangle & \langle S_{VH} S_{VH}^* \rangle & \langle S_{VH} S_{VV}^* \rangle \\ \langle S_{VV} S_{HH}^* \rangle & \langle S_{VV} S_{VH}^* \rangle & \langle S_{VV} S_{VV}^* \rangle \end{bmatrix}$$
(2)

if reciprocity is assumed. The elements along the diagonal of the covariance matrix are related to the real scattering coefficients

$$\sigma^{\circ}_{VV} = 4\pi \langle S_{VV} S_{VV}^{\dagger} \rangle$$
, and $\sigma^{\circ}_{HH} = 4\pi \langle S_{HH} S_{HH}^{\dagger} \rangle$, and $\sigma^{\circ}_{VH} = 4\pi \langle S_{VH} S_{VH}^{\dagger} \rangle$.

The polarimetric discriminants utilized in this study are defined in terms of the elements of the covariance matrix and will be presented here.

Phase Difference

One of the new pieces of new information provided by a polarimetric radar and its coherent properties is the difference between the phase at HH and VV polarizations. This phase difference may be retrieved from the covariance matrix by performing the calculation where

$$\theta_{\text{VVHH}} = \tan^{-1} \left| \frac{(\text{Im} \langle S_{\text{HH}} S_{\text{VV}}^* \rangle)}{(\text{Re} \langle S_{\text{HH}} S_{\text{VV}}^* \rangle)} \right|$$
 (3)

A simple man-made target made of a conducting material will produce a mean phase difference of 0 and a probability distribution that is very narrow, if not a delta function. Complex shapes and multiple reflections have been observed which produce non-zero phase difference values. The phase differences for plane dielectric surface is shown to increase with increasing angle.

Total Power or Span

Span is the terminology used to represent the total power of the scattered field. It may be calculated accordingly

$$SPAN = \langle S_{HH}S_{HH}^* \rangle + \langle S_{VH}S_{VH}^* \rangle + \langle S_{HV}S_{HV}^* \rangle + \langle S_{VV}S_{VV}^* \rangle$$
(4)

Depolarization Ratio

The depolarization ratio has been defined here as the ratio of the power associated with the copolarization elements of the scattering matrix and the cross polarization elements. It is defined as

$$Pd = \frac{\langle S_{HH} S_{HH}^* \rangle + \langle S_{VV} S_{VV}^* \rangle}{\langle S_{HV} S_{HV}^* \rangle + \langle S_{VH} S_{VH}^* \rangle}$$
(5)

One of the advantages of this definition for depolarization ratio is that it allows for an intuitive understanding and provides a reduction in the variance since it is composed of four elements rather than just two.

Correlation Coefficient

The correlation between the copolarization elements (VV and HH) is defined as $\frac{1}{2}$

$$\rho_{\rm HHVV} = \left| \frac{\langle S_{\rm HH} S_{\rm VV}^* \rangle}{\langle S_{\rm HH} S_{\rm HH}^* \rangle \langle S_{\rm VV} S_{\rm VV}^* \rangle} \right|$$

Table D-1. Clutter Statistics for Polarimetric Image Set at HH and HV Polarizations

		and	HV Polarizations	ns				
8	LANDUSE	PTS.	INCIDENCE ANGLE	MIN(dB)	MAX(dB)	MEAN(dB)	VARIANCE	STANDARD DEVIATION
U5	URBAN	00006	73.44	-44.00	21.17	79.67	1.44676	1.20281
20	URBAN	00006		. 4	. יי	2 M	2.74041	1.6554
0.8	URBAN	00006		4.	7	4	3.07333	1.7530
65 :	URBAN	90006		44.	S.	w,	3.94631	1.9865
010	UKBAN	00006		44	4. A	⊣ (6.62017	2.5729
7 7 7	CREAN	00006		•	ט פ	A 10	0.88836	0.9425
5 5 5	GRASS	11250	•	. 4	∞	າ –	0.00130	0.0360
G14	GRASS	11250		44.	? -	11	0.0000	0.0218
RE6		00006		14.	ω,	4	7.51306	2.7410
RE7		00006	•	4.	ω,	N	4.03536	2,0088
RE23		120000	•	44.	7.	0	4.93246	2.2209
RE24		60000		4.	σ,	3	2.04869	1.4313
HZ	TERMINAL	4800		4.	۲.	4	296.02515	17.2053
H3	TERMINAL	4800		4.	ω,	Ч	206.36307	14.3653
H4	BUILDING	2500		-44.00	ĸ,	S	195.87170	13,9954
H2	BUILDING	4000		4.	~	$^{\circ}$	214.81818	14.6566
11	LANDUSE	PTS.	INCIDENCE ANGLE	MIN(dB)	MAX(dB)	MEAN(dB)	VARIANCE	STANDARD DEVIATION
<u> </u>	TA A COLL	0		•				
0 1	UKBAN	00006	٠		8.21	٠.	•	
9 5	UKBAN	00006		4·	17.71	4, 4	•	
21	TORBAN	00006	•	144.00	13.61	†. 0	•	
8 E	IRBAN	00006	•	. 4	17.57	<u>،</u> د	0.03073	
010 U10	URBAN	00006		0.4	17.41	. 0		
U11	URBAN	90000	•	4.0	14.96	\sim	0.05955	
G4	GRASS	20000	•	٥.	-11.70	ч.	•	
GS		11250		٥.	-16.96	σ.	•	0.00222
G14		11250		٥.	-16.76	4.		0.00130
RE6		00006	•	0	4.86	⊣.	•	0.03437
KE/	RESIDENTIAL	00000		-44.00	13.03	ກຸດ	•	
RE24		00009		. 4	8.41	jσ	•	0.2300
H2		4800	77.65	44.	17.49	-0.36	4734	3.23626
£ ;	TERMINAL	4800		44.0	17.33	ω,	•	
H :	BUILDING	2500	•	-44.00	17.49	w c	.9720	2.44379
5	BUTTOTING	4000		,	74.17	V	•	3.30900

Table D-2. Clutter Statistics for Polarimetric Image Set at VH and VV Polarizations

STANDARD DEVIATION	3 0.00587 0.00110 0.004662 0.004666 0.00795 0.003986 0.00122 0.00122 0.00122 0.00152 0.00152 0.00152 0.00152 0.001656 0.014477 0.01656 0.03671	STANDARD DEVIATION 3 0.00539 2 0.00485 3 0.00485 3 0.00868 2 0.00485 0 0.00134 0 0.0122 0 0.00122 0 0.00123 0 0.001422 3 0.014640 4 0.06511 5 0.01868
VARIANCE	0.00003 0.000045 0.00002 0.00002 0.00009 0.00009 0.00023 0.02096 0.00023 0.02096 0.00023	VARIANCE 0.00039 0.00039 0.000039 0.000120 0.001243
MEAN(dB)	-256.30 -27.90 -27.90 -28.32 -28.32 -28.68 -31.12 -31.12 -29.91 -25.05 -25.05 -25.07 -25.07 -25.07	MEAN(dB) -26.62 -25.98 -27.98 -27.98 -28.36 -28.25 -28.36 -21.81 -25.05 -14.23 -17.57 -24.42
MAX(dB)	-5.23 -5.08 -5.06 -5.06 -1.84 -1.84 -1.84 -1.84 -1.84 -1.86 -1.86 -1.56	MAX(dB) -5.60 -7.56 -4.67 -1.39 0.49 0.49 1.67 1.67 1.67 1.67 1.67 1.67 1.67 1.67 1.67 1.67 1.67 1.67
MIN(dB)	444-000 4444-000 4444-000 4444-000 4444-000 4444-000 4444-000 4444-000 4444-000 4444-000 4444-000	MIN(GB) -44.00 -44.00 -44.00 -44.00 -44.00 -44.00 -44.00 -44.00 -44.00 -44.00 -44.00 -44.00 -44.00 -44.00
INCIDENCE ANGLE	73.44 74.45 75.24 75.24 76.82 77.23 77.62 59.97 64.92 68.14 61.25 77.65 80.23	INCIDENCE ANGLE 73.44 74.45 75.24 75.24 75.24 77.23 77.23 77.23 77.23 77.62 59.97 64.92 68.14 51.25 62.64 77.65
PTS.	90000 90000 90000 90000 20000 11125 90000 120000 64800 4800 4800 4800	PTS. 90000 90000 90000 90000 11250 11250 11250 90000 4800 4800 4800 4800 4800 4800 48
LANDUSE	URBAN URBAN URBAN URBAN URBAN URBAN GRASS	URBAN URBAN URBAN URBAN URBAN URBAN URBAN URBAN GRASS GRASS GRASS GRASS GRASS GRASS GRASS TESIDENTIAL RESIDENTIAL RESIDENTIAL TERMINAL TERMINAL
OI I	U5 U6 U6 U1 U10 U11 G4 G5 G14 REC REC H2 H2 H3	UD U6 U7 U7 U8 U9 U10 U11 G4 G5 G5 G14 RE6 RE7 RE23 RE23 H3 H4

Clutter Statistics for Polarimetric Image Set at LL and RL Polarizations Table D-3.

MEAN(dB) VARIANCE STANDARD DEVIATION	-15.37 0.08862 0.29769 -13.88 0.125862 0.47815 -15.60 0.12586 0.37471 -16.72 0.14099 0.37549 -15.71 0.19960 0.44677 -18.04 0.00817 0.31332 -20.79 0.00012 0.01096 -22.62 0.00004 0.00621 -27.97 0.00001 0.00256 -12.01 0.58274 0.76338 -11.77 0.24975 0.49975 -12.47 0.13578 0.36439 0.59 19.51025 4.41704 -1.05 9.22339 3.03700 -3.36 7.76472 2.78653	MEAN(dB) VARIANCE STANDARD DEVIATION
MAX(dB)	14.95 15.96 15.96 17.95 17.29 17.29 17.29 18.33 17.95 17.95 18.91 18.91	MAX(dB)
MIN(dB)	444.00 444.00 444.00 444.00 444.00 444.00 444.00 444.00 444.00 444.00 444.00 444.00 444.00 444.00	MIN(dB)
INCIDENCE ANGLE	73.44 74.44 75.24 75.24 77.23 77.62 51.33 55.72 59.97 64.92 64.92 64.92 67.65 68.14 77.65 80.23	INCIDENCE ANGLE
PTS.	90000 90000 90000 90000 90000 20000 11250 11250 90000 120000 4800 4800 4800 4800 4800	PTS.
LANDUSE	URBAN URBAN URBAN URBAN URBAN URBAN GRASS GRASS GRASS GRASS GRASS TESIDENTIAL RESIDENTIAL RESIDENTIAL TERMINAL TERMINAL	LANDUSE
A	U5 U6 U7 U8 U9 U11 G4 G5 G14 REC REC REC H2 REC H3 H2 H3	OI

Clutter Statistics for Polarimetric Image Set at LR and RR Polarizations Table D-4.

STANDARD DEVIATION	0.32829 0.69835 0.52137 0.56444 0.831654 1.11084 0.00879 0.00879 0.00295 0.66573 0.69187 0.3372 5.93220 5.6289	STANDARD DEVIATION 0.31071 0.49093 0.35089 0.39038 0.29043 0.35062 0.1528 0.1528 0.0167 0.00643 0.00437 0.66535 0.42847 0.66986 0.43491 3.87723 2.68474 2.76163
VARIANCE	0.10777 0.48770 0.27183 0.32086 0.69165 1.23397 0.14874 0.00000 0.00001 0.44820 0.37472 0.37472 0.37472 0.37472 0.37472 0.37472	VARIANCE 0.09654 0.24102 0.12737 0.12293 0.08435 0.02319 0.00014 0.00004 0.00002 0.44871 0.18915 15.03290 7.20784 7.62657
MEAN(dB)	-14.74 -13.26 -13.78 -13.78 -13.78 -12.38 -12.33 -12.33 -11.70 -11.70 -11.56 -15.55 -11.56 -15.55 -10.48	MEAN(dB) -15.33 -13.81 -15.49 -17.08 -16.32 -18.41 -20.42 -22.48 -27.91 -12.40 -10.85 -15.36 -1.62 -1.62 -1.62
MAX(dB)	15.26 19.04 17.18 17.18 20.95 21.82 18.24 -10.47 -19.60 20.60 17.44 20.99 20.98	MAX(dB) 15.16 16.50 16.87 16.87 16.87 16.87 10.29 19.68 118.63 118.63 117.46
MIN(dB)		MIN(dB) -44.00 -44.00 -44.00 -44.00 -44.00 -44.00 -44.00 -44.00 -44.00 -44.00 -44.00
INCIDENCE ANGLE	73.44 74.45 75.24 75.24 76.82 77.62 77.62 77.62 55.72 59.97 68.14 77.65 68.14 80.23	TNCIDENCE ANGLE 73.44 74.45 75.24 75.24 77.23 77.23 77.23 77.23 77.62 55.72 59.97 64.92 68.14 77.65 77.65
PTS.	90000 90000 90000 90000 90000 111250 111250 90000 90000 120000 4800 4000	PTS. 90000 90000 90000 90000 90000 11250 90000 120000 4800 4800 4800 4800 4800
LANDUSE	URBAN URBAN URBAN URBAN URBAN URBAN GRASS GRASS GRASS GRASS TESIDENTIAL RESIDENTIAL RESIDENTIAL RESIDENTIAL RESIDENTIAL RESIDENTIAL RESIDENTIAL RESIDENTIAL RESIDENTIAL	
ΩI	US U6 U7 U8 U9 U10 U11 G4 G5 G14 REC REC REC REC REC REC REC REC REC REC	1D U5 U6 U7 U10 U10 U11 G4 G5 G14 RE24 RE27 RE27 H2 RE24

Table D-5. Clutter Statistics for Polarimetric Image Set at LLe and RLe for a Canted Oblate Spheroid Case

LION		FION
STANDARD DEVIATION	0.30251 0.48448 0.36950 0.41346 0.42431 0.42431 0.00214 0.00214 0.00219 0.71572 0.47803 0.4780	D DEV 3815 3815 3815 3823 5832 5832 5832 5036 00111 0081 0081 0036 11351 1253 1351 1351 1351
VARIANCE	0.09151 0.13472 0.13472 0.13653 0.17095 0.18004 0.04057 0.000003 0.000003 0.000003 0.22852 0.15049 19.30264 9.72018	14557 14557 14557 14557 16856 16856 16856 16856 16856 16632 16632 16632 16632 164712
MEAN(dB)	15.57 115.63 115.63 115.63 115.63 116.80 117.23 116.29 116.29 116.29 116.29 116.29 116.29 116.29 116.29 116.29	5 04HWWQHQUHBOUA4HQB
MAX(dB)	15.05 16.31 16.31 17.06 17.06 17.07 17.07 17.07 18.28 20.05 18.28 19.48 17.91	. XI N0707000000000000000000000000000000000
MIN(dB)	44444444444444444444444444444444444444	Z
INCIDENCE ANGLE	73.44.4 75.24.44.75.76.82.77.7.23.77.62.92.97.72.83.80.92.97.70.80.92.97.92.97.92.97.92.98.04.92.93.93.93.93.93.93.93.93.93.93.93.93.93.	
PTS.	90000 90000 90000 90000 90000 20000 111250 90000 120000 4800 4800 4800 4800	90000 90000 90000 90000 90000 90000 11250 11250 90000 90000 4800 4800 4800 4800 4800 4
LANDUSE	URBAN URBAN URBAN URBAN URBAN URBAN GRASS GRASS GRASS GRASS GRASS TESIDENTIAL RESIDENTIAL RESIDENTIAL RESIDENTIAL TERMINAL TERMINAL	LANDUSE URBAN URBA
8	U5 U6 U7 U8 U10 U11 G4 G5 G14 RE7 RE24 RE24 H2 H3	U5 U6 U6 U7 U1 U1 U1 U1 G5 G5 G14 REG RE7 RE23 RE23 H2 H2 H3

Clutter Statistics for Polarimetric Image Set at LRe and RRe for a Canted Oblate Spheroid Case Table D-6.

		2	, , , , , , , , , , , , , , , , , , ,					
11	LANDUSE	PTS.	INCIDENCE ANGLE	MIN(dB)	MAX(dB)	MEAN(dB)	VARIANCE	STANDARD DEVIATION
71	IBBAN	00006	4	C	5.0	5	0	Ö
71	MAGGI	00000		-44 00	3	σ	0.23606	c
27	TERAN	00006	75.24	. 4	16.03	-15.67		0.36740
ò E	TRBAN	00006		-44.00	5.7	2		.0
S E	TIRBAN	00006	- ∞	4	7.5	80		Ö
1110	IRBAN	00006	~	4	7.0	9		o
111	URBAN	00006	. 6	4	4.7	3		Ó
4 45	GRASS	20000	٣,	4	7.0	0		0
E	GRASS	11250		4	1.1	5	•	0
714	GRASS	11250		4	Η.	7	0.00001	Ó
REG	RESTDENTIAL	00006	σ,		9.6	4.		Ö
RE7	RESIDENTIAL	00006	٦.	-44.00	6.3	ĸ.	•	0
RE23		120000	Ω,	4.	7.2	7		Ö
RE24		00009	9	4.	8.3	Ч	•	0
H2		4800	٠.	•	0.1	4	•	4
ï	TERMINAL	4800	٥.	4.0	4.6	0		m
H4	BUILDING	2500	2	0	7.8	6.	•	Ŕ
£	BUILDING	4000	ď.	-44.00	7.0	5	•	-
A	LANDUSE	PTS.	INCIDENCE ANGLE	MIN(dB)	MAX(dB)	MEAN(dB)	VARIANCE	STANDARD DEVIATION
0.5	URBAN	00006		•	14.62	ε,	.0723	
90	URBAN	00006		•	17.52	ς.	.2460	0.4960
70	URBAN	00006		-44.00	16.50	٦.	•	0.4306
n8	URBAN	00006		-44.00	17.37	9.	.2197	0.4687
6n	URBAN	00006		•	20.03	ω,	•	0.6753
010	URBAN	00006		-44.00	20.85	٦.	•	0.8939
011	URBAN	00006		-44.00	18.98	ω,		0.4050
G4	GRASS	20000	•	•	-8.63	७.	•	0.0088
G5	GRASS	11250		-44.00	-9.15	4.		0.0079
G14	GRASS	11250		4.	66.9-	œ.	•	0.0039
RE6	RESIDENTIAL	00006			19.26	'n.	0.39158	0.6257
RE7	_	00006		•	19.27	ᅼ	•	0.5365
RE23		120000		-44.00	22.46	٥.	•	0.9954
RE24		00009		-44.00	16.41	۲.		0.2760
H2	TERMINAL	4800	77.65	•	20.27	1.64	29.82462	5.46
Ŧ	TERMINAL	4800	•	4.0	20.41	ι.		5.1199
H4	BUILDING	2500		-44.00	19.65	۲.		5.0678
HS	BUILDING	4000		•	23.17	S		7.4886

Table D-7. Clutter Statistics for Polarimetric Image Set at LLe and

		RLe for	a Case of	Propag	Propagating Thru	ಹ	Rain Filled Medium	dium
a	LANDUSE	PTS.	INCIDENCE ANGLE	MIN(dB)	MAX(dB)	MEAN(dB)	VARIANCE	STANDARD DEVIATION
US	URBAN	00006		-44.00	16.42	-13.50	0.19121	
ne O	URBAN	00006	74.45		20.39	-11.00	0.95878	
70	URBAN	00006		-44.00	18.16	-12.70	0.44119	
U8	URBAN	00006			18.93	-12.90	0.50817	
60	URBAN	00006			21.98	-13.03	1.05882	П
010	URBAN	90000			22.71	-11.59	1.90456	
U11	URBAN	00006			18.98	-14.83	0.20561	0
G4	GRASS	20000			-6.62	-20.19	0.00016	U
G 5	GRASS	11250	55.72	-44.00	-10.01	-20.89	0.00008	
6.1.4 1.4	GKASS	11250	•		-7.13	-25.73	0.00002	<u>.</u> .
XE O	RESIDENTIAL	90006	•	44.	20.69	-11.26	0.70298	
조 된 된 년		90000	٠	•	20.10	-10.47	0.58271	0
KE23		120000	•	٠	20.79	-11.64	0.56883	<u> </u>
KE24		00009	•	-44.00	18.94	-14.18	ं	
7H S	TERMINAL	4800	•	٠.	21.15	2.89	ώ,	Ψ,
£	TERMINAL	4800	٦,	4.	21.33	1.62	;,	
# H	BITTIDING	4000	80.23 80.23	-44.00	20.30	-0.15	33.08904	5.75231
]	DO THE THE	•	6:00	÷	20.02	64.7	÷	.400
日	LANDUSE	PTS.	INCIDENCE ANGLE	MIN(dB)	MAX(dB)	MEAN(dB)	VARIANCE	STANDARD DEVIATION
,			;				1 1	•
02 1	URBAN	00006	73.44	-44.00	14.96	-15.75	0.08583	0.29296
5 5	UKBAN	00006	75.24	44.00	10.01	14.20	0.2033	5 ¢
) K	URBAN	00006	75.76	-44.00	15.53	-15.75	0 15403	, ,
66	URBAN	00006	76.82	-44.00	17.34	-17.12	0.11062	. 0
010	URBAN	00006	77.23	-44.00	16.68	-16.16	0.15425	0
011	URBAN	00006	77.62	-44.00	15.27	-18.57	0.03776	
G4	GRASS	20000	51.33	-44.00	-7.01	-21.04	0.00010	0
GS	GRASS	11250	55.72	-44.00	-11.00	-23.47	0.00003	0
G14	_	11250	59.97	-44.00	-9.93	-28.95	0.0000	0
RE6		00006	64.92	-44.00	19.96	-12.44	0.49892	0,
RE7		90000	68.14	-44.00	15.91	-12.39	0.2045/	,
KE23	A RESIDENTIAL	00007	51.25	144.00	10.40	-11.98 -16.33	0.22834	
REZ.		4800	77.65	-44 00 -46 00	19.17	0.08	17 02716	7 4
H	TERMINAL	4800	78.04	-44.00	19.00	-1.34	8.25210	. ()
H4	BUILDING	2500	80.23	-44.00	17.60	-3.31	7.98735	2.8261
HS	BUILDING	4000	80.37	4.	17.10	-8.78	2.76478	1.6627

Table D-8. Clutter Statistics for Polarimetric Image Set at LRe and RRe for a Case of Propagating Thru a Rain Filled Medium

		L L	The lot a case of r	Tiopag	מוווע וו	Topagainig iina a nan i med medidin) 	
£	LANDUSE	PTS.	INCIDENCE ANGLE	MIN(dB)	MAX(dB)	MEAN(dB)	VARIANCE	STANDARD DEVIATION
711	IRRAN	00006	73.44	-44.00	14.97	50	0.08708	
31.	TEBAN	00006	74.45	-44.00	16.11	-14.19	0.20830	
2 0	N COUNTY		75 24	. 4	15.83	-15.92	0.12120	
/ n	UKBAN	0000	75.76	. T T	15.47	-15 77	0.15071	
200	UKBAN	0000	76.00		17.21	-17.18	0.10342	
60:	UKBAN	00000	20.07	r =	16.50	-16.25	0.14369	
oTo	UKBAN	00006	57.11	00.44	14.50	18.60	0.03355	
011	UKBAN	90000	70.77	•	£0.£T	100	0.0000	
G4	GRASS	20000	51.33 EE 33	, , ,	10.90	-23.47	0.00003	0.00524
GS	GRASS	11.250	55.72	4.4	00.01	74.67	00000	
G14	GRASS	11250	59.97	母 ⋅	-10.27	66.87-	0.0000	
RE6	RESIDENTIAL	00006	64.92	4.	19.89	-12.50	0.48430	
RE7	RESIDENTIAL	00006	68.14	•	15.94	-12.46	0.19943	
RE23		120000	51.25	-44.00	16.95	-11.79	0.28262	
PED4		60000	62.64	-44.00	18.29	o	0.15099	
1307		4800	77 65	•	19.86	\sim	16.56062	
20		0001	78 04	. 4	18.97	-1.37	8.12680	
2 ;	LEKMINAL PIITI PINO	000	50:04	77.00	17.57	-3.31	8.05174	
H. :	BUILDING	7000	90.43	. 4	16.01	ηŒ	288	1.62137
H.	BUTTTO	4000	6.00	·	200			
U	LANDUSE	PTS.	INCIDENCE ANGLE	MIN(dB)	MAX(dB)	MEAN(dB)	VARIANCE	STANDARD DEVIATION
-		 						
1	MAGGII	00006		-44.00	~	-15.71	0.05444	
71	NEGNO	00006	74		ζ.	-13.57		0
2 5	MAGGI	00006	75		٠.	-14.82		_
\ 0 1	UKDAN	0000	75.	-44.00	· ·	-14.89	0.18129	_
0 6	UNDAN		76		-	-14.46		_
25	UKBAN	0000		-44 00	ے :	-13 23		
OTO	UKBAN	00006		00.11	· ~	-15 93		
TTO	UKBAN	9000	. [00.44		-22.73		
G4	GRASS	20000	. IC		, 0	11.77	•	
G2	GRASS	11250	, çç		ים ספ	76.12	00000	
614	GRASS	11250	. 65	-44.00		-21.01		
PER		90000	64	-44.00	8.4	-13.20		_
PF7	. –	00006	.89	-44.00	8.9	-12.68		•
DE22	-	12000	512		2.2	-10.46		•
ACT O		00009	629		5.5	-16.16	0.05357	_
200		4800	77		0.0	1.39	ø	-,
211	TENTING	4800	78	•	0.2	0.34	\sim	•
2 5	DITTING	2500	0.00	-44.00	19.62	-0.86	23.39676	•
* L	DOLLG THE	000	200	. 4	,	-2.68	-	
£	BUTTTO	7		:	} }	; ; ;		

Table of Polarimetric Discriminants for the Polarimetric Image Set at Linear Polarization Table D-9.

THETA HHVV (deg)	-52.942 -33.876 -25.597 -26.569 -37.958 -37.958 -44.429 -52.899 -54.423 -51.656 -53.656 -53.656
RHO HHVV (dB)	
DEPOL (dB)	13.101 115.094 115.801 117.918 16.352 17.918 12.855 12.855 14.029 14.638 14.638 16.839 18.545 20.066 23.371
SPAN (dB)	10.983 1.358
(vv vv*)/ (HH HH*) (dB)	-8.498 -8.540 -7.972 -7.972 -4.526 -4.887 -12.675 -12.675 -15.703 -14.006 -11.667 -13.084 -6.840 -7.020 -6.811
σ°W w w* (dB)	-19.682 -18.285 -17.546 -17.546 -13.085 -13.169 -26.929 -26.929 -21.265 -21.265 -187 -21.265 -187 -21.265 -21.265 -21.265 -21.265 -1.358 -1.358 -1.358 -1.358
o ^o HV HV HV* (dB)	26.551 -27.357 -27.819 -27.819 -27.990 -29.016 -26.063 -31.123 -31.123 -34.910 -25.911 -24.054 -25.213 -17.286 -17.796 -27.023
о ^о vн vн vн* (db)	26.900 -27.206 -27.235 -27.235 -27.235 -27.574 -28.337 -29.674 -29.674 -29.674 -29.674 -21.86 -21.86 -21.186 -21.186 -21.186 -21.186 -21.207 -25.068
о ^о НН нн нн ∗ (дв)	-11.184 -9.745 -9.502 -7.113 -9.066 -11.108 -12.517 -7.259 -7.259 -1.833 -1.833 -6.705 -6.705 -6.705 -7.259
LABEL	URBAN URBAN URBAN URBAN URBAN URBAN GRASS GRASS GRASS GRASS GRASS GRASS GRASS GRASS TESIDENTIA RESIDENTIA RESIDENTIA TERMINAL TERMINAL TERMINAL

IMAGE: P3T626 TARGET: DENVER

Table of Polarimetric Discriminants for the Polarimetric Image Set at Circular Polarization Table D-10.

4.929 5.276 4.929 3.821 1.655 1.184 -3.406 -3.406 4.042 -10.378 -4.042 -10.378 -3.899 -3.806 -3.806 -3.806 -3.806 -1.0.378 -3.806 -THETA RRLL (deg) -0.670 -0.670 -0.670 -0.813 -0.8133 -0.752 -0.7545 -0. RHO RRLL (dB) 0.760 1.773 1.773 1.773 1.773 1.773 1.773 1.773 1.773 1.042 DEPOL (dB) -10.402 -9.044 -9.044 -6.401 -8.315 -7.775 -7.775 -7.775 -16.271 -5.293 -6.272 -6.272 -10.983 7.359 6.016 4.348 4.348 (LL LL*)/ (RR RR*) (dB) -0.070 -0.464 -0.352 -0.252 -0.252 -0.370 -0.143 -0.1480 -0.1480 -0.7180 -0.465 -0.565 -0.565 -0.7180 -0.7180 -0.7465 -16.855 -16.279 -13.288 -17.112 -15.691 -20.789 -20.789 -22.624 -22.624 -11.096 -12.789 -12.789 -12.789 -13.355 -3.355 LL LL* -16.032 -14.238 -13.667 -11.761 -12.604 -12.3629 -14.000 -21.629 -22.056 -22.056 -22.056 -12.886 -12.8 RL RL* (dB) 16.088 -14.298 -13.723 -11.818 -12.401 -13.972 -21.655 -22.037 -22.037 -12.228 -12.228 -12.228 -12.3976 -12.228 -12.3976 -12.3976 -12.3976 -12.3976 -12.3976 -12.3976 -12.398 -0.398 LR LR* (dB) 16.784 -15.815 -13.037 -13.318 -16.071 -17.318 -16.18.817 -22.481 -22.481 -22.481 -22.481 -22.481 -27.388 -11.389 -11.602 -13.199 -13. RR RR* (dB) URBAN URBAN URBAN URBAN URBAN URBAN URBAN GRASS LABEL

IMAGE: p3t626 TARGET: DENVER

Image Set at Elliptical Polarization for the Canted Oblate Spheroid Case Table D-11. Table of Polarimetric Discriminants for the Polarimetric

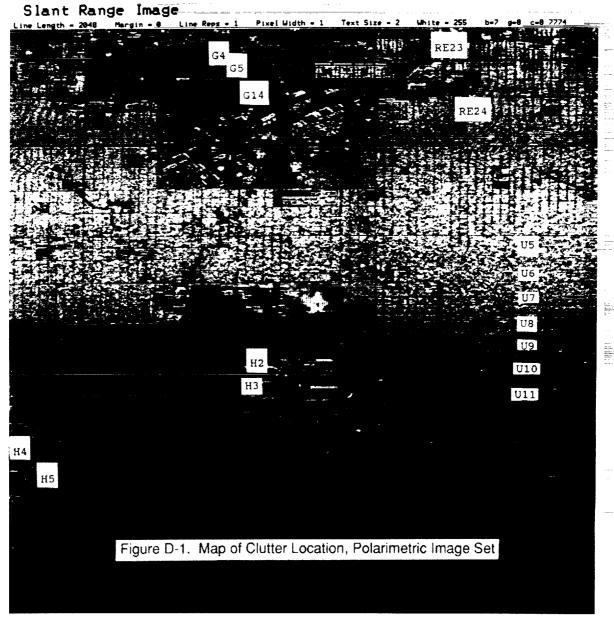
P3T626	DENVER
IMAGE:	TARGET:

	RLe* LLe B) (d	* RLe RLe* I (dB)
1.257	.223 -13.562 .374 -13.057	-13.
	228 -11.	-13.228 -11.
	283 -12. 767 -12.	-15.767 -12.
	112 -13.	-18.112 -13.
	019 -20.	-21.019 $-20.$
	$\frac{537}{262}$ -21.	-23.537 -21.
	757 -26. 373 -10	-28.757 -26.
	273 -12.	-13.273 -12.
1	237 -12.	-12.237 $-12.$
	732 -15.	-17.732 $-15.$
	486 2.	0.486 2.
	082 1.	-1.082 1.
	9320.	-2.932 -0.
	549 -2.	-8.549 -2.

Table of Polarimetric Discriminants for the Polarimetric Image Set at Elliptical Polarization for the Case of Propagating Thru a Rain Filled Medium Table D-12.

IMAGE: P3T626 TARGET: DENVER

LABEL	RRe RRe* (dB)	LRe LRe* (dB)	RLe RLe* (dB)	LLe LLe* (dB)	(LLe LLe*)/ (RRe RRe*) (dB)	SPAN (dB)	DEPOL (dB)	RHO RRELLE (dB)	THETA RReLLe (deg)
					1	1			
-		-17.333	-17.323	-14.821		-10.402	1.654	-0.796	0.979
7		-16.453	-16.427	-13.125		-9.044	2.418	-0.448	3.474
z		-16.595	-16.589	-12.651		-8.755	3.093	-0.353	1.561
z		-13.401	-13.392	-10.694		-6.401	1.771	-0.256	-0.111
z		-17.567	-17.596	-11.929		-8.315	5.083	-0.264	-2.293
z		-16.059	-16.111	-11.673		-7.775	3.780	-0.200	-1.590
z		-18.270	-18.421	-13.410		-9.466	4.568	-0.432	-11.132
S	-22.414	-21.041	-21.003	-20.186	2.228	-15.069	-0.137	-0.911	0.807
S		-23.473	-23.466	-20.886		-16.271	2.103	-1.439	0.186
S		-28.946	-28.955	-25.733		-21.438	2.600	-1.647	4.251
DENTIA		-11.410	-11.459	-10.256		-5.293	0.239	-0.309	-1.050
DENTIA		-13.302	-13.394	-11.569		-6.921	0.777	-0.669	-2.059
DENTIA		-12.457	-12.271	-12.167		-6.272	0.139	-0.448	9.259
DENTIA		-17.881	-17.837	-15.499		-10.983	1.569	-1.314	6.664
INAL		0.278	0.243	2.885		7.359	1.941	-0.161	-4.565
INAL		-1.344	-1.371	1.621		6.016	2.383	-0.100	-3.717
DING		-3.310	-3.306	-0.147		4.348	2.820	-0.029	1.753
BUILDING		-8.784	-8.861	-2.489		1.355	6.242	-0.031	-3.777



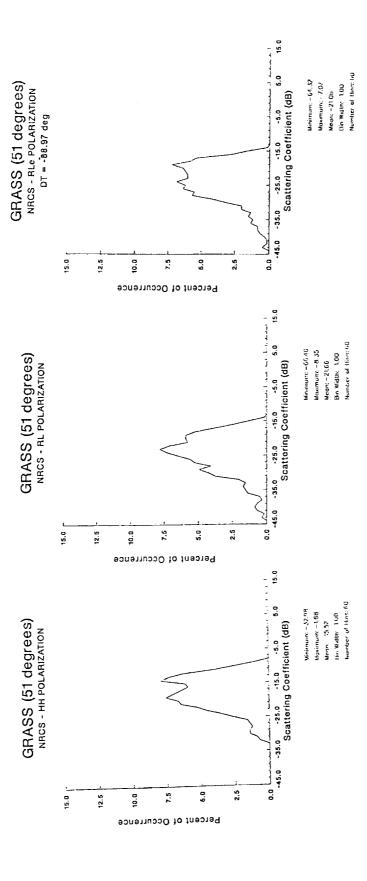


Figure D-2. Histogram at Linear-HH, Circular-RL, and Elliptical-RL for a Grass Area at an Incidence Angle of 51 Degrees.

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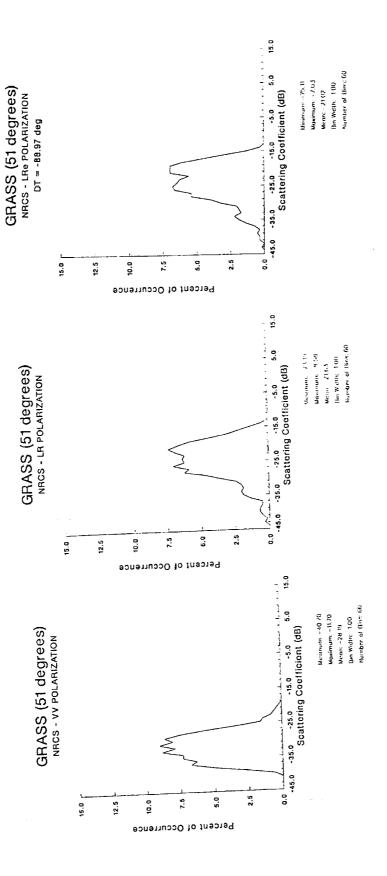


Figure D-3. Histogram at Linear-VV, Circular-LR, and Elliptical-LRe for Grass Area at an Incidence Angle of 51 Degrees.

THE THE STATE OF STAT

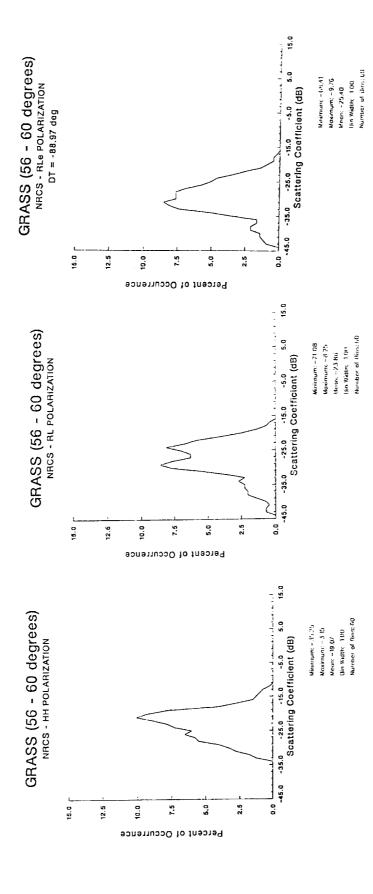


Figure D-4. Histogram at Linear-HH, Circular-RL, and Elliptical-RL for a Grass Area at an Incidence Angle of 56-60 Degrees.

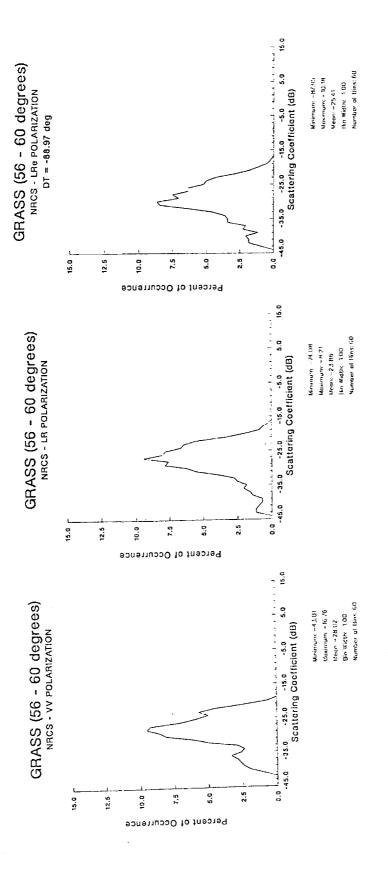


Figure D-5. Histogram at Linear-VV, Circular-LR, and Elliptical-LR for Grass Area at an Incidence Angle of 56-60 Degrees.

THE PERSON OF TH

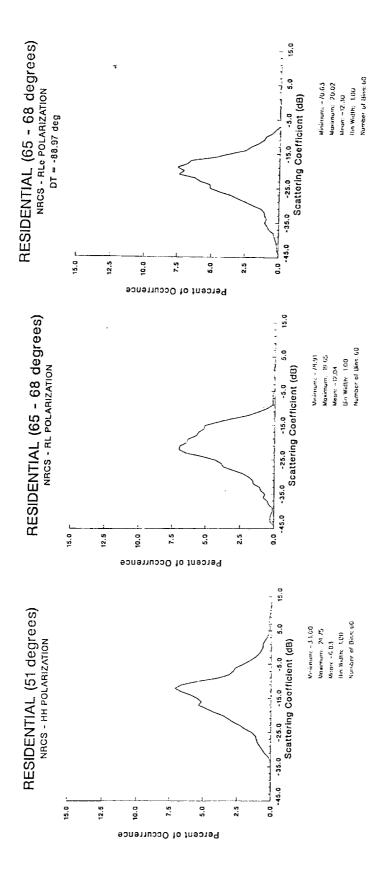


Figure D-6. Histogram at Linear-HH, Circular-RL, and Elliptical-RL for a Residential Area at an Incidence Angle of 51 Degrees.

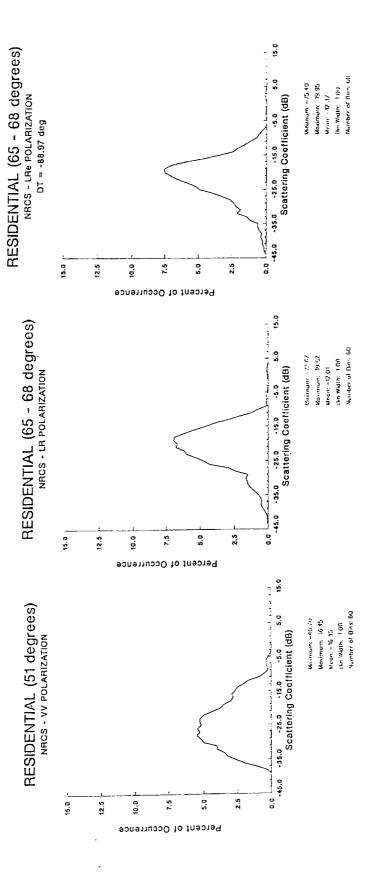


Figure D-7. Histogram at Linear-VV, Circular-LR, and Elliptical-LR for a Residential Area at an Incidence Angle of 51 Degrees.

₹.

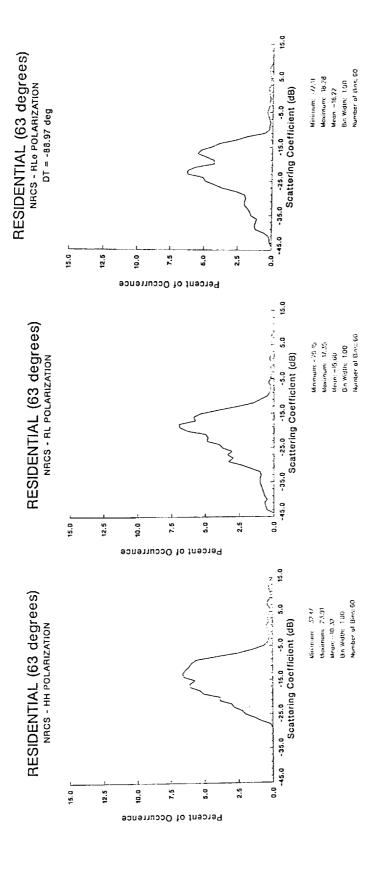


Figure D-8. Histogram at Linear-HH, Circular-RL, and Elliptical-RL for a Residential Area at an Incidence Angle of 63 Degrees.

<u>=</u>-

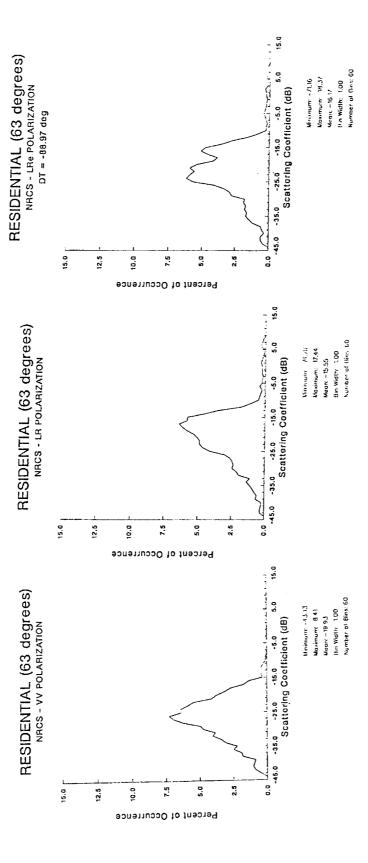
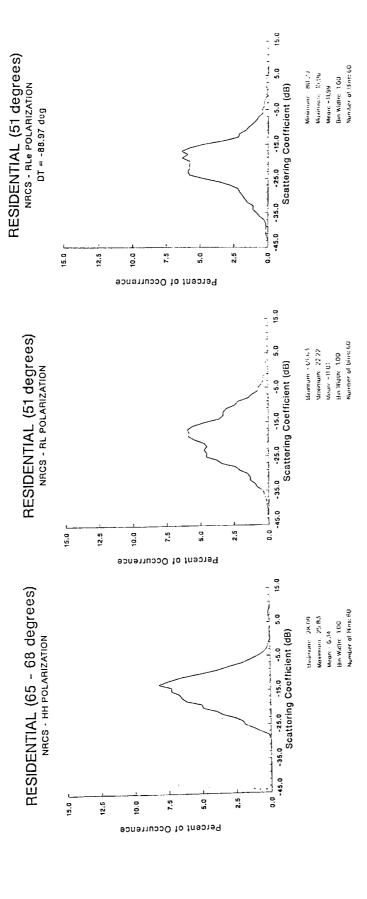


Figure D-9. Histogram at Linear-VV, Circular-LR, and Elliptical-LR for a Residential Area at an Incidence Angle of 63 Degrees.



a Residential Area at an Incidence Angle of 65-68 Degrees. Figure D-10. Histogram at Linear-HH, Circular-RL, and Elliptical-RL for

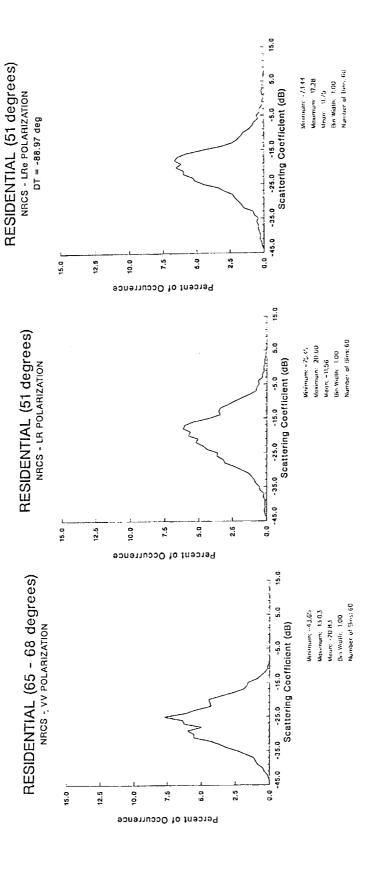


Figure D-11. Histogram at Linear-VV, Circular-LR, and Elliptical-LR for a Residential Area at an Incidence Angle of 65-68 Degrees.

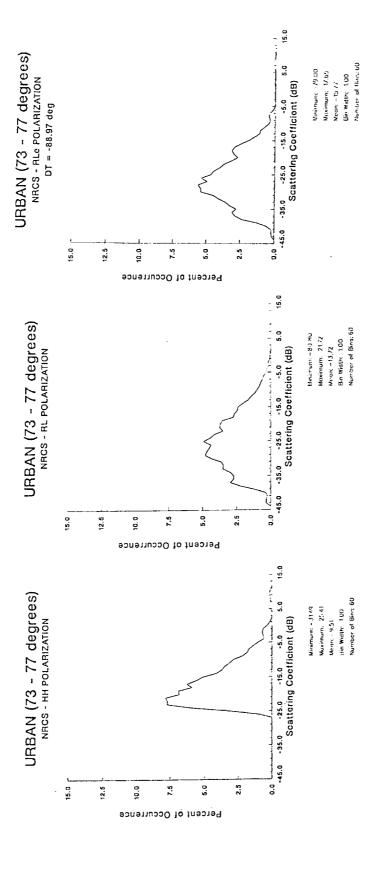


Figure D-12. Histogram at Linear-HH, Circular-RL, and Elliptical-RL for an Urban Area at an Incidence Angle of 73-77 Degrees.

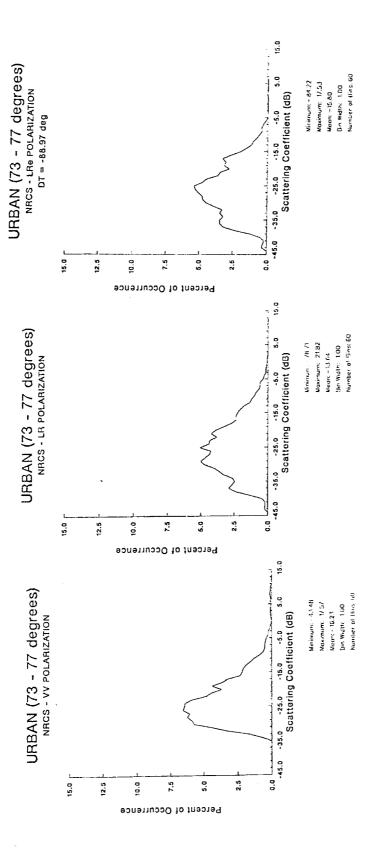


Figure D-13. Histogram at Linear-VV, Circular-LR, and Elliptical-LR for an Urban Area at an Incidence Angle of 73-77 Degrees.

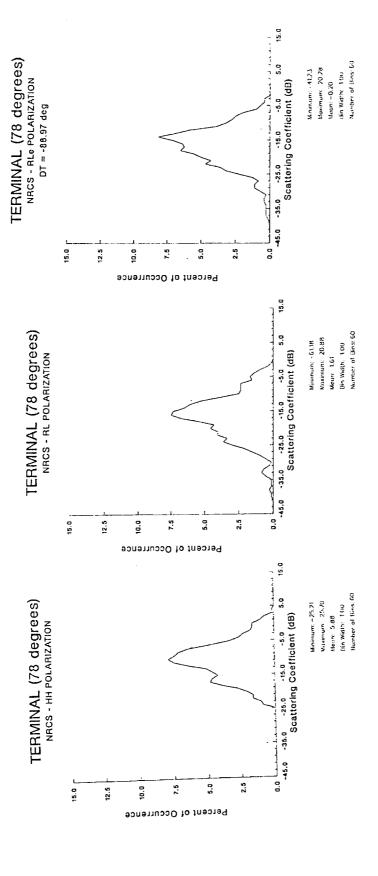


Figure D-14. Histogram at Linear-HH, Circular-RL, and Elliptical-RL for a Terminal Area at an Incidence Angle of 78 Degrees.



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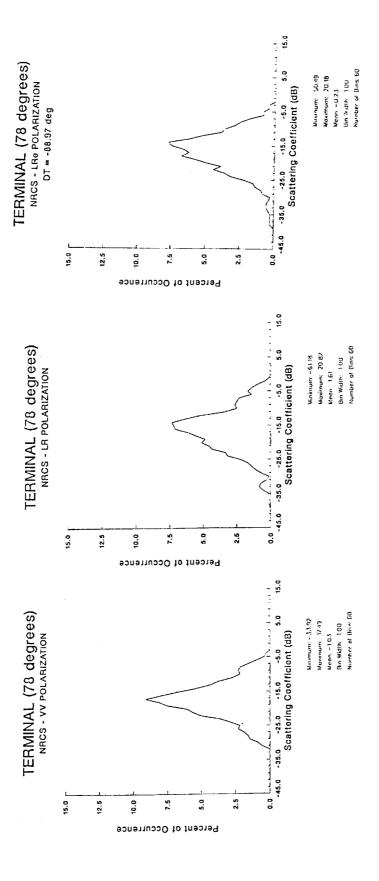


Figure D-15. Histogram at Linear-VV, Circular-LR, and Elliptical-LR for a Terminal Area at an Incidence Angle of 78 Degrees.

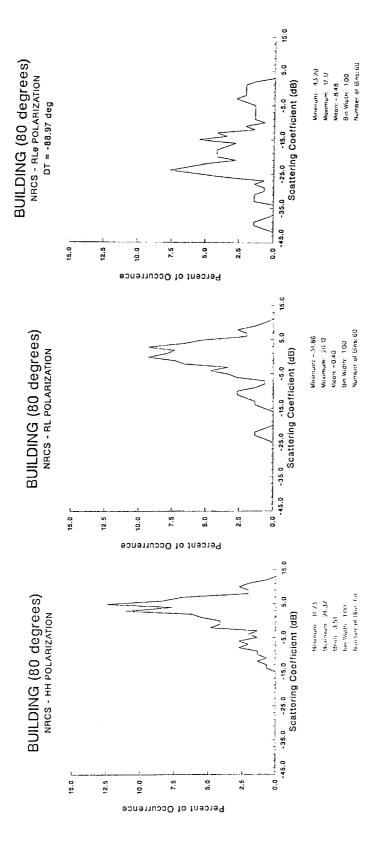


Figure D-16. Histogram at Linear-HH, Circular-RL, and Elliptical-RL for a Building Area at an Incidence Angle of 80 Degrees.

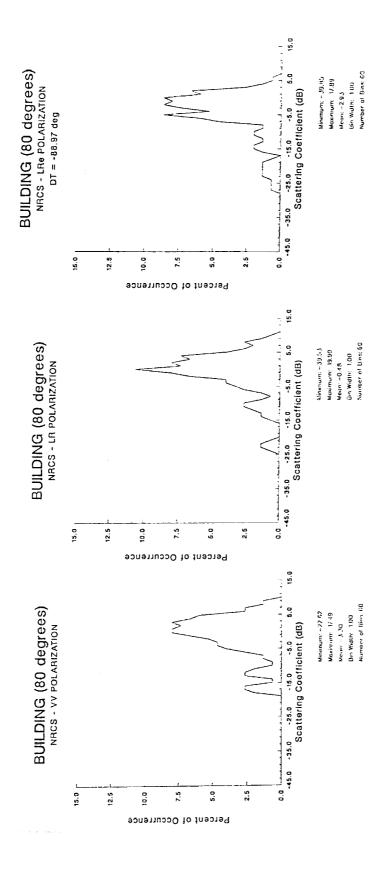


Figure D-17. Histogram at Linear-VV, Circular-LR, and Elliptical-LR for a Building Area at an Incidence Angle of 80 Degrees.

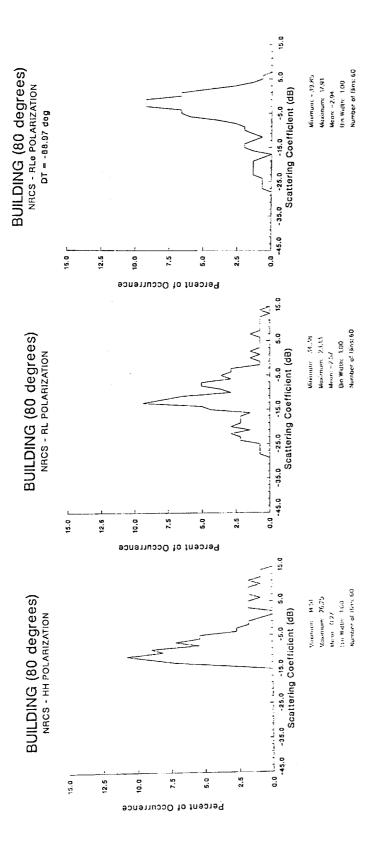


Figure D-18. Histogram at Linear-HH, Circular-RL, and Elliptical-RL for a Building Area at an Incidence Angle of 80 Degrees.

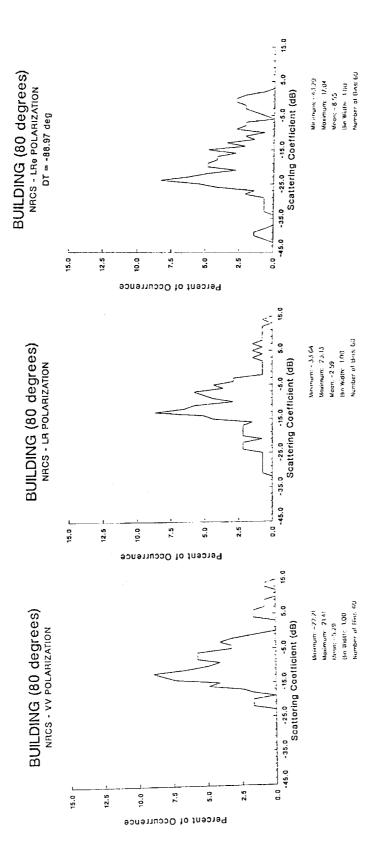


Figure D-19. Histogram at Linear-VV, Circular-LR, and Elliptical-LR for a Building Area at an Incidence Angle of 80 Degrees.

APPENDIX E

Examination of the Calibration of the Polarimetric Image Set

APPENDIX E

Calibration Targets

Trihedral calibration targets were utilized in the calibration of the VV and HH channels. These targets will be used to demonstrate balance between the VV and HH channels. The scattering matrices for these targets after calibration are provided here.

$$[S]_{TRI1} = \begin{bmatrix} 1.000/+12.2^{\circ} \\ 0.054/-89.1^{\circ} \end{bmatrix} \begin{bmatrix} 0.055/-89.1^{\circ} \\ 0.956/+14.7^{\circ} \end{bmatrix}$$

$$[S]_{TRI2} = \begin{bmatrix} 1.000/-157.3^{\circ} \\ 0.057/+95.7^{\circ} \end{bmatrix} \begin{bmatrix} 0.053/+95.7 \\ 1.010/-158.4^{\circ} \end{bmatrix}$$

$$[S]_{TRI3} = \begin{bmatrix} 1.000/-32.4^{\circ} \\ 0.020/-117.5^{\circ} \end{bmatrix} \begin{bmatrix} 0.045/-120.4^{\circ} \\ 1.010/-7.60^{\circ} \end{bmatrix}$$

$$[S]_{TRIavg} = \begin{bmatrix} 1.000/0.000^{\circ} \\ 0.044/-85.8^{\circ} \end{bmatrix} \begin{bmatrix} 0.051/-85.7^{\circ} \\ 0.994/+24.3^{\circ} \end{bmatrix}$$

$$[P]_{TRIavg} = \begin{bmatrix} 0.0 & dB \\ -27.13 & dB \end{bmatrix} \begin{bmatrix} -25.85 & dB \\ -0.05 & dB \end{bmatrix}$$

These results show that the VV and HH channels were well balanced, the standard deviation is 0.003 dB. The dihedral data also showed similar results.

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16. Abstract This report is the fourth in a series of four which address the statistical description of ground clutter at an airport and in the surrounding area. These data are being utilized in a program to detect microbursts. Synthetic aperture radar (SAR) data were collected at the Denver Stapleton Airport. Mountain terrain data were examined to determine if they may potentially contribute to range ambiguity problems and degrade microburst detection. Results suggest that mountain clutter may not present a special problem source. The examination of clutter at small grazing angles was continued by examining data collected at especially low altitudes. Cultural objects such as buildings produce strong sources of backscatter at angles of about 85°, with responses of 30 dB to 60 dB above the background. Otherwise there are a few sources which produce significant scatter. The polarization properties of hydrospheres and clutter were examined with the intent of determining the optimum polarization. This polarization was determined to be dependent upon the ratio of VV and HH polarizations of both rain and ground clutter. 17. Key Words (Suggested by Author(s)) Clutter, Backscatter, SAR, Microbursts, Grazing, Polarimetrics. Unclassified - Unlimited Subject Category 03				
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